

Global Mobile Manipulator Grippers Market Growth 2026-2032

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Abstracts

The global Mobile Manipulator Grippers market size is predicted to grow from US\$ 58.70 million in 2025 to US\$ 205 million in 2032; it is expected to grow at a CAGR of 18.7% from 2026 to 2032.

Mobile Manipulator Grippers are gripping end-effectors mounted at the wrist of a mobile manipulator, enabling the robot to grasp, pick, carry, place, and perform basic manipulation tasks after the mobile base reaches the target location. A typical product consists of mechanical fingers or soft fingertips, an actuator, force and position feedback modules, a controller, communication interfaces, flange adapters, and replaceable fingertips. Main product forms include electric parallel grippers, two-finger and three-finger adaptive grippers, soft grippers, vacuum-assisted hybrid grippers, and lightweight dexterous hands.

From an application perspective, Mobile Manipulator Grippers are not merely conventional industrial robot grippers used on a moving base. They are highly integrated end-effectors designed for mobile operation, dynamic environments, and human-adjacent deployment. Key requirements include low weight, low power consumption, fast deployment, object adaptability, and safety redundancy. Major applications include warehouse picking, mobile machine tending, laboratory automation, healthcare and commercial service robots, flexible manufacturing, inspection and maintenance, and robotics data collection. Major production and technology clusters are concentrated in the United States, Canada, Germany, Denmark, Japan, China, and South Korea.

In 2025, global Mobile Manipulator Grippers production reached approximately 11,000?15,000 sets, with demand mainly driven by warehouse picking, mobile machine

tending, research and robot training platforms, healthcare logistics, and commercial service robot applications. Mainstream FOB prices were approximately USD 3,000-7,800 per set. High-end dexterous hands and adaptive grippers with force control and multi-sensor feedback were priced significantly higher, while standard two-finger electric grippers and lightweight collaborative grippers remained the primary shipment category.

Mobile Manipulator Grippers are evolving from robotic accessories into a critical interface for mobile manipulation. In the past, mobile robots mainly handled transport, while robotic arms were usually deployed at fixed workstations. Today, manufacturers, warehouse operators, and service organizations are integrating mobile bases, collaborative arms, vision systems, and grippers into one mobile work unit, allowing robots not only to move objects across a facility but also to pick, sort, load, unload, and interact with them. For gripper suppliers, the opportunity comes from two directions: rising installations of mobile manipulators and growing demand for reliable grasping of mixed, irregular, and less-structured objects. In e-commerce logistics, semiconductor and electronics manufacturing, laboratory automation, hospital logistics, and robotics data collection, gripper reliability, compatibility, and software integration increasingly determine the practical deployment efficiency of the whole robot system.

The market still faces clear constraints. Mobile manipulators operate with more diverse objects, larger positioning uncertainty, and less controlled environments, which raises the requirements for force control, sensing, tolerance, and safety design. At the same time, customers often expect one gripper to cover more object types, but differences in size, weight, surface material, and grasping posture make it difficult for a single product to handle all use cases. On the pricing side, mobile manipulator systems remain relatively expensive, and end users continue to evaluate return on investment carefully before scaling deployments, limiting the pricing premium available to gripper suppliers. Over the next several years, competition will move beyond gripping force, stroke, and payload, shifting toward the combined capability of gripper hardware, vision, force control, software interfaces, and scenario data. Companies that can provide standardized interfaces, rapid changeover, stable grasping performance, and proven application cases will be better positioned to enter the mobile manipulation robot supply chain.

LP Information, Inc. (LPI)'s newest research report, the "Mobile Manipulator Grippers Industry Forecast" looks at past sales and reviews total world Mobile Manipulator Grippers sales in 2025, providing a comprehensive analysis by region and market sector of projected Mobile Manipulator Grippers sales for 2026 through 2032. With

Mobile Manipulator Grippers sales broken down by region, market sector and sub-sector, this report provides a detailed analysis in US\$ millions of the world Mobile Manipulator Grippers industry.

This Insight Report provides a comprehensive analysis of the global Mobile Manipulator Grippers landscape and highlights key trends related to product segmentation, company formation, revenue, and market share, latest development, and M&A activity. This report also analyzes the strategies of leading global companies with a focus on Mobile Manipulator Grippers portfolios and capabilities, market entry strategies, market positions, and geographic footprints, to better understand these firms' unique position in an accelerating global Mobile Manipulator Grippers market.

This Insight Report evaluates the key market trends, drivers, and affecting factors shaping the global outlook for Mobile Manipulator Grippers and breaks down the forecast by Type, by Application, geography, and market size to highlight emerging pockets of opportunity. With a transparent methodology based on hundreds of bottom-up qualitative and quantitative market inputs, this study forecast offers a highly nuanced view of the current state and future trajectory in the global Mobile Manipulator Grippers.

This report presents a comprehensive overview, market shares, and growth opportunities of Mobile Manipulator Grippers market by product type, application, key manufacturers and key regions and countries.

Segmentation by Type:

Electric Finger Grippers

Vacuum Grippers

Adaptive and Soft Grippers

Dexterous Hands

Others

Segmentation by Actuation Method:

Electric Servo Actuation

Pneumatic Actuation

Vacuum Actuation

Magnetic and Passive Actuation

Segmentation by Payload Class:

Below 1 kg

1 kg to 5 kg

5 kg to 10 kg

Above 10 kg

Segmentation by Gripper Structure:

Parallel Jaw Structure

Two Finger Adaptive Structure

Three Finger and Multi Finger Structure

Suction Cup and Foam Pad Structure

Segmentation by Application:

Logistics and E Commerce

Industrial Manufacturing

Research Education and Robot Training

Healthcare Commercial Service

Others

This report also splits the market by region:

Americas

United States

Canada

Mexico

Brazil

APAC

China

Japan

Korea

Southeast Asia

India

Australia

Europe

Germany

France

UK

Italy

Russia

Middle East & Africa

Egypt

South Africa

Israel

Turkey

GCC Countries

The below companies that are profiled have been selected based on inputs gathered from primary experts and analysing the company's coverage, product portfolio, its market penetration.

SCHUNK SE & Co. KG

Zimmer Group

Festo SE & Co. KG

J. Schmalz GmbH

Stabilus SE (DESTACO)

OnRobot A/S

Piab Group

Robotiq Inc.

PHD, Inc.

New Scale Robotics, Inc.

SMC Corporation

IAI Corporation

CKD Corporation

Oriental Motor Co., Ltd.

Koganei Corporation

DH-Robotics Technology Co., Ltd.

Hitbot Technology (Shenzhen) Co., Ltd.

Beijing Inspire Robots Technology Co., Ltd.

Linkerbot Beijing Technology Co., Ltd.

Soft Robot Tech Co., Ltd. (SRT)

Suzhou Rochu Robotics Co., Ltd.

HIWIN Technologies Corp.

TESOLLO INC.

ROBOTIS Co., Ltd.

Janatics India Private Limited

Key Questions Addressed in this Report

What is the 10-year outlook for the global Mobile Manipulator Grippers market?

