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Global High-DOF Dexterous Hand for Robot Market Growth 2026-2032

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Abstracts

The global High-DOF Dexterous Hand for Robot market size is predicted to grow from US$ 427 million in 2025 to US$ 1408 million in 2032; it is expected to grow at a CAGR of 18.9% from 2026 to 2032.

In 2025, global High-DOF Dexterous Hand for Robot production reached approximately 47,400 units?with an average global market price of around US$ 9,200 per unit, and a gross profit margin of approximately 20%-40%. A High-DOF Dexterous Hand for Robot is an anthropomorphic robotic end-effector designed to replicate the complex motion, grasping flexibility, and manipulation capability of the human hand. It normally adopts a four-finger or five-finger structure, provides at least 12 mechanical degrees of freedom, and typically includes eight or more actively driven joints. Advanced fully actuated models may offer 16–22 independent control axes, allowing multiple finger joints to move separately and perform coordinated actions. Compared with conventional industrial grippers or low-DOF underactuated hands, a high-DOF dexterous hand can execute precision grasping, adaptive holding, object rotation, in-hand manipulation, tool operation, button pressing, assembly, and other complex multi-finger tasks. The product generally integrates miniature motors or linear actuators, tendon, linkage, gear, direct-drive, or hybrid transmission mechanisms, together with encoders, motor drivers, embedded controllers, and communication interfaces. Higher-end products may also incorporate tactile arrays, force/torque sensors, fingertip pressure sensing, and closed-loop force-position control. These hands are mainly used in humanoid robots, industrial robots, service robots, teleoperation systems, embodied-intelligence platforms, research equipment, and robots operating in hazardous or unstructured environments.

The industrial chain of High-DOF Dexterous Hands for Robots includes upstream coreless motors, frameless motors, miniature reducers, planetary gearboxes, lead

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screws, tendons, steel cables, bearings, encoders, force sensors, tactile arrays, flexible circuits, control chips, motor drivers, engineering plastics, aluminum alloys, and elastomeric skin materials. Midstream activities include anthropomorphic structural design, finger-joint development, actuator integration, transmission-system assembly, sensor embedding, force-position hybrid control, tactile calibration, kinematic modeling, manipulation-algorithm development, communication-interface integration, durability testing, impact testing, thermal testing, and complete-hand assembly. Downstream applications include humanoid robots, robotic arms, industrial manipulation, service robots, hazardous-environment robots, teleoperation platforms, laboratory automation, embodied-AI research, and robot-learning systems.

United States market for High-DOF Dexterous Hand for Robot is estimated to increase from US$ million in 2025 to US$ million by 2032, at a CAGR of % from 2026 through 2032.

China market for High-DOF Dexterous Hand for Robot is estimated to increase from US$ million in 2025 to US$ million by 2032, at a CAGR of % from 2026 through 2032.

Europe market for High-DOF Dexterous Hand for Robot is estimated to increase from US$ million in 2025 to US$ million by 2032, at a CAGR of % from 2026 through 2032.

Global key High-DOF Dexterous Hand for Robot players cover LinkerBot, AGIBOT, RobotEra, DexRobot, PaXini, etc. In terms of revenue, the global two largest companies occupied for a share nearly % in 2025.

LP Information, Inc. (LPI) ' newest research report, the “High-DOF Dexterous Hand for Robot Industry Forecast” looks at past sales and reviews total world High-DOF Dexterous Hand for Robot sales in 2025, providing a comprehensive analysis by region and market sector of projected High-DOF Dexterous Hand for Robot sales for 2026 through 2032. With High-DOF Dexterous Hand for Robot sales broken down by region, market sector and sub-sector, this report provides a detailed analysis in US$ millions of the world High-DOF Dexterous Hand for Robot industry.

This Insight Report provides a comprehensive analysis of the global High-DOF Dexterous Hand for Robot landscape and highlights key trends related to product segmentation, company formation, revenue, and market share, latest development, and M&A activity. This report also analyzes the strategies of leading global companies with a focus on High-DOF Dexterous Hand for Robot portfolios and capabilities, market entry strategies, market positions, and geographic footprints, to better understand these

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firms' unique position in an accelerating global High-DOF Dexterous Hand for Robot market.

