

Global Tactile Data Acquisition Service Market Growth (Status and Outlook) 2026-2032

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Abstracts

The global Tactile Data Acquisition Service market size is predicted to grow from US\$ 798 million in 2025 to US\$ 3189 million in 2032; it is expected to grow at a CAGR of 22.0% from 2026 to 2032.

Tactile data acquisition services are specialized data services that capture, synchronize, process, and structure tactile information—centered on physical contact between robots, objects, human bodies, and the environment—to produce deliverable datasets. This research primarily covers a service ecosystem comprising tactile sensors, force/torque sensors, vision-based tactile devices, robotic dexterous hands or grippers, teleoperation systems, acquisition software, and data processing infrastructure. Core data includes contact pressure, normal force, shear force, deformation, slip, vibration, surface texture, contact geometry, temperature, and tactile images; high-end systems further synchronize the acquisition of tactile information with visual data, robot joint states, motion trajectories, and operational commands.

Key Findings

Tactile data has become critical for dexterous manipulation.

Multimodal data acquisition is replacing single-mode force measurement.

Embodied AI is driving the demand for real-world interaction data.

High-frequency data acquisition supports training for complex contact-based manipulation.

Industrial robotics remains the primary commercial application scenario.

Industry Trends

Tactile data acquisition services are evolving from sensor-centric measurement operations into data infrastructure designed for physical interaction. Early tactile systems primarily recorded pressure, force, or contact distribution for engineering testing and quality inspection. With the rise of embodied AI, the market now demands synchronized data—encompassing tactile, visual, proprioceptive, and action states—that can feed directly into robot learning pipelines. Consequently, the value of tactile data has expanded beyond measurement and analysis to include model training, policy learning, manipulation assessment, and automated recovery.

Market Dynamics

Driving Factors

The primary growth driver for tactile data acquisition services is the increasing demand for robots capable of complex contact-based manipulation. Tasks such as grasping, insertion, fastening, pressing, manipulating flexible objects, and detecting slippage are difficult to perform reliably using vision alone; robots require additional information regarding contact occurrence, direction, force magnitude, and material deformation. Tactile information becomes particularly crucial when target positioning is imprecise, vision is obstructed, or when dealing with transparent, flexible, or complex-structured objects. XELA views industrial tasks like insertion and assembly as key applications for tactile sensing, utilizing contact and force feedback to help robots detect deviations and adjust their pose and manipulation force in real-time.

Limiting Factors

The production costs and engineering complexity associated with high-quality, real-world tactile data remain significant barriers to market expansion. Unlike image or text data, tactile data must be generated through physical contact between sensors and real objects; thus, data acquisition efficiency is constrained by factors such as robot hardware, human operators, task execution speed, and sensor durability. High-resolution systems also require rigorous calibration and precise temporal synchronization with robot state and visual data. Data formats vary significantly across tactile technologies: vision-based tactile sensors typically generate image-like contact data, force arrays primarily output multi-dimensional force information, and electronic

skins produce high-density spatiotemporal signals. This heterogeneity increases the costs associated with data cleaning and format standardization.

Market Opportunities

Training-grade tactile datasets designed for embodied foundation models, dexterous manipulation models, and humanoid robots represent the market opportunity with the greatest future potential. As robots evolve from simple pick-and-place operations to general-purpose manipulation, tactile sensing provides crucial information—such as contact states, friction, material properties, deformation, and slippage—that cameras struggle to reliably assess. Consequently, integrating tactile data with visual data, proprioceptive states, language instructions, and motion trajectories into a unified dataset offers significantly higher training value than isolated sensor recordings.

Industry Risks and Challenges

A core long-term challenge for the industry is establishing data standards that are reusable across diverse tactile technologies and robot platforms. Tactile data varies widely in terms of sensor form factor, force range, taxel density, sampling frequency, coordinate systems, contact materials, and calibration methods; this makes cross-platform data integration and joint model training significantly more complex than handling traditional visual data. Data quality is another critical issue, as repeated physical contact can lead to sensor drift, wear, changes in frictional conditions, and reduced trajectory repeatability. For AI training, simply increasing data volume does not guarantee improved model capabilities; factors such as task coverage, the diversity of contact scenarios, the accuracy of force calibration, and the quality of motion label synchronization are equally important. Furthermore, adapting tactile input for multimodal foundation models remains in the exploratory stage, with various technical approaches emerging—ranging from raw signals and tactile images to processed force vectors and learned latent space representations. Moving forward, service providers must continuously balance data precision, acquisition efficiency, hardware reliability, and data costs.

Value Chain Analysis

The upstream segment of the tactile data acquisition service value chain comprises tactile sensing technologies, force/torque sensors, vision-based tactile sensors, electronic skin, robotic dexterous hands and grippers, data acquisition electronics, cameras, motion capture equipment, edge computing modules, teleoperation hardware,

and data storage resources. These foundational components determine the types of physical information that can be captured and set the technical upper limits of the resulting datasets.

