

Global Tomato Harvesting Robot Market Growth 2026-2032

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Abstracts

The global Tomato Harvesting Robot market size is predicted to grow from US\$ 25.83 million in 2025 to US\$ 58.48 million in 2032; it is expected to grow at a CAGR of 12.4% from 2026 to 2032.

The tomato harvesting robot is a smart agricultural equipment that uses machine vision technology and automated control systems. It can accurately identify and locate ripe tomatoes and automatically complete the picking and collection work. It is characterized by efficient operation, precise picking, low damage rate, and can operate stably in complex and changeable farmland environments, greatly reducing the labor intensity of manual picking, and improving picking efficiency and the automation level of agricultural production. In 2025, global Tomato Harvesting Robot production reached approximately 240 units with an average global market price of around k US\$110 per unit.

The tomato harvesting robot industry is currently in a phase of rapid development, with the global transformation toward smart agriculture presenting significant opportunities for this field. As a pioneer in the industry, the Chinese Academy of Agricultural Mechanization Sciences has successfully made breakthroughs in multiple key technologies and developed a range of robot products covering the entire process of planting, harvesting, and field management, significantly enhancing agricultural production efficiency and quality. These robots leverage various sensing technologies such as vision and LiDAR, integrating AI deep learning and large model training algorithms to achieve precise recognition and localization of tomatoes and their peduncles. Combined with an innovative clip-and-cut integrated end-effector and an autonomous mobile chassis, they demonstrate outstanding performance. The YOLOv8np-RCW model proposed by Professor Yuan Ting's team at China Agricultural University employs a decoupled head structure to simultaneously detect tomato

clusters, ripeness, and picking keypoints, providing an efficient solution for the industry. Currently, China's research output in agricultural robotics has surpassed that of the United States, with a particular focus on harvesting and picking robots. In the future, the industry must overcome challenges related to environmental adaptability, strengthen cross-disciplinary collaboration, and explore more flexible business models, such as developing interchangeable end-effectors to improve robot utilization. Facility horticulture robots have already achieved labor-reduced operations across the entire tomato planting process, including transportation, spraying, pollination, inspection, and harvesting, offering a diversified development pathway for the industry.

LP Information, Inc. (LPI) ' newest research report, the "Tomato Harvesting Robot Industry Forecast" looks at past sales and reviews total world Tomato Harvesting Robot sales in 2025, providing a comprehensive analysis by region and market sector of projected Tomato Harvesting Robot sales for 2026 through 2032. With Tomato Harvesting Robot sales broken down by region, market sector and sub-sector, this report provides a detailed analysis in US\$ millions of the world Tomato Harvesting Robot industry.

This Insight Report provides a comprehensive analysis of the global Tomato Harvesting Robot landscape and highlights key trends related to product segmentation, company formation, revenue, and market share, latest development, and M&A activity. This report also analyzes the strategies of leading global companies with a focus on Tomato Harvesting Robot portfolios and capabilities, market entry strategies, market positions, and geographic footprints, to better understand these firms' unique position in an accelerating global Tomato Harvesting Robot market.

This Insight Report evaluates the key market trends, drivers, and affecting factors shaping the global outlook for Tomato Harvesting Robot and breaks down the forecast by Type, by Application, geography, and market size to highlight emerging pockets of opportunity. With a transparent methodology based on hundreds of bottom-up qualitative and quantitative market inputs, this study forecast offers a highly nuanced view of the current state and future trajectory in the global Tomato Harvesting Robot.

This report presents a comprehensive overview, market shares, and growth opportunities of Tomato Harvesting Robot market by product type, application, key manufacturers and key regions and countries.

Segmentation by Type:

track-motion

Self-propelled

Segmentation by System Configuration:

Single Arm

Dual Arm

Segmentation by Automation Level:

Fully Automated

Semi-automated

Segmentation by Application:

Farmland

Greenhouse

Others

This report also splits the market by region:

Americas

United States

Canada

Mexico

Brazil

APAC

China

Japan

Korea

Southeast Asia

India

Australia

Europe

Germany

France

UK

Italy

Russia

Middle East & Africa

Egypt

South Africa

Israel

Turkey

GCC Countries

The below companies that are profiled have been selected based on inputs gathered from primary experts and analysing the company's coverage, product portfolio, its market penetration.

Inaho

Certhon

MetoMotion

TTA-ISO

Tokuiten

Four Growers

GRoW

Ridder

Suzhou Botian Automation Technology

Tianfalcon (Wuhan) Technology

Hangzhou Qogori(K2) Tech

Beijing AIForce Technology

Nanjing Xiyue Intelligent Technology

Key Questions Addressed in this Report

What is the 10-year outlook for the global Tomato Harvesting Robot market?

What factors are driving Tomato Harvesting Robot market growth, globally and by region?

Which technologies are poised for the fastest growth by market and region?

How do Tomato Harvesting Robot market opportunities vary by end market size?

How does Tomato Harvesting Robot break out by Type, by Application?

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