What factors are driving Mobile Manipulator Grippers market growth, globally and by region?

Which technologies are poised for the fastest growth by market and region?

How do Mobile Manipulator Grippers market opportunities vary by end market size?

How does Mobile Manipulator Grippers break out by Type, by Application?

Contents

1 SCOPE OF THE REPORT

- 1.1 Market Introduction
- 1.2 Years Considered
- 1.3 Research Objectives
- 1.4 Market Research Methodology
- 1.5 Research Process and Data Source
- 1.6 Economic Indicators
- 1.7 Currency Considered
- 1.8 Market Estimation Caveats

2 EXECUTIVE SUMMARY

- 2.1 World Market Overview
 - 2.1.1 Global Mobile Manipulator Grippers Annual Sales 2021-2032
 - 2.1.2 World Current & Future Analysis for Mobile Manipulator Grippers by Geographic Region, 2021, 2025 & 2032
 - 2.1.3 World Current & Future Analysis for Mobile Manipulator Grippers by Country/Region, 2021, 2025 & 2032
- 2.2 Mobile Manipulator Grippers Segment by Type
 - 2.2.1 Electric Finger Grippers
 - 2.2.2 Vacuum Grippers
 - 2.2.3 Adaptive and Soft Grippers
 - 2.2.4 Dexterous Hands
 - 2.2.5 Others
 - 2.2.6 Mobile Manipulator Grippers Sales by Type
 - 2.2.6.1 Global Mobile Manipulator Grippers Sales Market Share by Type (2021-2026)
 - 2.2.6.2 Global Mobile Manipulator Grippers Revenue and Market Share by Type (2021-2026)
 - 2.2.6.3 Global Mobile Manipulator Grippers Sale Price by Type (2021-2026)
- 2.3 Mobile Manipulator Grippers Segment by Actuation Method
 - 2.3.1 Electric Servo Actuation
 - 2.3.2 Pneumatic Actuation
 - 2.3.3 Vacuum Actuation
 - 2.3.4 Magnetic and Passive Actuation
 - 2.3.5 Mobile Manipulator Grippers Sales by Actuation Method
 - 2.3.5.1 Global Mobile Manipulator Grippers Sales Market Share by Actuation Method

(2021-2026)

2.3.5.2 Global Mobile Manipulator Grippers Revenue and Market Share by Actuation Method (2021-2026)

2.3.5.3 Global Mobile Manipulator Grippers Sale Price by Actuation Method (2021-2026)

2.4 Mobile Manipulator Grippers Segment by Payload Class

2.4.1 Below 1 kg

2.4.2 1 kg to 5 kg

2.4.3 5 kg to 10 kg

2.4.4 Above 10 kg

2.4.5 Mobile Manipulator Grippers Sales by Payload Class

2.4.5.1 Global Mobile Manipulator Grippers Sales Market Share by Payload Class (2021-2026)

2.4.5.2 Global Mobile Manipulator Grippers Revenue and Market Share by Payload Class (2021-2026)

2.4.5.3 Global Mobile Manipulator Grippers Sale Price by Payload Class (2021-2026)

2.5 Mobile Manipulator Grippers Segment by Gripper Structure

2.5.1 Parallel Jaw Structure

2.5.2 Two Finger Adaptive Structure

2.5.3 Three Finger and Multi Finger Structure

2.5.4 Suction Cup and Foam Pad Structure

2.5.5 Mobile Manipulator Grippers Sales by Gripper Structure

2.5.5.1 Global Mobile Manipulator Grippers Sales Market Share by Gripper Structure (2021-2026)

2.5.5.2 Global Mobile Manipulator Grippers Revenue and Market Share by Gripper Structure (2021-2026)

2.5.5.3 Global Mobile Manipulator Grippers Sale Price by Gripper Structure (2021-2026)

2.6 Mobile Manipulator Grippers Segment by Application

2.6.1 Logistics and E Commerce

2.6.2 Industrial Manufacturing

2.6.3 Research Education and Robot Training

2.6.4 Healthcare Commercial Service

2.6.5 Others

2.6.6 Mobile Manipulator Grippers Sales by Application

2.6.6.1 Global Mobile Manipulator Grippers Sale Market Share by Application (2021-2026)

2.6.6.2 Global Mobile Manipulator Grippers Revenue and Market Share by Application (2021-2026)

2.6.6.3 Global Mobile Manipulator Grippers Sale Price by Application (2021-2026)

3 GLOBAL BY COMPANY

3.1 Global Mobile Manipulator Grippers Breakdown Data by Company

3.1.1 Global Mobile Manipulator Grippers Annual Sales by Company (2021-2026)

3.1.2 Global Mobile Manipulator Grippers Sales Market Share by Company (2021-2026)

3.2 Global Mobile Manipulator Grippers Annual Revenue by Company (2021-2026)

3.2.1 Global Mobile Manipulator Grippers Revenue by Company (2021-2026)

3.2.2 Global Mobile Manipulator Grippers Revenue Market Share by Company (2021-2026)

3.3 Global Mobile Manipulator Grippers Sale Price by Company

3.4 Key Manufacturers Mobile Manipulator Grippers Producing Area Distribution, Sales Area, Product Type

3.4.1 Key Manufacturers Mobile Manipulator Grippers Product Location Distribution

3.4.2 Players Mobile Manipulator Grippers Products Offered

3.5 Market Concentration Rate Analysis

3.5.1 Competition Landscape Analysis

3.5.2 Concentration Ratio (CR3, CR5 and CR10) & (2024-2026)

3.6 New Products and Potential Entrants

3.7 Market M&A Activity & Strategy

4 WORLD HISTORIC REVIEW FOR MOBILE MANIPULATOR GRIPPERS BY GEOGRAPHIC REGION

4.1 World Historic Mobile Manipulator Grippers Market Size by Geographic Region (2021-2026)

4.1.1 Global Mobile Manipulator Grippers Annual Sales by Geographic Region (2021-2026)

4.1.2 Global Mobile Manipulator Grippers Annual Revenue by Geographic Region (2021-2026)

4.2 World Historic Mobile Manipulator Grippers Market Size by Country/Region (2021-2026)

4.2.1 Global Mobile Manipulator Grippers Annual Sales by Country/Region (2021-2026)

4.2.2 Global Mobile Manipulator Grippers Annual Revenue by Country/Region (2021-2026)

4.3 Americas Mobile Manipulator Grippers Sales Growth

- 4.4 APAC Mobile Manipulator Grippers Sales Growth
- 4.5 Europe Mobile Manipulator Grippers Sales Growth
- 4.6 Middle East & Africa Mobile Manipulator Grippers Sales Growth

5 AMERICAS

- 5.1 Americas Mobile Manipulator Grippers Sales by Country
 - 5.1.1 Americas Mobile Manipulator Grippers Sales by Country (2021-2026)
 - 5.1.2 Americas Mobile Manipulator Grippers Revenue by Country (2021-2026)
- 5.2 Americas Mobile Manipulator Grippers Sales by Type (2021-2026)
- 5.3 Americas Mobile Manipulator Grippers Sales by Application (2021-2026)
- 5.4 United States
- 5.5 Canada
- 5.6 Mexico
- 5.7 Brazil

