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Global Servo Rotary Electric Gripper Market Growth 2026-2032

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Abstracts

The global Servo Rotary Electric Gripper market size is predicted to grow from US$ 76.79 million in 2025 to US$ 133 million in 2032; it is expected to grow at a CAGR of 8.4% from 2026 to 2032.

A servo rotary electric gripper is a mechatronic end effector that integrates an electric gripping mechanism, a servo rotary mechanism, position feedback components, and a drive control system, enabling simultaneous workpiece gripping and rotary positioning. The gripping axis and rotary axis are typically controlled by independent servo systems, allowing programmable control of gripping position, gripping force, gripping speed, rotation angle, and rotation speed, while supporting either continuous rotation or rotation to a specified angle. In essence, the product is an integrated actuation unit combining a servo electric gripper with an independent rotary axis. Compared with a conventional electric gripper, it provides an additional independently controlled rotational degree of freedom, eliminating the need for a separate rotary module and enabling compound operations such as gripping, reorientation, twisting, and positioning.

Key Findings

Integrated gripping and rotation define the core product value

Dual-axis servo control represents a major technical barrier

Direct-drive architecture supports higher-precision product development

High integration is becoming an important equipment-selection factor

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Market Trends

Servo Rotary Electric Gripper products are evolving from conventional geared mechanisms and basic rotary gripping toward higher precision, lower backlash, and integrated drive-control architectures. Development priorities increasingly include rotary positioning accuracy, gripping-force control, dynamic response, and more compact mechanical integration. Industrial communication, operating-status feedback, and programmable control are also becoming more important, supporting the transition toward standardized dual-degree-of-freedom motion units for precision automation equipment.

Market Dynamics

Drivers

Automated equipment increasingly requires combined motions such as gripping, rotation, flipping, alignment, and assembly after workpiece pickup. Conventional configurations using a separate gripper and rotary module can increase installation space, mechanical interfaces, and control complexity. Servo Rotary Electric Gripper integrates both functions into one execution unit, reducing peripheral mechanisms while enabling programmable control of gripping force, position, and rotation angle. This creates particular value in high-density automation, flexible assembly, and multi-product manufacturing environments.

Restraints

Dual-axis servo systems, precision transmission mechanisms, encoder feedback, and compact mechanical architecture increase manufacturing complexity and product cost. The gripping and rotary axes must simultaneously balance rigidity, precision, torque, thermal performance, and service life within limited space. For applications requiring only basic gripping or fixed-angle rotation, conventional electric grippers combined with lower-cost rotary mechanisms may remain economically attractive, limiting adoption to applications with stronger requirements for integration, flexibility, and precision.

Opportunities

Medical automation, precision Electronics and Semiconductor assembly, New Energy manufacturing, and flexible robotic operations provide significant opportunities for Servo Rotary Electric Gripper development. As machine footprints shrink and process motions

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become more complex, products capable of gripping, rotating, and accurately positioning within a single module provide greater integration value. Direct-drive rotation, zero-backlash architecture, precision force control, absolute position feedback, and industrial communication are also important directions for penetration into higher-value applications.

Challenges

Servo Rotary Electric Gripper products still lack a highly standardized specification framework, with significant differences among manufacturers in gripping stroke, gripping force, rotary torque, positioning accuracy, communication interfaces, and mounting dimensions. These differences increase the complexity of cross-brand replacement and standardized machine design. Conventional electric grippers, rotary actuators, and customized end-effectors are also improving, requiring manufacturers to differentiate through precision, reliability, service life, integration convenience, and cost.

Industry Chain Analysis

The upstream industry chain includes servo motors, miniature drive motors, encoders, precision gears, bearings, reduction mechanisms, force or position sensors, servo drives, control chips, and precision structural components. Midstream manufacturing requires mechanical integration of gripping and rotary mechanisms together with coordinated dual-axis control, including drive algorithms, feedback control, precision assembly, calibration, and durability testing. Commercial products are primarily developed around Gear Transmission Type and Direct Drive Type architectures.

Value creation is concentrated in precision mechanical design, dual-axis motion control, gripping-force regulation, rotary positioning, and overall system reliability. Direct Drive Type products reduce intermediate transmission elements and place greater requirements on motor design, control algorithms, and feedback accuracy, while Gear Transmission Type products emphasize transmission design, torque amplification, and cost efficiency. Downstream products are integrated into Medical, Electronics and Semiconductor, Automotive, New Energy, and Packaging equipment as robotic or automated end-effectors for compound motion tasks.

Segment Insights

By drive architecture, Gear Transmission Type products offer mature technology, flexible torque output, and relatively controllable cost, making them suitable for a broad

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range of rotary gripping tasks. Direct Drive Type products reduce mechanical backlash associated with gears and reduction mechanisms and can improve dynamic response and rotary positioning performance, giving them stronger suitability for high-precision assembly, inspection, and alignment. As precision manufacturing requirements rise, direct-drive solutions provide meaningful upgrade potential, although motor, feedback, and control requirements are also higher.