This Insight Report evaluates the key market trends, drivers, and affecting factors shaping the global outlook for High-DOF Dexterous Hand for Robot and breaks down the forecast by Type, by Application, geography, and market size to highlight emerging pockets of opportunity. With a transparent methodology based on hundreds of bottom-up qualitative and quantitative market inputs, this study forecast offers a highly nuanced view of the current state and future trajectory in the global High-DOF Dexterous Hand for Robot.

This report presents a comprehensive overview, market shares, and growth opportunities of High-DOF Dexterous Hand for Robot market by product type, application, key manufacturers and key regions and countries.

Segmentation by Type:

Four-Fingered Dexterous Hand

Five-Fingered Dexterous Hand

Segmentation by DOF:

12–15 DoF

16–20 DoF

Over 20 DoF

Segmentation by Application:

Collaborative Robots

Humanoid Robots

Medical and Surgical Robots

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Others

This report also splits the market by region:

Americas

United States

Canada

Mexico

Brazil

APAC

China

Japan

Korea

Southeast Asia

India

Australia

Europe

Germany

France

UK

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Italy

Russia

Middle East & Africa

Egypt

South Africa

Israel

Turkey

GCC Countries

The below companies that are profiled have been selected based on inputs gathered from primary experts and analysing the company's coverage, product portfolio, its market penetration.

LinkerBot

AGIBOT

RobotEra

DexRobot

PaXini

WUJI TECH

Shadow Robot

Agile Robots

Seed Robotics

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Sharpa Robotics

Tokyo Robotics

Inspire Robots Technology

Zhejiang BrainCo

Jodell Robotics

ZWHAND

Leadshine

Unitree Robotics

ENCOS

PsiBot

Stella-Robot

AIDIN Robotics

Key Questions Addressed in this Report

What is the 10-year outlook for the global High-DOF Dexterous Hand for Robot market?

What factors are driving High-DOF Dexterous Hand for Robot market growth, globally and by region?

Which technologies are poised for the fastest growth by market and region?

How do High-DOF Dexterous Hand for Robot market opportunities vary by end market size?

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How does High-DOF Dexterous Hand for Robot break out by Type, by Application?

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Contents

1 SCOPE OF THE REPORT

1.1 Market Introduction
1.2 Years Considered
1.3 Research Objectives
1.4 Market Research Methodology
1.5 Research Process and Data Source
1.6 Economic Indicators
1.7 Currency Considered
1.8 Market Estimation Caveats

2 EXECUTIVE SUMMARY

2.1 World Market Overview
  2.1.1 Global High-DOF Dexterous Hand for Robot Annual Sales 2021-2032
  2.1.2 World Current & Future Analysis for High-DOF Dexterous Hand for Robot by Geographic Region, 2021, 2025 & 2032
  2.1.3 World Current & Future Analysis for High-DOF Dexterous Hand for Robot by Country/Region, 2021, 2025 & 2032
2.2 High-DOF Dexterous Hand for Robot Segment by Type
  2.2.1 Four-Fingered Dexterous Hand
  2.2.2 Five-Fingered Dexterous Hand
  2.2.3 High-DOF Dexterous Hand for Robot Sales by Type
    2.2.3.1 Global High-DOF Dexterous Hand for Robot Sales Market Share by Type (2021-2026)
    2.2.3.2 Global High-DOF Dexterous Hand for Robot Revenue and Market Share by Type (2021-2026)
    2.2.3.3 Global High-DOF Dexterous Hand for Robot Sale Price by Type (2021-2026)
2.3 High-DOF Dexterous Hand for Robot Segment by DOF
  2.3.1 12–15 DoF
  2.3.2 16–20 DoF
  2.3.3 Over 20 DoF
  2.3.4 High-DOF Dexterous Hand for Robot Sales by DOF
    2.3.4.1 Global High-DOF Dexterous Hand for Robot Sales Market Share by DOF (2021-2026)
    2.3.4.2 Global High-DOF Dexterous Hand for Robot Revenue and Market Share by DOF (2021-2026)