6 APAC

- 6.1 APAC Mobile Manipulator Grippers Sales by Region
 - 6.1.1 APAC Mobile Manipulator Grippers Sales by Region (2021-2026)
 - 6.1.2 APAC Mobile Manipulator Grippers Revenue by Region (2021-2026)
- 6.2 APAC Mobile Manipulator Grippers Sales by Type (2021-2026)
- 6.3 APAC Mobile Manipulator Grippers Sales by Application (2021-2026)
- 6.4 China
- 6.5 Japan
- 6.6 South Korea
- 6.7 Southeast Asia
- 6.8 India
- 6.9 Australia
- 6.10 China Taiwan

7 EUROPE

- 7.1 Europe Mobile Manipulator Grippers by Country
 - 7.1.1 Europe Mobile Manipulator Grippers Sales by Country (2021-2026)
 - 7.1.2 Europe Mobile Manipulator Grippers Revenue by Country (2021-2026)
- 7.2 Europe Mobile Manipulator Grippers Sales by Type (2021-2026)
- 7.3 Europe Mobile Manipulator Grippers Sales by Application (2021-2026)
- 7.4 Germany

7.5 France

7.6 UK

7.7 Italy

7.8 Russia

8 MIDDLE EAST & AFRICA

8.1 Middle East & Africa Mobile Manipulator Grippers by Country

8.1.1 Middle East & Africa Mobile Manipulator Grippers Sales by Country (2021-2026)

8.1.2 Middle East & Africa Mobile Manipulator Grippers Revenue by Country
(2021-2026)

8.2 Middle East & Africa Mobile Manipulator Grippers Sales by Type (2021-2026)

8.3 Middle East & Africa Mobile Manipulator Grippers Sales by Application (2021-2026)

8.4 Egypt

8.5 South Africa

8.6 Israel

8.7 Turkey

8.8 GCC Countries

9 MARKET DRIVERS, CHALLENGES AND TRENDS

9.1 Market Drivers & Growth Opportunities

9.2 Market Challenges & Risks

9.3 Industry Trends

10 MANUFACTURING COST STRUCTURE ANALYSIS

10.1 Raw Material and Suppliers

10.2 Manufacturing Cost Structure Analysis of Mobile Manipulator Grippers

10.3 Manufacturing Process Analysis of Mobile Manipulator Grippers

10.4 Industry Chain Structure of Mobile Manipulator Grippers

11 MARKETING, DISTRIBUTORS AND CUSTOMER

11.1 Sales Channel

11.1.1 Direct Channels

11.1.2 Indirect Channels

11.2 Mobile Manipulator Grippers Distributors

11.3 Mobile Manipulator Grippers Customer

12 WORLD FORECAST REVIEW FOR MOBILE MANIPULATOR GRIPPERS BY GEOGRAPHIC REGION

- 12.1 Global Mobile Manipulator Grippers Market Size Forecast by Region
 - 12.1.1 Global Mobile Manipulator Grippers Forecast by Region (2027-2032)
 - 12.1.2 Global Mobile Manipulator Grippers Annual Revenue Forecast by Region (2027-2032)
- 12.2 Americas Forecast by Country (2027-2032)
- 12.3 APAC Forecast by Region (2027-2032)
- 12.4 Europe Forecast by Country (2027-2032)
- 12.5 Middle East & Africa Forecast by Country (2027-2032)
- 12.6 Global Mobile Manipulator Grippers Forecast by Type (2027-2032)
- 12.7 Global Mobile Manipulator Grippers Forecast by Application (2027-2032)

13 KEY PLAYERS ANALYSIS

- 13.1 SCHUNK SE & Co. KG
 - 13.1.1 SCHUNK SE & Co. KG Company Information
 - 13.1.2 SCHUNK SE & Co. KG Mobile Manipulator Grippers Product Portfolios and Specifications
 - 13.1.3 SCHUNK SE & Co. KG Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)
 - 13.1.4 SCHUNK SE & Co. KG Main Business Overview
 - 13.1.5 SCHUNK SE & Co. KG Latest Developments
- 13.2 Zimmer Group
 - 13.2.1 Zimmer Group Company Information
 - 13.2.2 Zimmer Group Mobile Manipulator Grippers Product Portfolios and Specifications
 - 13.2.3 Zimmer Group Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)
 - 13.2.4 Zimmer Group Main Business Overview
 - 13.2.5 Zimmer Group Latest Developments
- 13.3 Festo SE & Co. KG
 - 13.3.1 Festo SE & Co. KG Company Information
 - 13.3.2 Festo SE & Co. KG Mobile Manipulator Grippers Product Portfolios and Specifications
 - 13.3.3 Festo SE & Co. KG Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)

- 13.3.4 Festo SE & Co. KG Main Business Overview
- 13.3.5 Festo SE & Co. KG Latest Developments
- 13.4 J. Schmalz GmbH
 - 13.4.1 J. Schmalz GmbH Company Information
 - 13.4.2 J. Schmalz GmbH Mobile Manipulator Grippers Product Portfolios and Specifications
 - 13.4.3 J. Schmalz GmbH Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)
 - 13.4.4 J. Schmalz GmbH Main Business Overview
 - 13.4.5 J. Schmalz GmbH Latest Developments
- 13.5 Stabilus SE (DESTACO)
 - 13.5.1 Stabilus SE (DESTACO) Company Information
 - 13.5.2 Stabilus SE (DESTACO) Mobile Manipulator Grippers Product Portfolios and Specifications
 - 13.5.3 Stabilus SE (DESTACO) Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)
 - 13.5.4 Stabilus SE (DESTACO) Main Business Overview
 - 13.5.5 Stabilus SE (DESTACO) Latest Developments
- 13.6 OnRobot A/S
 - 13.6.1 OnRobot A/S Company Information
 - 13.6.2 OnRobot A/S Mobile Manipulator Grippers Product Portfolios and Specifications
 - 13.6.3 OnRobot A/S Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)
 - 13.6.4 OnRobot A/S Main Business Overview
 - 13.6.5 OnRobot A/S Latest Developments
- 13.7 Piab Group
 - 13.7.1 Piab Group Company Information
 - 13.7.2 Piab Group Mobile Manipulator Grippers Product Portfolios and Specifications
 - 13.7.3 Piab Group Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)
 - 13.7.4 Piab Group Main Business Overview
 - 13.7.5 Piab Group Latest Developments
- 13.8 Robotiq Inc.
 - 13.8.1 Robotiq Inc. Company Information
 - 13.8.2 Robotiq Inc. Mobile Manipulator Grippers Product Portfolios and Specifications
 - 13.8.3 Robotiq Inc. Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)
 - 13.8.4 Robotiq Inc. Main Business Overview
 - 13.8.5 Robotiq Inc. Latest Developments

