

Global Humanoid Tactile Sensor Market Growth 2026-2032

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Abstracts

The global Humanoid Tactile Sensor market size is predicted to grow from US\$ 124 million in 2025 to US\$ 414 million in 2032; it is expected to grow at a CAGR of 18.5% from 2026 to 2032.

Humanoid tactile sensors are sensing devices that simulate the tactile functions of human skin, including piezoresistive, capacitive, piezoelectric, photoelectric, and magnetoelectric Hall effect sensors. From a product form perspective, tactile sensors are mainly divided into three categories: First, array-type tactile sensors, which utilize piezoresistive or capacitive principles to construct a pressure distribution image (i.e., ?tactile pixels?) in the fingertip area, enabling robots to perceive the shape and sliding tendency of objects, achieving flexible grasping; second, six-dimensional force/torque sensors, which measure the overall force and torque at the end effector, and are the core for robots to achieve precision assembly, force-position hybrid control, and bipedal balance; and third, flexible electronic skin, which uses stretchable materials to achieve large-area, fully curved surface coverage, capable of sensing multi-dimensional physical quantities such as pressure, temperature, and humidity.

In 2025, global Humanoid Tactile Sensor sales reached approximately 428 K Units, with an average global market price of around 295 US\$/Unit. Production capacity reached 1,000 K Units, with a gross profit margin of approximately 45%.

Upstream applications extend from traditional pressure-sensitive materials to flexible substrates, conductive voltage-sensitive layers, TFT active matrix, Hall arrays, elastomer packaging, edge computing, and haptic software platforms. JDI achieves high-resolution flexible haptics with LTPS TFT active matrix, Pasini constructs multi-dimensional haptic units using 6D Hall array technology, XELA packages the uSkin

sensor and uAi software into a complete haptic system, and Meta continues to advance research platforms such as DIGIT, ReSkin, and Digit Plexus. Downstream value is more concentrated in dexterous hands, humanoid robots, industrial end effectors, surgical robots, and teleoperation systems. SynTouch has already used BioTac in autonomous robots, teleoperation, surgical robots, and prosthetic hands.

LP Information, Inc. (LPI) ' newest research report, the "Humanoid Tactile Sensor Industry Forecast" looks at past sales and reviews total world Humanoid Tactile Sensor sales in 2025, providing a comprehensive analysis by region and market sector of projected Humanoid Tactile Sensor sales for 2026 through 2032. With Humanoid Tactile Sensor sales broken down by region, market sector and sub-sector, this report provides a detailed analysis in US\$ millions of the world Humanoid Tactile Sensor industry.

This Insight Report provides a comprehensive analysis of the global Humanoid Tactile Sensor landscape and highlights key trends related to product segmentation, company formation, revenue, and market share, latest development, and M&A activity. This report also analyzes the strategies of leading global companies with a focus on Humanoid Tactile Sensor portfolios and capabilities, market entry strategies, market positions, and geographic footprints, to better understand these firms' unique position in an accelerating global Humanoid Tactile Sensor market.

This Insight Report evaluates the key market trends, drivers, and affecting factors shaping the global outlook for Humanoid Tactile Sensor and breaks down the forecast by Type, by Application, geography, and market size to highlight emerging pockets of opportunity. With a transparent methodology based on hundreds of bottom-up qualitative and quantitative market inputs, this study forecast offers a highly nuanced view of the current state and future trajectory in the global Humanoid Tactile Sensor.

This report presents a comprehensive overview, market shares, and growth opportunities of Humanoid Tactile Sensor market by product type, application, key manufacturers and key regions and countries.

Segmentation by Type:

Piezoresistive Type

Capacitive Type

Piezoelectric Type

Photoelectric Type

Inductive Type

Segmentation by Flexible Substrates:

PI

PDMS

PET

Segmentation by Installation Location:

Fingertip Type

Fingerpad and Joint Type

Palm Type

Others

Segmentation by Application:

Dexterous Hands

Humanoid Robots

Industrial Grippers

Surgical Robots

Others

This report also splits the market by region:

Americas

United States

Canada

Mexico

Brazil

APAC

China

Japan

Korea

Southeast Asia

India

Australia

Europe

Germany

France

UK

Italy

Russia

Middle East & Africa

Egypt

South Africa

Israel

Turkey

GCC Countries

The below companies that are profiled have been selected based on inputs gathered from primary experts and analysing the company's coverage, product portfolio, its market penetration.

SynTouch

Tekscan Group

JDI

XELA Robotics

Novasentis

Touchence

Meta (Facebook)

Zhejiang Fulai New Materials

Hubei Huaweike Intelligent

Beijing Tashan Technology

Shenzhen ModuTech

PaXini Tech

Shenzhen Sycsense Technology

Shenzhen Ensuring Technology

Dongguan Moxian Technology

Shenzhen Dobot

Shenzhen LEGACT Technology

Shenzhen New Degree Technology

Shenzhen Daimon Robotics Technology

Suzhou Hangkai Microelectronics Technology

Hanwei Electronics Group

Shanghai Hapttech Robot Technology

Shanghai Xense Robotics Technology

Guangzhou PhlexSense

Shanghai ViTai Technology

Key Questions Addressed in this Report

What is the 10-year outlook for the global Humanoid Tactile Sensor market?

What factors are driving Humanoid Tactile Sensor market growth, globally and by region?

Which technologies are poised for the fastest growth by market and region?

How do Humanoid Tactile Sensor market opportunities vary by end market size?

How does Humanoid Tactile Sensor break out by Type, by Application?

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