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2.3.4.3 Global High-DOF Dexterous Hand for Robot Sale Price by DOF (2021-2026)
2.4 High-DOF Dexterous Hand for Robot Segment by Application
2.4.1 Collaborative Robots
2.4.2 Humanoid Robots
2.4.3 Medical and Surgical Robots
2.4.4 Others
2.4.5 High-DOF Dexterous Hand for Robot Sales by Application
2.4.5.1 Global High-DOF Dexterous Hand for Robot Sale Market Share by Application (2021-2026)
2.4.5.2 Global High-DOF Dexterous Hand for Robot Revenue and Market Share by Application (2021-2026)
2.4.5.3 Global High-DOF Dexterous Hand for Robot Sale Price by Application (2021-2026)

3 GLOBAL BY COMPANY

3.1 Global High-DOF Dexterous Hand for Robot Breakdown Data by Company
3.1.1 Global High-DOF Dexterous Hand for Robot Annual Sales by Company (2021-2026)
3.1.2 Global High-DOF Dexterous Hand for Robot Sales Market Share by Company (2021-2026)
3.2 Global High-DOF Dexterous Hand for Robot Annual Revenue by Company (2021-2026)
3.2.1 Global High-DOF Dexterous Hand for Robot Revenue by Company (2021-2026)
3.2.2 Global High-DOF Dexterous Hand for Robot Revenue Market Share by Company (2021-2026)
3.3 Global High-DOF Dexterous Hand for Robot Sale Price by Company
3.4 Key Manufacturers High-DOF Dexterous Hand for Robot Producing Area Distribution, Sales Area, Product Type
3.4.1 Key Manufacturers High-DOF Dexterous Hand for Robot Product Location Distribution
3.4.2 Players High-DOF Dexterous Hand for Robot Products Offered
3.5 Market Concentration Rate Analysis
3.5.1 Competition Landscape Analysis
3.5.2 Concentration Ratio (CR3, CR5 and CR10) & (2024-2026)
3.6 New Products and Potential Entrants
3.7 Market M&A Activity & Strategy

4 WORLD HISTORIC REVIEW FOR HIGH-DOF DEXTEROUS HAND FOR ROBOT

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BY GEOGRAPHIC REGION

4.1 World Historic High-DOF Dexterous Hand for Robot Market Size by Geographic Region (2021-2026)
  4.1.1 Global High-DOF Dexterous Hand for Robot Annual Sales by Geographic Region (2021-2026)
  4.1.2 Global High-DOF Dexterous Hand for Robot Annual Revenue by Geographic Region (2021-2026)
4.2 World Historic High-DOF Dexterous Hand for Robot Market Size by Country/Region (2021-2026)
  4.2.1 Global High-DOF Dexterous Hand for Robot Annual Sales by Country/Region (2021-2026)
  4.2.2 Global High-DOF Dexterous Hand for Robot Annual Revenue by Country/Region (2021-2026)
4.3 Americas High-DOF Dexterous Hand for Robot Sales Growth
4.4 APAC High-DOF Dexterous Hand for Robot Sales Growth
4.5 Europe High-DOF Dexterous Hand for Robot Sales Growth
4.6 Middle East & Africa High-DOF Dexterous Hand for Robot Sales Growth

5 AMERICAS

5.1 Americas High-DOF Dexterous Hand for Robot Sales by Country
  5.1.1 Americas High-DOF Dexterous Hand for Robot Sales by Country (2021-2026)
  5.1.2 Americas High-DOF Dexterous Hand for Robot Revenue by Country (2021-2026)
5.2 Americas High-DOF Dexterous Hand for Robot Sales by Type (2021-2026)
5.3 Americas High-DOF Dexterous Hand for Robot Sales by Application (2021-2026)
5.4 United States
5.5 Canada
5.6 Mexico
5.7 Brazil