13.9 PHD, Inc.

13.9.1 PHD, Inc. Company Information

13.9.2 PHD, Inc. Mobile Manipulator Grippers Product Portfolios and Specifications

13.9.3 PHD, Inc. Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)

13.9.4 PHD, Inc. Main Business Overview

13.9.5 PHD, Inc. Latest Developments

13.10 New Scale Robotics, Inc.

13.10.1 New Scale Robotics, Inc. Company Information

13.10.2 New Scale Robotics, Inc. Mobile Manipulator Grippers Product Portfolios and Specifications

13.10.3 New Scale Robotics, Inc. Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)

13.10.4 New Scale Robotics, Inc. Main Business Overview

13.10.5 New Scale Robotics, Inc. Latest Developments

13.11 SMC Corporation

13.11.1 SMC Corporation Company Information

13.11.2 SMC Corporation Mobile Manipulator Grippers Product Portfolios and Specifications

13.11.3 SMC Corporation Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)

13.11.4 SMC Corporation Main Business Overview

13.11.5 SMC Corporation Latest Developments

13.12 IAI Corporation

13.12.1 IAI Corporation Company Information

13.12.2 IAI Corporation Mobile Manipulator Grippers Product Portfolios and Specifications

13.12.3 IAI Corporation Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)

13.12.4 IAI Corporation Main Business Overview

13.12.5 IAI Corporation Latest Developments

13.13 CKD Corporation

13.13.1 CKD Corporation Company Information

13.13.2 CKD Corporation Mobile Manipulator Grippers Product Portfolios and Specifications

13.13.3 CKD Corporation Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)

13.13.4 CKD Corporation Main Business Overview

13.13.5 CKD Corporation Latest Developments

13.14 Oriental Motor Co., Ltd.

13.14.1 Oriental Motor Co., Ltd. Company Information

13.14.2 Oriental Motor Co., Ltd. Mobile Manipulator Grippers Product Portfolios and Specifications

13.14.3 Oriental Motor Co., Ltd. Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)

13.14.4 Oriental Motor Co., Ltd. Main Business Overview

13.14.5 Oriental Motor Co., Ltd. Latest Developments

13.15 Koganei Corporation

13.15.1 Koganei Corporation Company Information

13.15.2 Koganei Corporation Mobile Manipulator Grippers Product Portfolios and Specifications

13.15.3 Koganei Corporation Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)

13.15.4 Koganei Corporation Main Business Overview

13.15.5 Koganei Corporation Latest Developments

13.16 DH-Robotics Technology Co., Ltd.

13.16.1 DH-Robotics Technology Co., Ltd. Company Information

13.16.2 DH-Robotics Technology Co., Ltd. Mobile Manipulator Grippers Product Portfolios and Specifications

13.16.3 DH-Robotics Technology Co., Ltd. Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)

13.16.4 DH-Robotics Technology Co., Ltd. Main Business Overview

13.16.5 DH-Robotics Technology Co., Ltd. Latest Developments

13.17 Hitbot Technology (Shenzhen) Co., Ltd.

13.17.1 Hitbot Technology (Shenzhen) Co., Ltd. Company Information

13.17.2 Hitbot Technology (Shenzhen) Co., Ltd. Mobile Manipulator Grippers Product Portfolios and Specifications

13.17.3 Hitbot Technology (Shenzhen) Co., Ltd. Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)

13.17.4 Hitbot Technology (Shenzhen) Co., Ltd. Main Business Overview

13.17.5 Hitbot Technology (Shenzhen) Co., Ltd. Latest Developments

13.18 Beijing Inspire Robots Technology Co., Ltd.

13.18.1 Beijing Inspire Robots Technology Co., Ltd. Company Information

13.18.2 Beijing Inspire Robots Technology Co., Ltd. Mobile Manipulator Grippers Product Portfolios and Specifications

13.18.3 Beijing Inspire Robots Technology Co., Ltd. Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)

13.18.4 Beijing Inspire Robots Technology Co., Ltd. Main Business Overview

- 13.18.5 Beijing Inspire Robots Technology Co., Ltd. Latest Developments
- 13.19 Linkerbot Beijing Technology Co., Ltd.
 - 13.19.1 Linkerbot Beijing Technology Co., Ltd. Company Information
 - 13.19.2 Linkerbot Beijing Technology Co., Ltd. Mobile Manipulator Grippers Product Portfolios and Specifications
 - 13.19.3 Linkerbot Beijing Technology Co., Ltd. Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)
 - 13.19.4 Linkerbot Beijing Technology Co., Ltd. Main Business Overview
 - 13.19.5 Linkerbot Beijing Technology Co., Ltd. Latest Developments
- 13.20 Soft Robot Tech Co., Ltd. (SRT)
 - 13.20.1 Soft Robot Tech Co., Ltd. (SRT) Company Information
 - 13.20.2 Soft Robot Tech Co., Ltd. (SRT) Mobile Manipulator Grippers Product Portfolios and Specifications
 - 13.20.3 Soft Robot Tech Co., Ltd. (SRT) Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)
 - 13.20.4 Soft Robot Tech Co., Ltd. (SRT) Main Business Overview
 - 13.20.5 Soft Robot Tech Co., Ltd. (SRT) Latest Developments
- 13.21 Suzhou Rochu Robotics Co., Ltd.
 - 13.21.1 Suzhou Rochu Robotics Co., Ltd. Company Information
 - 13.21.2 Suzhou Rochu Robotics Co., Ltd. Mobile Manipulator Grippers Product Portfolios and Specifications
 - 13.21.3 Suzhou Rochu Robotics Co., Ltd. Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)
 - 13.21.4 Suzhou Rochu Robotics Co., Ltd. Main Business Overview
 - 13.21.5 Suzhou Rochu Robotics Co., Ltd. Latest Developments
- 13.22 HIWIN Technologies Corp.
 - 13.22.1 HIWIN Technologies Corp. Company Information
 - 13.22.2 HIWIN Technologies Corp. Mobile Manipulator Grippers Product Portfolios and Specifications
 - 13.22.3 HIWIN Technologies Corp. Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)
 - 13.22.4 HIWIN Technologies Corp. Main Business Overview
 - 13.22.5 HIWIN Technologies Corp. Latest Developments
- 13.23 TESOLLO INC.
 - 13.23.1 TESOLLO INC. Company Information
 - 13.23.2 TESOLLO INC. Mobile Manipulator Grippers Product Portfolios and Specifications
 - 13.23.3 TESOLLO INC. Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)

13.23.4 TESOLLO INC. Main Business Overview

13.23.5 TESOLLO INC. Latest Developments

13.24 ROBOTIS Co., Ltd.

13.24.1 ROBOTIS Co., Ltd. Company Information

13.24.2 ROBOTIS Co., Ltd. Mobile Manipulator Grippers Product Portfolios and Specifications

13.24.3 ROBOTIS Co., Ltd. Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)

13.24.4 ROBOTIS Co., Ltd. Main Business Overview

13.24.5 ROBOTIS Co., Ltd. Latest Developments

13.25 Janatics India Private Limited

13.25.1 Janatics India Private Limited Company Information

13.25.2 Janatics India Private Limited Mobile Manipulator Grippers Product Portfolios and Specifications

13.25.3 Janatics India Private Limited Mobile Manipulator Grippers Sales, Revenue, Price and Gross Margin (2021-2026)

13.25.4 Janatics India Private Limited Main Business Overview

13.25.5 Janatics India Private Limited Latest Developments

14 RESEARCH FINDINGS AND CONCLUSION

List Of Tables

LIST OF TABLES

Table 1. Mobile Manipulator Grippers Annual Sales CAGR by Geographic Region (2021, 2025 & 2032) & (\$ millions)

