

Global MLCC for Humanoid Robot Market Growth 2026-2032

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Abstracts

The global MLCC for Humanoid Robot market size is predicted to grow from US\$ 1.47 million in 2025 to US\$ 111 million in 2032; it is expected to grow at a CAGR of 77.8% from 2026 to 2032.

In 2025, global MLCC for Humanoid Robot production reached approximately 50 million units with an average price of USD \$0.03 per unit. In market-research terms, this product is an application-defined pocket within high-reliability multilayer ceramic chip capacitors rather than a new capacitor chemistry. Demand is created by dense humanoid robot electronics where compute boards, servo-drive boards, power conversion circuits, sensors and tactile modules need compact decoupling, filtering and transient suppression components that can tolerate board flex, vibration, thermal cycling and current spikes. Typical forms include soft-termination MLCCs, automotive-grade X7R or X8R parts, low-ESR high-capacitance MLCCs and small-size C0G signal capacitors. The product sits in the passive-component layer between ceramic powders and robot electronic assemblies. It is narrower than the general MLCC market and should not include distributors, robot OEMs, servo-drive manufacturers or non-MLCC capacitors. Its research value comes from linking humanoid robot commercialization with a measurable pull-through effect on premium MLCC mixes.

MLCC for Humanoid Robot should be treated as a narrow demand pocket inside high-reliability MLCCs. The relevant purchasing logic is not that robot makers buy a unique capacitor class, but that humanoid robot electronics shift part of their capacitor mix toward soft-termination, automotive-grade, low-ESR, high-capacitance and compact-package MLCCs. This makes the product suitable for independent research only when the boundary is tied to humanoid robot boards and modules, not to the full MLCC market. The practical market unit is the individual chip capacitor, while demand is driven

by board count, joint count, sensor density and the level of integration in AI compute modules. 2) Industry development is still early but structurally favorable. Public robotics information indicates that humanoid robots are moving from demonstrations and research procurement toward pilot production, especially in China, while service robots and industrial automation continue to create broader acceptance of robots in commercial settings. For MLCC suppliers, this does not create a new supply chain from scratch; it increases exposure to premium reliability series already developed for automotive electronics, AI servers, industrial controls and power electronics. As robot volumes rise, the capacitor value per robot may decline because of scale purchasing and design standardization, but piece consumption should expand with higher electronic density. 3) The present supply side is led by established Japanese, Korean, Taiwanese, Chinese and U.S. MLCC manufacturers. Murata, TDK, Samsung Electro-Mechanics, Taiyo Yuden, Kyocera AVX, Yageo, Walsin, Vishay, Knowles, Fenghua and Three-Circle are relevant because they already have source manufacturing capability and reliability-oriented MLCC families. Smaller qualified producers can participate in selected industrial and control-board sockets, but humanoid robot programs are likely to favor suppliers with stable quality systems, long-term availability, AEC-Q200 experience, and the ability to support both small-package decoupling parts and larger power-board capacitors. 4) Growth will be shaped by two opposing forces. Robot shipments, actuator counts and edge-AI computing requirements support rapid volume growth from a small base. At the same time, MLCCs are highly standardized, price competition is intense, and many robot designs will use catalog automotive or industrial parts rather than customized capacitors. The strongest pull-through should appear in soft-termination anti-crack parts for mechanically stressed boards, high-temperature or high-voltage MLCCs for power stages, and low-ESR capacitors around processors and motor controllers. 5) The product's market position is best described as a premium mix upgrade within a mature passive-component industry. It is not a bottleneck component in the same way as actuators, reducers, batteries or AI chips, but it is an enabling reliability layer for dense electromechanical systems. Research should therefore focus on BOM intensity, qualification preference, supplier share shift and price erosion rather than only on humanoid robot shipment forecasts.

LP Information, Inc. (LPI) ' newest research report, the "MLCC for Humanoid Robot Industry Forecast" looks at past sales and reviews total world MLCC for Humanoid Robot sales in 2025, providing a comprehensive analysis by region and market sector of projected MLCC for Humanoid Robot sales for 2026 through 2032. With MLCC for Humanoid Robot sales broken down by region, market sector and sub-sector, this report provides a detailed analysis in US\$ millions of the world MLCC for Humanoid Robot industry.

This Insight Report provides a comprehensive analysis of the global MLCC for Humanoid Robot landscape and highlights key trends related to product segmentation, company formation, revenue, and market share, latest development, and M&A activity. This report also analyzes the strategies of leading global companies with a focus on MLCC for Humanoid Robot portfolios and capabilities, market entry strategies, market positions, and geographic footprints, to better understand these firms' unique position in an accelerating global MLCC for Humanoid Robot market.

This Insight Report evaluates the key market trends, drivers, and affecting factors shaping the global outlook for MLCC for Humanoid Robot and breaks down the forecast by Termination, by Application, geography, and market size to highlight emerging pockets of opportunity. With a transparent methodology based on hundreds of bottom-up qualitative and quantitative market inputs, this study forecast offers a highly nuanced view of the current state and future trajectory in the global MLCC for Humanoid Robot.

This report presents a comprehensive overview, market shares, and growth opportunities of MLCC for Humanoid Robot market by product type, application, key manufacturers and key regions and countries.

Segmentation by Termination:

Standard Nickel Barrier Termination

Soft Termination

Metal Frame Termination

Floating Electrode Design

Others

Segmentation by Dielectric and Reliability:

C0G Class I

X7R Automotive Grade

X7S High Temperature Grade

X8R High Temperature Grade

Others

Segmentation by Chip Size:

01005 to 0201

0402

0603

0805 and Larger

Segmentation by Application:

AI Compute Modules

Joint Servo Drive Boards

Vision and Sensor Modules

Tactile and IMU Electronics

Others

This report also splits the market by region:

Americas

United States

Canada

Mexico

Brazil

APAC

China

Japan

Korea

Southeast Asia

India

Australia

Europe

Germany

France

UK

Italy

Russia

Middle East & Africa

Egypt

South Africa

Israel

Turkey

GCC Countries

The below companies that are profiled have been selected based on inputs gathered from primary experts and analysing the company's coverage, product portfolio, its market penetration.

Murata Manufacturing Co., Ltd.

TDK Corporation

Samsung Electro-Mechanics Co., Ltd.

Guangdong Fenghua Advanced Technology Holding Co., Ltd.

Guangdong Viiyong Electronic Technology Co., Ltd.

KYOCERA Corporation (KYOCERA AVX Components Corporation)

YAGEO Corporation (KEMET Electronics Corporation)

TAIYO YUDEN CO., LTD.

Walsin Technology Corporation

Vishay Intertechnology, Inc.

Knowles Corporation (Knowles Precision Devices)

Holy Stone Enterprise Co., Ltd.

Chaozhou Three-Circle (Group) Co., Ltd.

Darfon Electronics Corp.

Key Questions Addressed in this Report

What is the 10-year outlook for the global MLCC for Humanoid Robot market?

What factors are driving MLCC for Humanoid Robot market growth, globally and by region?

Which technologies are poised for the fastest growth by market and region?

How do MLCC for Humanoid Robot market opportunities vary by end market size?

How does MLCC for Humanoid Robot break out by Termination, by Application?

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