6 APAC

6.1 APAC High-DOF Dexterous Hand for Robot Sales by Region
  6.1.1 APAC High-DOF Dexterous Hand for Robot Sales by Region (2021-2026)
  6.1.2 APAC High-DOF Dexterous Hand for Robot Revenue by Region (2021-2026)
6.2 APAC High-DOF Dexterous Hand for Robot Sales by Type (2021-2026)
6.3 APAC High-DOF Dexterous Hand for Robot Sales by Application (2021-2026)

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6.4 China
6.5 Japan
6.6 South Korea
6.7 Southeast Asia
6.8 India
6.9 Australia
6.10 China Taiwan

7 EUROPE

7.1 Europe High-DOF Dexterous Hand for Robot by Country
  7.1.1 Europe High-DOF Dexterous Hand for Robot Sales by Country (2021-2026)
  7.1.2 Europe High-DOF Dexterous Hand for Robot Revenue by Country (2021-2026)
7.2 Europe High-DOF Dexterous Hand for Robot Sales by Type (2021-2026)
7.3 Europe High-DOF Dexterous Hand for Robot Sales by Application (2021-2026)
7.4 Germany
7.5 France
7.6 UK
7.7 Italy
7.8 Russia

8 MIDDLE EAST & AFRICA

8.1 Middle East & Africa High-DOF Dexterous Hand for Robot by Country
  8.1.1 Middle East & Africa High-DOF Dexterous Hand for Robot Sales by Country (2021-2026)
  8.1.2 Middle East & Africa High-DOF Dexterous Hand for Robot Revenue by Country (2021-2026)
8.2 Middle East & Africa High-DOF Dexterous Hand for Robot Sales by Type (2021-2026)
8.3 Middle East & Africa High-DOF Dexterous Hand for Robot Sales by Application (2021-2026)
8.4 Egypt
8.5 South Africa
8.6 Israel
8.7 Turkey
8.8 GCC Countries

9 MARKET DRIVERS, CHALLENGES AND TRENDS

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9.1 Market Drivers & Growth Opportunities
9.2 Market Challenges & Risks
9.3 Industry Trends

10 MANUFACTURING COST STRUCTURE ANALYSIS

10.1 Raw Material and Suppliers
10.2 Manufacturing Cost Structure Analysis of High-DOF Dexterous Hand for Robot
10.3 Manufacturing Process Analysis of High-DOF Dexterous Hand for Robot
10.4 Industry Chain Structure of High-DOF Dexterous Hand for Robot

11 MARKETING, DISTRIBUTORS AND CUSTOMER

11.1 Sales Channel
  11.1.1 Direct Channels
  11.1.2 Indirect Channels
11.2 High-DOF Dexterous Hand for Robot Distributors
11.3 High-DOF Dexterous Hand for Robot Customer

12 WORLD FORECAST REVIEW FOR HIGH-DOF DEXTEROUS HAND FOR ROBOT BY GEOGRAPHIC REGION

12.1 Global High-DOF Dexterous Hand for Robot Market Size Forecast by Region
  12.1.1 Global High-DOF Dexterous Hand for Robot Forecast by Region (2027-2032)
  12.1.2 Global High-DOF Dexterous Hand for Robot Annual Revenue Forecast by Region (2027-2032)
12.2 Americas Forecast by Country (2027-2032)
12.3 APAC Forecast by Region (2027-2032)
12.4 Europe Forecast by Country (2027-2032)
12.5 Middle East & Africa Forecast by Country (2027-2032)
12.6 Global High-DOF Dexterous Hand for Robot Forecast by Type (2027-2032)
12.7 Global High-DOF Dexterous Hand for Robot Forecast by Application (2027-2032)

13 KEY PLAYERS ANALYSIS

13.1 LinkerBot
  13.1.1 LinkerBot Company Information
  13.1.2 LinkerBot High-DOF Dexterous Hand for Robot Product Portfolios and