Table 2. Mobile Manipulator Grippers Annual Sales CAGR by Country/Region (2021, 2025 & 2032) & (\$ millions)

Table 3. Major Players of Electric Finger Grippers

Table 4. Major Players of Vacuum Grippers

Table 5. Major Players of Adaptive and Soft Grippers

Table 6. Major Players of Dexterous Hands

Table 7. Major Players of Others

Table 8. Global Mobile Manipulator Grippers Sales by Type (2021-2026) & (Sets)

Table 9. Global Mobile Manipulator Grippers Sales Market Share by Type (2021-2026)

Table 10. Global Mobile Manipulator Grippers Revenue by Type (2021-2026) & (\$ million)

Table 11. Global Mobile Manipulator Grippers Revenue Market Share by Type (2021-2026)

Table 12. Global Mobile Manipulator Grippers Sale Price by Type (2021-2026) & (US\$/Set)

Table 13. Major Players of Electric Servo Actuation

Table 14. Major Players of Pneumatic Actuation

Table 15. Major Players of Vacuum Actuation

Table 16. Major Players of Magnetic and Passive Actuation

Table 17. Global Mobile Manipulator Grippers Sales by Actuation Method (2021-2026) & (Sets)

Table 18. Global Mobile Manipulator Grippers Sales Market Share by Actuation Method (2021-2026)

Table 19. Global Mobile Manipulator Grippers Revenue by Actuation Method (2021-2026) & (\$ million)

Table 20. Global Mobile Manipulator Grippers Revenue Market Share by Actuation Method (2021-2026)

Table 21. Global Mobile Manipulator Grippers Sale Price by Actuation Method (2021-2026) & (US\$/Set)

Table 22. Major Players of Below 1 kg

Table 23. Major Players of 1 kg to 5 kg

Table 24. Major Players of 5 kg to 10 kg

Table 25. Major Players of Above 10 kg

Table 26. Global Mobile Manipulator Grippers Sales by Payload Class (2021-2026) & (Sets)

Table 27. Global Mobile Manipulator Grippers Sales Market Share by Payload Class (2021-2026)

Table 28. Global Mobile Manipulator Grippers Revenue by Payload Class (2021-2026) & (\$ million)

Table 29. Global Mobile Manipulator Grippers Revenue Market Share by Payload Class (2021-2026)

Table 30. Global Mobile Manipulator Grippers Sale Price by Payload Class (2021-2026) & (US\$/Set)

Table 31. Major Players of Parallel Jaw Structure

Table 32. Major Players of Two Finger Adaptive Structure

Table 33. Major Players of Three Finger and Multi Finger Structure

Table 34. Major Players of Suction Cup and Foam Pad Structure

Table 35. Global Mobile Manipulator Grippers Sales by Gripper Structure (2021-2026) & (Sets)

Table 36. Global Mobile Manipulator Grippers Sales Market Share by Gripper Structure (2021-2026)

Table 37. Global Mobile Manipulator Grippers Revenue by Gripper Structure (2021-2026) & (\$ million)

Table 38. Global Mobile Manipulator Grippers Revenue Market Share by Gripper Structure (2021-2026)

Table 39. Global Mobile Manipulator Grippers Sale Price by Gripper Structure (2021-2026) & (US\$/Set)

Table 40. Global Mobile Manipulator Grippers Sale by Application (2021-2026) & (Sets)

Table 41. Global Mobile Manipulator Grippers Sale Market Share by Application (2021-2026)

Table 42. Global Mobile Manipulator Grippers Revenue by Application (2021-2026) & (\$ million)

Table 43. Global Mobile Manipulator Grippers Revenue Market Share by Application (2021-2026)

Table 44. Global Mobile Manipulator Grippers Sale Price by Application (2021-2026) & (US\$/Set)

Table 45. Global Mobile Manipulator Grippers Sales by Company (2021-2026) & (Sets)

Table 46. Global Mobile Manipulator Grippers Sales Market Share by Company (2021-2026)

Table 47. Global Mobile Manipulator Grippers Revenue by Company (2021-2026) & (\$ millions)

Table 48. Global Mobile Manipulator Grippers Revenue Market Share by Company

(2021-2026)

Table 49. Global Mobile Manipulator Grippers Sale Price by Company (2021-2026) & (US\$/Set)

Table 50. Key Manufacturers Mobile Manipulator Grippers Producing Area Distribution and Sales Area

Table 51. Players Mobile Manipulator Grippers Products Offered

Table 52. Mobile Manipulator Grippers Concentration Ratio (CR3, CR5 and CR10) & (2024-2026)

Table 53. New Products and Potential Entrants

Table 54. Market M&A Activity & Strategy

Table 55. Global Mobile Manipulator Grippers Sales by Geographic Region (2021-2026) & (Sets)

Table 56. Global Mobile Manipulator Grippers Sales Market Share Geographic Region (2021-2026)

Table 57. Global Mobile Manipulator Grippers Revenue by Geographic Region (2021-2026) & (\$ millions)

Table 58. Global Mobile Manipulator Grippers Revenue Market Share by Geographic Region (2021-2026)

Table 59. Global Mobile Manipulator Grippers Sales by Country/Region (2021-2026) & (Sets)

Table 60. Global Mobile Manipulator Grippers Sales Market Share by Country/Region (2021-2026)

Table 61. Global Mobile Manipulator Grippers Revenue by Country/Region (2021-2026) & (\$ millions)

Table 62. Global Mobile Manipulator Grippers Revenue Market Share by Country/Region (2021-2026)

Table 63. Americas Mobile Manipulator Grippers Sales by Country (2021-2026) & (Sets)

Table 64. Americas Mobile Manipulator Grippers Sales Market Share by Country (2021-2026)

Table 65. Americas Mobile Manipulator Grippers Revenue by Country (2021-2026) & (\$ millions)

Table 66. Americas Mobile Manipulator Grippers Sales by Type (2021-2026) & (Sets)

Table 67. Americas Mobile Manipulator Grippers Sales by Application (2021-2026) & (Sets)

Table 68. APAC Mobile Manipulator Grippers Sales by Region (2021-2026) & (Sets)

Table 69. APAC Mobile Manipulator Grippers Sales Market Share by Region (2021-2026)

Table 70. APAC Mobile Manipulator Grippers Revenue by Region (2021-2026) & (\$ millions)