By gripping force, products at ?35 N are oriented toward lightweight workpieces and precision handling, while the 35–100 N range covers a wider spectrum of industrial automation tasks. Products above 100 N address applications requiring greater payload and stronger gripping capability. Each gripping-force class is also associated with different body dimensions, rotary torque, and end-load capability, meaning that actual product competition is based on the overall balance among gripping performance, rotary capability, and compactness.

Downstream Market Opportunities

Medical automation is well suited to gripping and rotating small objects such as tubes and sample containers. Electronics and Semiconductor manufacturing places greater emphasis on precision positioning, flexible gripping, and compact equipment integration. Automotive and New Energy applications generate demand for assembly, inspection, and component rotation, while Packaging automation emphasizes cycle speed, flexible changeover, and continuous operation. As automation systems increasingly combine multiple movements within individual process steps, integrated rotary gripping solutions can address a broader range of equipment designs.

Regional Insights

The regional supply structure of Servo Rotary Electric Gripper closely follows the development of robotics, precision automation, and end-effector industries. Asia has an active manufacturing and application base, with Japanese suppliers benefiting from established industrial automation platforms and standardized component capabilities, while specialized Chinese manufacturers continue to expand portfolios in electric gripping, integrated drive-control systems, and precision force control. Europe benefits from a mature industrial automation and precision-equipment ecosystem, with strong demand for reliability, modularity, and standardized interfaces.

Competitive Landscape Analysis

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Confirmed manufacturers in the Servo Rotary Electric Gripper market include SMC, Festo, SCHUNK, Zimmer Group, IAI, KSS, DH-Robotics, HITBOT, Jodell Robotics, and Foshan Augmented Intelligence Technology. International manufacturers generally compete through established automation platforms, standardized product systems, and broad industrial customer bases, while specialized Chinese suppliers are actively developing electric servo gripping, integrated drive-control architectures, rapid product iteration, and application-specific solutions. Competitive differentiation is shifting beyond gripping force and rotational speed toward positioning accuracy, backlash control, dual-axis coordination, compact dimensions, communication capability, and machine-integration efficiency.

Report Scope

LP Information, Inc. (LPI) ' newest research report, the “Servo Rotary Electric Gripper Industry Forecast” looks at past sales and reviews total world Servo Rotary Electric Gripper sales in 2025, providing a comprehensive analysis by region and market sector of projected Servo Rotary Electric Gripper sales for 2026 through 2032. With Servo Rotary Electric Gripper sales broken down by region, market sector and sub-sector, this report provides a detailed analysis in US$ millions of the world Servo Rotary Electric Gripper industry.

This Insight Report provides a comprehensive analysis of the global Servo Rotary Electric Gripper landscape and highlights key trends related to product segmentation, company formation, revenue, and market share, latest development, and M&A activity. This report also analyzes the strategies of leading global companies with a focus on Servo Rotary Electric Gripper portfolios and capabilities, market entry strategies, market positions, and geographic footprints, to better understand these firms’ unique position in an accelerating global Servo Rotary Electric Gripper market.

This Insight Report evaluates the key market trends, drivers, and affecting factors shaping the global outlook for Servo Rotary Electric Gripper and breaks down the forecast by Type, by Application, geography, and market size to highlight emerging pockets of opportunity. With a transparent methodology based on hundreds of bottom-up qualitative and quantitative market inputs, this study forecast offers a highly nuanced view of the current state and future trajectory in the global Servo Rotary Electric Gripper.

This report presents a comprehensive overview, market shares, and growth opportunities of Servo Rotary Electric Gripper market by product type, application, key

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manufacturers and key regions and countries.

Market Segmentation

Segmentation by Type:

Rod Type

Guided Rod Type

Slider Type

Segmentation by Gripping Force:

?100 N

100–300 N

?300 N

Segmentation by Application:

Lithium Battery

Semiconductor and Electronics

Medical Device

Robot

Other

This report also splits the market by region:

Americas

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United States

Canada

Mexico

Brazil

APAC

China

Japan

Korea

Southeast Asia

India

Australia

Europe

Germany

France

UK

Italy

Russia

Middle East & Africa

Egypt

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South Africa

Israel

Turkey

GCC Countries

The below companies that are profiled have been selected based on inputs gathered from primary experts and analysing the company's coverage, product portfolio, its market penetration.

SMC

Festo

SCHUNK

Zimmer Group

KSS

Shenzhen DH-Robotics Technology

Huiling-tech Robotic

Suzhou Jodell Robotics

Key Questions Addressed in this Report

What is the 10-year outlook for the global Servo Rotary Electric Gripper market?

What factors are driving Servo Rotary Electric Gripper market growth, globally and by region?

Which technologies are poised for the fastest growth by market and region?

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How do Servo Rotary Electric Gripper market opportunities vary by end market size?

How does Servo Rotary Electric Gripper break out by Type, by Application?

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