Midstream service providers create value through activities such as experimental design, object and task selection, robotic or manual operation, multimodal synchronization, sensor calibration, data cleaning, annotation, trajectory segmentation, quality control, and dataset management and delivery. The market is shifting from pure hardware sales toward a combined "hardware + software + data service" model. For instance, companies like Daimon have developed a product ecosystem encompassing vision-based tactile sensors, datasets, teleoperation data acquisition systems, and Data-as-a-Service (DaaS) offerings, while Pasini is simultaneously targeting the markets for multidimensional tactile hardware and embodied AI data clouds. Downstream customers further utilize this data for embodied foundation models, dexterous manipulation by humanoid and industrial robots, medical robotics, prosthetics and rehabilitation, service robots, and haptic research. Consequently, future value creation depends increasingly on factors such as the volume of effective interaction trajectories, multimodal completeness, annotation quality, data reproducibility, and seamless integration with model training workflows, rather than merely on the unit price of individual sensors.

Market Segment Analysis

Based on the number of synchronized haptic modalities, haptic data acquisition services can be categorized into: single-modal services (1 modality); basic multimodal services (2–3 modalities); advanced multimodal services (4–6 modalities); and full-modal haptic services (7 or more modalities). The market is shifting toward advanced multimodal capabilities because dexterous robots require not only the detection of contact but also the simultaneous identification of force direction and magnitude, slippage, surface texture, and object deformation.

Downstream Market Opportunities

Embodied AI and humanoid robotics represent the most strategically valuable downstream markets for haptic data acquisition services; haptic information enhances capabilities in dexterous grasping, fine manipulation, contact state assessment, and adaptation to unknown objects. Industrial manufacturing stands out as one of the sectors with the strongest commercialization foundations; tasks such as plugging/unplugging, assembly, connector handling, grinding, press-fitting, and flexible

material handling often suffer from errors when relying solely on vision, whereas haptic feedback enables robots to achieve finer control.

Report Scope

LPI (LP Information)' newest research report, the "Tactile Data Acquisition Service Industry Forecast" looks at past sales and reviews total world Tactile Data Acquisition Service sales in 2025, providing a comprehensive analysis by region and market sector of projected Tactile Data Acquisition Service sales for 2026 through 2032. With Tactile Data Acquisition Service sales broken down by region, market sector and sub-sector, this report provides a detailed analysis in US\$ millions of the world Tactile Data Acquisition Service industry.

This Insight Report provides a comprehensive analysis of the global Tactile Data Acquisition Service landscape and highlights key trends related to product segmentation, company formation, revenue, and market share, latest development, and M&A activity. This report also analyses the strategies of leading global companies with a focus on Tactile Data Acquisition Service portfolios and capabilities, market entry strategies, market positions, and geographic footprints, to better understand these firms' unique position in an accelerating global Tactile Data Acquisition Service market.

This Insight Report evaluates the key market trends, drivers, and affecting factors shaping the global outlook for Tactile Data Acquisition Service and breaks down the forecast by Type, by Application, geography, and market size to highlight emerging pockets of opportunity. With a transparent methodology based on hundreds of bottom-up qualitative and quantitative market inputs, this study forecast offers a highly nuanced view of the current state and future trajectory in the global Tactile Data Acquisition Service.

This report presents a comprehensive overview, market shares, and growth opportunities of Tactile Data Acquisition Service market by product type, application, key players and key regions and countries.

Market Segmentation

Segmentation by Type:

Single-Modality Acquisition Platform (1 Modality)

Basic Multimodal Platform (2–3 Modalities)

Advanced Multimodal Platform (4–6 Modalities)

Full-Modality Acquisition Platform (?7 Modalities)

Segmentation by Tactile Sampling Frequency:

Low-Frequency Data Acquisition Platform

Standard Data Acquisition Platform

High-Frequency Data Acquisition Platform

Ultra-High-Frequency Data Acquisition Platform

Segmentation by Synchronization Delay:

Offline Synchronization Type

Near-Real-Time Synchronization Type

Real-Time Synchronization Type

Ultra-Low-Latency Synchronization Type

Segmentation by Application:

Embodied AI and Humanoid Robots

Automotive Manufacturing Industry

Consumer Electronics Industry

Logistics Industry

Healthcare Industry

Others

This report also splits the market by region:

Americas

United States

Canada

Mexico

Brazil

APAC

China

Japan

Korea

Southeast Asia

India

Australia

Europe

Germany

France

UK

Italy

Russia

Middle East & Africa

Egypt

South Africa

Israel

Turkey

GCC Countries

The below companies that are profiled have been selected based on inputs gathered from primary experts and analyzing the company's coverage, product portfolio, its market penetration.

GelSight

Tekscan

ATI Industrial Automation

Pressure Profile Systems

Shadow Robot

Touchlab

Tacterion

WEISS Robotics

OnRobot

PaXini Tech

Xense Robotics

Daimon Robotics

AgileTact

ViTai Robotics

SaiGan Technology

XELA Robotics

Touchence

Nitta

WACOH-TECH

Leprino

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