Table 71. APAC Mobile Manipulator Grippers Sales by Type (2021-2026) & (Sets)
Table 72. APAC Mobile Manipulator Grippers Sales by Application (2021-2026) & (Sets)
Table 73. Europe Mobile Manipulator Grippers Sales by Country (2021-2026) & (Sets)
Table 74. Europe Mobile Manipulator Grippers Revenue by Country (2021-2026) & (\$ millions)
Table 75. Europe Mobile Manipulator Grippers Sales by Type (2021-2026) & (Sets)
Table 76. Europe Mobile Manipulator Grippers Sales by Application (2021-2026) & (Sets)
Table 77. Middle East & Africa Mobile Manipulator Grippers Sales by Country (2021-2026) & (Sets)
Table 78. Middle East & Africa Mobile Manipulator Grippers Revenue Market Share by Country (2021-2026)
Table 79. Middle East & Africa Mobile Manipulator Grippers Sales by Type (2021-2026) & (Sets)
Table 80. Middle East & Africa Mobile Manipulator Grippers Sales by Application (2021-2026) & (Sets)
Table 81. Key Market Drivers & Growth Opportunities of Mobile Manipulator Grippers
Table 82. Key Market Challenges & Risks of Mobile Manipulator Grippers
Table 83. Key Industry Trends of Mobile Manipulator Grippers
Table 84. Mobile Manipulator Grippers Raw Material
Table 85. Key Suppliers of Raw Materials
Table 86. Mobile Manipulator Grippers Distributors List
Table 87. Mobile Manipulator Grippers Customer List
Table 88. Global Mobile Manipulator Grippers Sales Forecast by Region (2027-2032) & (Sets)
Table 89. Global Mobile Manipulator Grippers Revenue Forecast by Region (2027-2032) & (\$ millions)
Table 90. Americas Mobile Manipulator Grippers Sales Forecast by Country (2027-2032) & (Sets)
Table 91. Americas Mobile Manipulator Grippers Annual Revenue Forecast by Country (2027-2032) & (\$ millions)
Table 92. APAC Mobile Manipulator Grippers Sales Forecast by Region (2027-2032) & (Sets)
Table 93. APAC Mobile Manipulator Grippers Annual Revenue Forecast by Region (2027-2032) & (\$ millions)
Table 94. Europe Mobile Manipulator Grippers Sales Forecast by Country (2027-2032) & (Sets)
Table 95. Europe Mobile Manipulator Grippers Revenue Forecast by Country (2027-2032) & (\$ millions)

Table 96. Middle East & Africa Mobile Manipulator Grippers Sales Forecast by Country (2027-2032) & (Sets)

Table 97. Middle East & Africa Mobile Manipulator Grippers Revenue Forecast by Country (2027-2032) & (\$ millions)

Table 98. Global Mobile Manipulator Grippers Sales Forecast by Type (2027-2032) & (Sets)

Table 99. Global Mobile Manipulator Grippers Revenue Forecast by Type (2027-2032) & (\$ millions)

Table 100. Global Mobile Manipulator Grippers Sales Forecast by Application (2027-2032) & (Sets)

Table 101. Global Mobile Manipulator Grippers Revenue Forecast by Application (2027-2032) & (\$ millions)

Table 102. SCHUNK SE & Co. KG Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 103. SCHUNK SE & Co. KG Mobile Manipulator Grippers Product Portfolios and Specifications

Table 104. SCHUNK SE & Co. KG Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 105. SCHUNK SE & Co. KG Main Business

Table 106. SCHUNK SE & Co. KG Latest Developments

Table 107. Zimmer Group Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 108. Zimmer Group Mobile Manipulator Grippers Product Portfolios and Specifications

Table 109. Zimmer Group Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 110. Zimmer Group Main Business

Table 111. Zimmer Group Latest Developments

Table 112. Festo SE & Co. KG Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 113. Festo SE & Co. KG Mobile Manipulator Grippers Product Portfolios and Specifications

Table 114. Festo SE & Co. KG Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 115. Festo SE & Co. KG Main Business

Table 116. Festo SE & Co. KG Latest Developments

Table 117. J. Schmalz GmbH Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 118. J. Schmalz GmbH Mobile Manipulator Grippers Product Portfolios and

Specifications

Table 119. J. Schmalz GmbH Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 120. J. Schmalz GmbH Main Business

Table 121. J. Schmalz GmbH Latest Developments

Table 122. Stabilus SE (DESTACO) Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 123. Stabilus SE (DESTACO) Mobile Manipulator Grippers Product Portfolios and Specifications

Table 124. Stabilus SE (DESTACO) Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 125. Stabilus SE (DESTACO) Main Business

Table 126. Stabilus SE (DESTACO) Latest Developments

Table 127. OnRobot A/S Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 128. OnRobot A/S Mobile Manipulator Grippers Product Portfolios and Specifications

Table 129. OnRobot A/S Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 130. OnRobot A/S Main Business

Table 131. OnRobot A/S Latest Developments

Table 132. Piab Group Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 133. Piab Group Mobile Manipulator Grippers Product Portfolios and Specifications

Table 134. Piab Group Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 135. Piab Group Main Business

Table 136. Piab Group Latest Developments

Table 137. Robotiq Inc. Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 138. Robotiq Inc. Mobile Manipulator Grippers Product Portfolios and Specifications

Table 139. Robotiq Inc. Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 140. Robotiq Inc. Main Business

Table 141. Robotiq Inc. Latest Developments

Table 142. PHD, Inc. Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 143. PHD, Inc. Mobile Manipulator Grippers Product Portfolios and Specifications

Table 144. PHD, Inc. Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 145. PHD, Inc. Main Business

Table 146. PHD, Inc. Latest Developments

Table 147. New Scale Robotics, Inc. Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 148. New Scale Robotics, Inc. Mobile Manipulator Grippers Product Portfolios and Specifications

Table 149. New Scale Robotics, Inc. Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 150. New Scale Robotics, Inc. Main Business

Table 151. New Scale Robotics, Inc. Latest Developments

Table 152. SMC Corporation Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 153. SMC Corporation Mobile Manipulator Grippers Product Portfolios and Specifications

Table 154. SMC Corporation Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 155. SMC Corporation Main Business

Table 156. SMC Corporation Latest Developments

Table 157. IAI Corporation Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 158. IAI Corporation Mobile Manipulator Grippers Product Portfolios and Specifications

Table 159. IAI Corporation Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 160. IAI Corporation Main Business

Table 161. IAI Corporation Latest Developments

Table 162. CKD Corporation Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 163. CKD Corporation Mobile Manipulator Grippers Product Portfolios and Specifications

Table 164. CKD Corporation Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 165. CKD Corporation Main Business

Table 166. CKD Corporation Latest Developments

Table 167. Oriental Motor Co., Ltd. Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 168. Oriental Motor Co., Ltd. Mobile Manipulator Grippers Product Portfolios and Specifications

Table 169. Oriental Motor Co., Ltd. Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 170. Oriental Motor Co., Ltd. Main Business

Table 171. Oriental Motor Co., Ltd. Latest Developments

Table 172. Koganei Corporation Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 173. Koganei Corporation Mobile Manipulator Grippers Product Portfolios and Specifications

Table 174. Koganei Corporation Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 175. Koganei Corporation Main Business