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Specifications
13.1.3 LinkerBot High-DOF Dexterous Hand for Robot Sales, Revenue, Price and Gross Margin (2021-2026)
13.1.4 LinkerBot Main Business Overview
13.1.5 LinkerBot Latest Developments
13.2 AGIBOT
13.2.1 AGIBOT Company Information
13.2.2 AGIBOT High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
13.2.3 AGIBOT High-DOF Dexterous Hand for Robot Sales, Revenue, Price and Gross Margin (2021-2026)
13.2.4 AGIBOT Main Business Overview
13.2.5 AGIBOT Latest Developments
13.3 RobotEra
13.3.1 RobotEra Company Information
13.3.2 RobotEra High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
13.3.3 RobotEra High-DOF Dexterous Hand for Robot Sales, Revenue, Price and Gross Margin (2021-2026)
13.3.4 RobotEra Main Business Overview
13.3.5 RobotEra Latest Developments
13.4 DexRobot
13.4.1 DexRobot Company Information
13.4.2 DexRobot High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
13.4.3 DexRobot High-DOF Dexterous Hand for Robot Sales, Revenue, Price and Gross Margin (2021-2026)
13.4.4 DexRobot Main Business Overview
13.4.5 DexRobot Latest Developments
13.5 PaXini
13.5.1 PaXini Company Information
13.5.2 PaXini High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
13.5.3 PaXini High-DOF Dexterous Hand for Robot Sales, Revenue, Price and Gross Margin (2021-2026)
13.5.4 PaXini Main Business Overview
13.5.5 PaXini Latest Developments
13.6 WUJI TECH
13.6.1 WUJI TECH Company Information

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13.6.2 WUJI TECH High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
13.6.3 WUJI TECH High-DOF Dexterous Hand for Robot Sales, Revenue, Price and Gross Margin (2021-2026)
13.6.4 WUJI TECH Main Business Overview
13.6.5 WUJI TECH Latest Developments
13.7 Shadow Robot
13.7.1 Shadow Robot Company Information
13.7.2 Shadow Robot High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
13.7.3 Shadow Robot High-DOF Dexterous Hand for Robot Sales, Revenue, Price and Gross Margin (2021-2026)
13.7.4 Shadow Robot Main Business Overview
13.7.5 Shadow Robot Latest Developments
13.8 Agile Robots
13.8.1 Agile Robots Company Information
13.8.2 Agile Robots High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
13.8.3 Agile Robots High-DOF Dexterous Hand for Robot Sales, Revenue, Price and Gross Margin (2021-2026)
13.8.4 Agile Robots Main Business Overview
13.8.5 Agile Robots Latest Developments
13.9 Seed Robotics
13.9.1 Seed Robotics Company Information
13.9.2 Seed Robotics High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
13.9.3 Seed Robotics High-DOF Dexterous Hand for Robot Sales, Revenue, Price and Gross Margin (2021-2026)
13.9.4 Seed Robotics Main Business Overview
13.9.5 Seed Robotics Latest Developments
13.10 Sharpa Robotics
13.10.1 Sharpa Robotics Company Information
13.10.2 Sharpa Robotics High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
13.10.3 Sharpa Robotics High-DOF Dexterous Hand for Robot Sales, Revenue, Price and Gross Margin (2021-2026)
13.10.4 Sharpa Robotics Main Business Overview
13.10.5 Sharpa Robotics Latest Developments
13.11 Tokyo Robotics

+357 96 030922
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13.11.1 Tokyo Robotics Company Information
13.11.2 Tokyo Robotics High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
13.11.3 Tokyo Robotics High-DOF Dexterous Hand for Robot Sales, Revenue, Price and Gross Margin (2021-2026)
13.11.4 Tokyo Robotics Main Business Overview
13.11.5 Tokyo Robotics Latest Developments
13.12 Inspire Robots Technology
13.12.1 Inspire Robots Technology Company Information
13.12.2 Inspire Robots Technology High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
13.12.3 Inspire Robots Technology High-DOF Dexterous Hand for Robot Sales, Revenue, Price and Gross Margin (2021-2026)
13.12.4 Inspire Robots Technology Main Business Overview
13.12.5 Inspire Robots Technology Latest Developments
13.13 Zhejiang BrainCo
13.13.1 Zhejiang BrainCo Company Information
13.13.2 Zhejiang BrainCo High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
13.13.3 Zhejiang BrainCo High-DOF Dexterous Hand for Robot Sales, Revenue, Price and Gross Margin (2021-2026)
13.13.4 Zhejiang BrainCo Main Business Overview
13.13.5 Zhejiang BrainCo Latest Developments
13.14 Jodell Robotics
13.14.1 Jodell Robotics Company Information
13.14.2 Jodell Robotics High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
13.14.3 Jodell Robotics High-DOF Dexterous Hand for Robot Sales, Revenue, Price and Gross Margin (2021-2026)
13.14.4 Jodell Robotics Main Business Overview
13.14.5 Jodell Robotics Latest Developments
13.15 ZWHAND
13.15.1 ZWHAND Company Information
13.15.2 ZWHAND High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
13.15.3 ZWHAND High-DOF Dexterous Hand for Robot Sales, Revenue, Price and Gross Margin (2021-2026)
13.15.4 ZWHAND Main Business Overview
13.15.5 ZWHAND Latest Developments

