

Global and Chinese SLAM in mobile robots and smart AR Industry, 2018 Market Research Report

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Abstracts

The 'Global and Chinese SLAM in mobile robots and smart AR Industry, 2013-2023 Market Research Report' is a professional and in-depth study on the current state of the global SLAM in mobile robots and smart AR industry with a focus on the Chinese market. The report provides key statistics on the market status of the SLAM in mobile robots and smart AR manufacturers and is a valuable source of guidance and direction for companies and individuals interested in the industry. Firstly, the report provides a basic overview of the industry including its definition, applications and manufacturing technology. Then, the report explores the international and Chinese major industry players in detail. The compnaies include: MAXST, LG Electronics, Lenovo, Sony, IBM, Exosite, Swisslog (KUKA), Omron Adept, Clearpath Robotics, Vecna, Mobile Industrial Robots, SMP Robotics, Cimcorp Automation, Aethon, Locus Robotics, Fetch Ro et al. In this part, the report presents the company profile, product specifications, capacity, production value, and 2013-2018 market shares for each company. Through the statistical analysis, the report depicts the global and Chinese total market of SLAM in mobile robots and smart AR industry including capacity, production, production value, cost/profit, supply/demand and Chinese import/export. The total market is further divided by company, by country, and by application/type for the competitive landscape analysis. The report then estimates 2018-2023 market development trends of SLAM in mobile robots and smart AR industry. Analysis of upstream raw materials, downstream demand, and current market dynamics is also carried out. In the end, the report makes some important proposals for a new project of SLAM in mobile robots and smart AR Industry before evaluating its feasibility. Overall, the report provides an in-depth insight of 2013-2023 global and Chinese SLAM in mobile robots and smart AR industry covering all important parameters.

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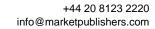
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