Table 176. Koganei Corporation Latest Developments

Table 177. DH-Robotics Technology Co., Ltd. Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 178. DH-Robotics Technology Co., Ltd. Mobile Manipulator Grippers Product Portfolios and Specifications

Table 179. DH-Robotics Technology Co., Ltd. Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 180. DH-Robotics Technology Co., Ltd. Main Business

Table 181. DH-Robotics Technology Co., Ltd. Latest Developments

Table 182. Hitbot Technology (Shenzhen) Co., Ltd. Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 183. Hitbot Technology (Shenzhen) Co., Ltd. Mobile Manipulator Grippers Product Portfolios and Specifications

Table 184. Hitbot Technology (Shenzhen) Co., Ltd. Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 185. Hitbot Technology (Shenzhen) Co., Ltd. Main Business

Table 186. Hitbot Technology (Shenzhen) Co., Ltd. Latest Developments

Table 187. Beijing Inspire Robots Technology Co., Ltd. Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 188. Beijing Inspire Robots Technology Co., Ltd. Mobile Manipulator Grippers Product Portfolios and Specifications

Table 189. Beijing Inspire Robots Technology Co., Ltd. Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 190. Beijing Inspire Robots Technology Co., Ltd. Main Business

Table 191. Beijing Inspire Robots Technology Co., Ltd. Latest Developments

Table 192. Linkerbot Beijing Technology Co., Ltd. Basic Information, Mobile Manipulator

Grippers Manufacturing Base, Sales Area and Its Competitors

Table 193. Linkerbot Beijing Technology Co., Ltd. Mobile Manipulator Grippers Product Portfolios and Specifications

Table 194. Linkerbot Beijing Technology Co., Ltd. Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 195. Linkerbot Beijing Technology Co., Ltd. Main Business

Table 196. Linkerbot Beijing Technology Co., Ltd. Latest Developments

Table 197. Soft Robot Tech Co., Ltd. (SRT) Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 198. Soft Robot Tech Co., Ltd. (SRT) Mobile Manipulator Grippers Product Portfolios and Specifications

Table 199. Soft Robot Tech Co., Ltd. (SRT) Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 200. Soft Robot Tech Co., Ltd. (SRT) Main Business

Table 201. Soft Robot Tech Co., Ltd. (SRT) Latest Developments

Table 202. Suzhou Rochu Robotics Co., Ltd. Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 203. Suzhou Rochu Robotics Co., Ltd. Mobile Manipulator Grippers Product Portfolios and Specifications

Table 204. Suzhou Rochu Robotics Co., Ltd. Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 205. Suzhou Rochu Robotics Co., Ltd. Main Business

Table 206. Suzhou Rochu Robotics Co., Ltd. Latest Developments

Table 207. HIWIN Technologies Corp. Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 208. HIWIN Technologies Corp. Mobile Manipulator Grippers Product Portfolios and Specifications

Table 209. HIWIN Technologies Corp. Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 210. HIWIN Technologies Corp. Main Business

Table 211. HIWIN Technologies Corp. Latest Developments

Table 212. TESOLLO INC. Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 213. TESOLLO INC. Mobile Manipulator Grippers Product Portfolios and Specifications

Table 214. TESOLLO INC. Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 215. TESOLLO INC. Main Business

Table 216. TESOLLO INC. Latest Developments

Table 217. ROBOTIS Co., Ltd. Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 218. ROBOTIS Co., Ltd. Mobile Manipulator Grippers Product Portfolios and Specifications

Table 219. ROBOTIS Co., Ltd. Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 220. ROBOTIS Co., Ltd. Main Business

Table 221. ROBOTIS Co., Ltd. Latest Developments

Table 222. Janatics India Private Limited Basic Information, Mobile Manipulator Grippers Manufacturing Base, Sales Area and Its Competitors

Table 223. Janatics India Private Limited Mobile Manipulator Grippers Product Portfolios and Specifications

Table 224. Janatics India Private Limited Mobile Manipulator Grippers Sales (Sets), Revenue (\$ Million), Price (US\$/Set) and Gross Margin (2021-2026)

Table 225. Janatics India Private Limited Main Business

Table 226. Janatics India Private Limited Latest Developments

List Of Figures

LIST OF FIGURES

- Figure 1. Picture of Mobile Manipulator Grippers
- Figure 2. Mobile Manipulator Grippers Report Years Considered
- Figure 3. Research Objectives
- Figure 4. Research Methodology
- Figure 5. Research Process and Data Source
- Figure 6. Global Mobile Manipulator Grippers Sales Growth Rate 2021-2032 (Sets)
- Figure 7. Global Mobile Manipulator Grippers Revenue Growth Rate 2021-2032 (\$ millions)
- Figure 8. Mobile Manipulator Grippers Sales by Geographic Region (2021, 2025 & 2032) & (\$ millions)
- Figure 9. Mobile Manipulator Grippers Sales Market Share by Country/Region (2025)
- Figure 10. Mobile Manipulator Grippers Sales Market Share by Country/Region (2021, 2025 & 2032)
- Figure 11. Product Picture of Electric Finger Grippers
- Figure 12. Product Picture of Vacuum Grippers
- Figure 13. Product Picture of Adaptive and Soft Grippers
- Figure 14. Product Picture of Dexterous Hands
- Figure 15. Product Picture of Others
- Figure 16. Global Mobile Manipulator Grippers Sales Market Share by Type in 2026
- Figure 17. Global Mobile Manipulator Grippers Revenue Market Share by Type (2021-2026)
- Figure 18. Product Picture of Electric Servo Actuation
- Figure 19. Product Picture of Pneumatic Actuation
- Figure 20. Product Picture of Vacuum Actuation
- Figure 21. Product Picture of Magnetic and Passive Actuation
- Figure 22. Global Mobile Manipulator Grippers Sales Market Share by Actuation Method in 2026
- Figure 23. Global Mobile Manipulator Grippers Revenue Market Share by Actuation Method (2021-2026)
- Figure 24. Product Picture of Below 1 kg
- Figure 25. Product Picture of 1 kg to 5 kg
- Figure 26. Product Picture of 5 kg to 10 kg
- Figure 27. Product Picture of Above 10 kg
- Figure 28. Global Mobile Manipulator Grippers Sales Market Share by Payload Class in 2026

Figure 29. Global Mobile Manipulator Grippers Revenue Market Share by Payload Class (2021-2026)

Figure 30. Product Picture of Parallel Jaw Structure

Figure 31. Product Picture of Two Finger Adaptive Structure

Figure 32. Product Picture of Three Finger and Multi Finger Structure

Figure 33. Product Picture of Suction Cup and Foam Pad Structure

Figure 34. Global Mobile Manipulator Grippers Sales Market Share by Gripper Structure in 2026

Figure 35. Global Mobile Manipulator Grippers Revenue Market Share by Gripper Structure (2021-2026)

Figure 36. Mobile Manipulator Grippers Consumed in Logistics and E Commerce

Figure 37. Global Mobile Manipulator Grippers Market: Logistics and E Commerce (2021-2026) & (Sets)

