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Global Multi-axis Force Torque Sensor for Robot Market Growth 2026-2032

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Abstracts

The global Multi-axis Force Torque Sensor for Robot market size is predicted to grow from US$ 347 million in 2025 to US$ 2251 million in 2032; it is expected to grow at a CAGR of 33.2% from 2026 to 2032.

In 2025, global Multi-axis Force Torque Sensor for Robot production reached approximately 148 k units?with an average global market price of around US$ 2,400 per unit, and a gross profit margin of approximately 20%-40%. Multi-axis Force Torque Sensors for Robots are precision sensing devices that simultaneously measure forces and torques acting along multiple spatial axes. Six-axis products measure three orthogonal forces—Fx, Fy, and Fz—and three corresponding moments—Tx, Ty, and Tz—while simplified products may measure three or five components. A typical sensor integrates an elastic structure, strain gauges or other sensing elements, signal-conditioning circuits, analog-to-digital converters, temperature-compensation components, embedded processors, communication interfaces, calibration matrices, and mechanical mounting flanges. Sensors are commonly installed between a robot wrist and end effector or integrated into robotic feet and manipulation platforms to provide real-time contact feedback.

The industrial chain of Multi-axis Force Torque Sensors for Robots includes upstream strain gauges, piezoelectric materials, capacitive or optical sensing elements, elastic alloy structures, stainless steel, aluminum alloys, adhesive materials, amplifiers, analog-to-digital converters, processors, temperature sensors, PCBs, cables, connectors, and industrial communication chips. Midstream activities include elastic-structure design, finite-element analysis, precision machining, sensing-element bonding, circuit assembly, temperature compensation, decoupling-algorithm development, calibration, overload testing, cross-talk testing, fatigue testing, environmental validation, firmware

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development, and robot-interface integration. Downstream applications include industrial robots, collaborative robots, humanoid robots, surgical robots, legged robots, robotic arms, polishing equipment, assembly systems, teleoperation platforms, and robotics research.

United States market for Multi-axis Force Torque Sensor for Robot is estimated to increase from US$ million in 2025 to US$ million by 2032, at a CAGR of % from 2026 through 2032.

China market for Multi-axis Force Torque Sensor for Robot is estimated to increase from US$ million in 2025 to US$ million by 2032, at a CAGR of % from 2026 through 2032.

Europe market for Multi-axis Force Torque Sensor for Robot is estimated to increase from US$ million in 2025 to US$ million by 2032, at a CAGR of % from 2026 through 2032.

Global key Multi-axis Force Torque Sensor for Robot players cover ATI Industrial Automation, Sunrise Instruments (SRI), Schunk, Kunwei, Link-touch, etc. In terms of revenue, the global two largest companies occupied for a share nearly % in 2025.

LP Information, Inc. (LPI) ' newest research report, the “Multi-axis Force Torque Sensor for Robot Industry Forecast” looks at past sales and reviews total world Multi-axis Force Torque Sensor for Robot sales in 2025, providing a comprehensive analysis by region and market sector of projected Multi-axis Force Torque Sensor for Robot sales for 2026 through 2032. With Multi-axis Force Torque Sensor for Robot sales broken down by region, market sector and sub-sector, this report provides a detailed analysis in US$ millions of the world Multi-axis Force Torque Sensor for Robot industry.

This Insight Report provides a comprehensive analysis of the global Multi-axis Force Torque Sensor for Robot landscape and highlights key trends related to product segmentation, company formation, revenue, and market share, latest development, and M&A activity. This report also analyzes the strategies of leading global companies with a focus on Multi-axis Force Torque Sensor for Robot portfolios and capabilities, market entry strategies, market positions, and geographic footprints, to better understand these firms’ unique position in an accelerating global Multi-axis Force Torque Sensor for Robot market.

This Insight Report evaluates the key market trends, drivers, and affecting factors

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shaping the global outlook for Multi-axis Force Torque Sensor for Robot and breaks down the forecast by Type, by Application, geography, and market size to highlight emerging pockets of opportunity. With a transparent methodology based on hundreds of bottom-up qualitative and quantitative market inputs, this study forecast offers a highly nuanced view of the current state and future trajectory in the global Multi-axis Force Torque Sensor for Robot.

This report presents a comprehensive overview, market shares, and growth opportunities of Multi-axis Force Torque Sensor for Robot market by product type, application, key manufacturers and key regions and countries.

Segmentation by Type:

Aluminum

Stainless Steel

Others

Segmentation by Diameter:

Diameter: 60mm

Diameter: 75mm

Others

Segmentation by Application:

Collaborative Robots

Humanoid Robots

Medical and Surgical Robots

Others

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This report also splits the market by region:

- Americas
  - United States
  - Canada
  - Mexico
  - Brazil
- APAC
  - China
  - Japan
  - Korea
  - Southeast Asia
  - India
  - Australia
- Europe
  - Germany
  - France
  - UK
  - Italy

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Russia

Middle East & Africa

Egypt

South Africa

Israel

Turkey

GCC Countries

The below companies that are profiled have been selected based on inputs gathered from primary experts and analysing the company's coverage, product portfolio, its market penetration.

ATI Industrial Automation

Sunrise Instruments (SRI)

Schunk

Kunwei

Link-touch

AMTI

XJCSENSOR

Kistler

Robotiq

Bota Systems

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Nordbo Robotics

Wacoh-Tech

FUTEK

Robotous

Aidin Robotics

ME-Me?systeme

Sintokogio

OnRobot

Hypersen Technologies

Anhui Zhongkemi Dian Sensor

Changzhou Right Measurement and Control System

CHI FENG Technology

Key Questions Addressed in this Report

What is the 10-year outlook for the global Multi-axis Force Torque Sensor for Robot market?

What factors are driving Multi-axis Force Torque Sensor for Robot market growth, globally and by region?

Which technologies are poised for the fastest growth by market and region?

How do Multi-axis Force Torque Sensor for Robot market opportunities vary by end market size?

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How does Multi-axis Force Torque Sensor for Robot break out by Type, by Application?

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