

Global Two-finger Parallel Pneumatic Gripper Market Growth 2026-2032

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Abstracts

The global Two-finger Parallel Pneumatic Gripper market size is predicted to grow from US\$ 361 million in 2025 to US\$ 557 million in 2032; it is expected to grow at a CAGR of 6.4% from 2026 to 2032.

In 2025, global Two-finger Parallel Pneumatic Gripper production reached approximately 615k units , with an average global market price of around US\$600 per unit.

A Two-finger Parallel Pneumatic Gripper is an industrial automation end-effector driven by compressed air, using two parallel-moving fingers to grip and handle workpieces. It is widely used in industrial robots, automated assembly lines, CNC machine loading and unloading, semiconductor manufacturing, electronics assembly, medical equipment, food packaging, and precision inspection systems. The gripper typically consists of a pneumatic cylinder drive mechanism, guide rails, gripper fingers, synchronization structures, and cushioning control systems, enabling high repeatability, stable clamping force, and fast response speed. Compared with angular grippers, two-finger parallel pneumatic grippers maintain parallel gripping surfaces during operation, making them especially suitable for precision parts, regular-shaped components, and high-consistency automated handling applications. Depending on structural design, they can be classified into slide-guide types, wedge-cam types, rack-and-pinion types, ball-guide types, and ultra-thin compact types. They can also integrate with force sensors, vision systems, and collaborative robots for intelligent flexible gripping applications. With the rapid development of Industry 4.0, intelligent manufacturing, and humanoid robotics, two-finger parallel pneumatic grippers are continuously evolving toward higher precision, higher speed, lightweight structures, miniaturization, and intelligent flexible handling capabilities.

The upstream industry chain of Two-finger Parallel Pneumatic Grippers mainly includes suppliers of aluminum alloys, stainless steel, high-strength engineering plastics, pneumatic components, guide rails, bearings, sealing components, magnetic sensors, and precision machining equipment. Representative companies include SMC, Festo, THK, NSK, HIWIN, Bosch Rexroth, Parker Hannifin, MISUMI, SKF, and Airtac. The midstream segment mainly consists of pneumatic gripper manufacturers, industrial automation actuator companies, and robotic end-effector suppliers, with representative companies including SMC, Airtac, SCHUNK, and Festo. These companies are mainly responsible for two-finger parallel pneumatic gripper R&D, gripping mechanism design, pneumatic control system development, and automated end-effector integration. Downstream applications are widely distributed across industrial robotics, automotive manufacturing, consumer electronics, semiconductors, food packaging, medical devices, logistics warehousing, and new energy equipment industries. Representative end users include ABB, KUKA, FANUC, Tesla, Foxconn, BYD, CATL, and TSMC. Overall, the industry is continuously evolving toward higher precision, lightweight structures, intelligent sensing, collaborative robot compatibility, and flexible automation systems.

As industries such as new energy vehicles, semiconductors, consumer electronics, logistics automation, and collaborative robotics continue to demand high-efficiency and high-precision automated handling solutions, two-finger parallel pneumatic grippers, as one of the most mainstream robotic end-effectors, are seeing continuously expanding market demand. Industry products are evolving toward lightweight structures, miniaturization, higher gripping precision, faster response speed, and intelligent sensing capabilities. At the same time, flexible gripping systems, force feedback control, machine vision integration, and AI-based intelligent handling technologies are being increasingly integrated into advanced gripper systems. The rapid development of collaborative robots, humanoid robots, and flexible automated production lines is further driving demand for high-end pneumatic grippers. However, the industry still faces challenges including high costs of precision guide rails, miniature pneumatic components, and high-performance sealing elements, as well as strong technological barriers from international premium brands and cyclical fluctuations in downstream manufacturing investments. In addition, increasingly demanding requirements for stability, durability, and high-frequency operational lifespan under complex industrial conditions continue to raise the industry's technical barriers. Overall, driven by the continued expansion of global intelligent manufacturing and robotics industries, the market maintains strong long-term growth potential.

LP Information, Inc. (LPI) ' newest research report, the "Two-finger Parallel Pneumatic Gripper Industry Forecast" looks at past sales and reviews total world Two-finger Parallel Pneumatic Gripper sales in 2025, providing a comprehensive analysis by region and market sector of projected Two-finger Parallel Pneumatic Gripper sales for 2026 through 2032. With Two-finger Parallel Pneumatic Gripper sales broken down by region, market sector and sub-sector, this report provides a detailed analysis in US\$ millions of the world Two-finger Parallel Pneumatic Gripper industry.

This Insight Report provides a comprehensive analysis of the global Two-finger Parallel Pneumatic Gripper landscape and highlights key trends related to product segmentation, company formation, revenue, and market share, latest development, and M&A activity. This report also analyzes the strategies of leading global companies with a focus on Two-finger Parallel Pneumatic Gripper portfolios and capabilities, market entry strategies, market positions, and geographic footprints, to better understand these firms' unique position in an accelerating global Two-finger Parallel Pneumatic Gripper market.

This Insight Report evaluates the key market trends, drivers, and affecting factors shaping the global outlook for Two-finger Parallel Pneumatic Gripper and breaks down the forecast by Type, by Application, geography, and market size to highlight emerging pockets of opportunity. With a transparent methodology based on hundreds of bottom-up qualitative and quantitative market inputs, this study forecast offers a highly nuanced view of the current state and future trajectory in the global Two-finger Parallel Pneumatic Gripper.

This report presents a comprehensive overview, market shares, and growth opportunities of Two-finger Parallel Pneumatic Gripper market by product type, application, key manufacturers and key regions and countries.

Segmentation by Type:

Slide Rail Type

Wedge Block Drive Type

Rack and Pinion Type

Ball Guide Type

Others

Segmentation by Gripping Force Range:

5 ? 50 N

50 ? 300 N

300 ? 2000 N

2000 ? 10000 N

Above 10000 N

Segmentation by Application:

Industrial Robots

CNC Machine Tools

Automated Assembly Lines

Others

This report also splits the market by region:

Americas

United States

Canada

Mexico

Brazil

APAC

China

Japan

Korea

Southeast Asia

India

Australia

Europe

Germany

France

UK

Italy

Russia

Middle East & Africa

Egypt

South Africa

Israel

Turkey

GCC Countries

The below companies that are profiled have been selected based on inputs gathered from primary experts and analysing the company's coverage, product portfolio, its market penetration.

Destaco

SMC

FESTO

SCHUNK

Zimmer Group

AirTAC

WOMMER

Fouk Machinery

DH-Robotics

HITBOT

Qiaotian Intelligent Equipment

Key Questions Addressed in this Report

What is the 10-year outlook for the global Two-finger Parallel Pneumatic Gripper market?

What factors are driving Two-finger Parallel Pneumatic Gripper market growth, globally and by region?

Which technologies are poised for the fastest growth by market and region?

How do Two-finger Parallel Pneumatic Gripper market opportunities vary by end market size?

How does Two-finger Parallel Pneumatic Gripper break out by Type, by Application?

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