Figure 38. Mobile Manipulator Grippers Consumed in Industrial Manufacturing

Figure 39. Global Mobile Manipulator Grippers Market: Industrial Manufacturing (2021-2026) & (Sets)

Figure 40. Mobile Manipulator Grippers Consumed in Research Education and Robot Training

Figure 41. Global Mobile Manipulator Grippers Market: Research Education and Robot Training (2021-2026) & (Sets)

Figure 42. Mobile Manipulator Grippers Consumed in Healthcare Commercial Service

Figure 43. Global Mobile Manipulator Grippers Market: Healthcare Commercial Service (2021-2026) & (Sets)

Figure 44. Mobile Manipulator Grippers Consumed in Others

Figure 45. Global Mobile Manipulator Grippers Market: Others (2021-2026) & (Sets)

Figure 46. Global Mobile Manipulator Grippers Sale Market Share by Application (2025)

Figure 47. Global Mobile Manipulator Grippers Revenue Market Share by Application in 2025

Figure 48. Mobile Manipulator Grippers Sales by Company in 2025 (Sets)

Figure 49. Global Mobile Manipulator Grippers Sales Market Share by Company in 2025

Figure 50. Mobile Manipulator Grippers Revenue by Company in 2025 (\$ millions)

Figure 51. Global Mobile Manipulator Grippers Revenue Market Share by Company in 2025

Figure 52. Global Mobile Manipulator Grippers Sales Market Share by Geographic Region (2021-2026)

Figure 53. Global Mobile Manipulator Grippers Revenue Market Share by Geographic Region in 2025

Figure 54. Americas Mobile Manipulator Grippers Sales 2021-2026 (Sets)

Figure 55. Americas Mobile Manipulator Grippers Revenue 2021-2026 (\$ millions)

Figure 56. APAC Mobile Manipulator Grippers Sales 2021-2026 (Sets)

Figure 57. APAC Mobile Manipulator Grippers Revenue 2021-2026 (\$ millions)

Figure 58. Europe Mobile Manipulator Grippers Sales 2021-2026 (Sets)

Figure 59. Europe Mobile Manipulator Grippers Revenue 2021-2026 (\$ millions)

Figure 60. Middle East & Africa Mobile Manipulator Grippers Sales 2021-2026 (Sets)

Figure 61. Middle East & Africa Mobile Manipulator Grippers Revenue 2021-2026 (\$ millions)

Figure 62. Americas Mobile Manipulator Grippers Sales Market Share by Country in 2025

Figure 63. Americas Mobile Manipulator Grippers Revenue Market Share by Country (2021-2026)

Figure 64. Americas Mobile Manipulator Grippers Sales Market Share by Type (2021-2026)

Figure 65. Americas Mobile Manipulator Grippers Sales Market Share by Application (2021-2026)

Figure 66. United States Mobile Manipulator Grippers Revenue Growth 2021-2026 (\$ millions)

Figure 67. Canada Mobile Manipulator Grippers Revenue Growth 2021-2026 (\$ millions)

Figure 68. Mexico Mobile Manipulator Grippers Revenue Growth 2021-2026 (\$ millions)

Figure 69. Brazil Mobile Manipulator Grippers Revenue Growth 2021-2026 (\$ millions)

Figure 70. APAC Mobile Manipulator Grippers Sales Market Share by Region in 2025

Figure 71. APAC Mobile Manipulator Grippers Revenue Market Share by Region (2021-2026)

Figure 72. APAC Mobile Manipulator Grippers Sales Market Share by Type (2021-2026)

Figure 73. APAC Mobile Manipulator Grippers Sales Market Share by Application (2021-2026)

Figure 74. China Mobile Manipulator Grippers Revenue Growth 2021-2026 (\$ millions)

Figure 75. Japan Mobile Manipulator Grippers Revenue Growth 2021-2026 (\$ millions)

Figure 76. South Korea Mobile Manipulator Grippers Revenue Growth 2021-2026 (\$ millions)

Figure 77. Southeast Asia Mobile Manipulator Grippers Revenue Growth 2021-2026 (\$ millions)

Figure 78. India Mobile Manipulator Grippers Revenue Growth 2021-2026 (\$ millions)

Figure 79. Australia Mobile Manipulator Grippers Revenue Growth 2021-2026 (\$ millions)

Figure 80. China Taiwan Mobile Manipulator Grippers Revenue Growth 2021-2026 (\$ millions)

Figure 81. Europe Mobile Manipulator Grippers Sales Market Share by Country in 2025

Figure 82. Europe Mobile Manipulator Grippers Revenue Market Share by Country (2021-2026)

Figure 83. Europe Mobile Manipulator Grippers Sales Market Share by Type (2021-2026)

Figure 84. Europe Mobile Manipulator Grippers Sales Market Share by Application (2021-2026)

Figure 85. Germany Mobile Manipulator Grippers Revenue Growth 2021-2026 (\$ millions)

Figure 86. France Mobile Manipulator Grippers Revenue Growth 2021-2026 (\$ millions)

Figure 87. UK Mobile Manipulator Grippers Revenue Growth 2021-2026 (\$ millions)

Figure 88. Italy Mobile Manipulator Grippers Revenue Growth 2021-2026 (\$ millions)

Figure 89. Russia Mobile Manipulator Grippers Revenue Growth 2021-2026 (\$ millions)

Figure 90. Middle East & Africa Mobile Manipulator Grippers Sales Market Share by Country (2021-2026)

Figure 91. Middle East & Africa Mobile Manipulator Grippers Sales Market Share by Type (2021-2026)

Figure 92. Middle East & Africa Mobile Manipulator Grippers Sales Market Share by Application (2021-2026)

Figure 93. Egypt Mobile Manipulator Grippers Revenue Growth 2021-2026 (\$ millions)

Figure 94. South Africa Mobile Manipulator Grippers Revenue Growth 2021-2026 (\$ millions)

Figure 95. Israel Mobile Manipulator Grippers Revenue Growth 2021-2026 (\$ millions)

Figure 96. Turkey Mobile Manipulator Grippers Revenue Growth 2021-2026 (\$ millions)

Figure 97. GCC Countries Mobile Manipulator Grippers Revenue Growth 2021-2026 (\$ millions)

Figure 98. Manufacturing Cost Structure Analysis of Mobile Manipulator Grippers in 2026

Figure 99. Manufacturing Process Analysis of Mobile Manipulator Grippers

Figure 100. Industry Chain Structure of Mobile Manipulator Grippers

Figure 101. Channels of Distribution

Figure 102. Global Mobile Manipulator Grippers Sales Market Forecast by Region (2027-2032)

Figure 103. Global Mobile Manipulator Grippers Revenue Market Share Forecast by Region (2027-2032)

Figure 104. Global Mobile Manipulator Grippers Sales Market Share Forecast by Type (2027-2032)

Figure 105. Global Mobile Manipulator Grippers Revenue Market Share Forecast by Type (2027-2032)

Figure 106. Global Mobile Manipulator Grippers Sales Market Share Forecast by Application (2027-2032)

Figure 107. Global Mobile Manipulator Grippers Revenue Market Share Forecast by Application (2027-2032)

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