+357 96 030922
info@marketpublishers.com

13.16 Leadshine
13.16.1 Leadshine Company Information
13.16.2 Leadshine High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
13.16.3 Leadshine High-DOF Dexterous Hand for Robot Sales, Revenue, Price and Gross Margin (2021-2026)
13.16.4 Leadshine Main Business Overview
13.16.5 Leadshine Latest Developments
13.17 Unitree Robotics
13.17.1 Unitree Robotics Company Information
13.17.2 Unitree Robotics High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
13.17.3 Unitree Robotics High-DOF Dexterous Hand for Robot Sales, Revenue, Price and Gross Margin (2021-2026)
13.17.4 Unitree Robotics Main Business Overview
13.17.5 Unitree Robotics Latest Developments
13.18 ENCOS
13.18.1 ENCOS Company Information
13.18.2 ENCOS High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
13.18.3 ENCOS High-DOF Dexterous Hand for Robot Sales, Revenue, Price and Gross Margin (2021-2026)
13.18.4 ENCOS Main Business Overview
13.18.5 ENCOS Latest Developments
13.19 PsiBot
13.19.1 PsiBot Company Information
13.19.2 PsiBot High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
13.19.3 PsiBot High-DOF Dexterous Hand for Robot Sales, Revenue, Price and Gross Margin (2021-2026)
13.19.4 PsiBot Main Business Overview
13.19.5 PsiBot Latest Developments
13.20 Stella-Robot
13.20.1 Stella-Robot Company Information
13.20.2 Stella-Robot High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
13.20.3 Stella-Robot High-DOF Dexterous Hand for Robot Sales, Revenue, Price and Gross Margin (2021-2026)
13.20.4 Stella-Robot Main Business Overview

+357 96 030922
info@marketpublishers.com

13.20.5 Stella-Robot Latest Developments
13.21 AIDIN Robotics
13.21.1 AIDIN Robotics Company Information
13.21.2 AIDIN Robotics High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
13.21.3 AIDIN Robotics High-DOF Dexterous Hand for Robot Sales, Revenue, Price and Gross Margin (2021-2026)
13.21.4 AIDIN Robotics Main Business Overview
13.21.5 AIDIN Robotics Latest Developments

14 RESEARCH FINDINGS AND CONCLUSION

+357 96 030922
info@marketpublishers.com

List Of Tables

LIST OF TABLES

Table 1. High-DOF Dexterous Hand for Robot Annual Sales CAGR by Geographic Region (2021, 2025 & 2032) & ($ millions)
Table 2. High-DOF Dexterous Hand for Robot Annual Sales CAGR by Country/Region (2021, 2025 & 2032) & ($ millions)
Table 3. Major Players of Four-Fingered Dexterous Hand
Table 4. Major Players of Five-Fingered Dexterous Hand
Table 5. Global High-DOF Dexterous Hand for Robot Sales by Type (2021-2026) & (Units)
Table 6. Global High-DOF Dexterous Hand for Robot Sales Market Share by Type (2021-2026)
Table 7. Global High-DOF Dexterous Hand for Robot Revenue by Type (2021-2026) & ($ million)
Table 8. Global High-DOF Dexterous Hand for Robot Revenue Market Share by Type (2021-2026)
Table 9. Global High-DOF Dexterous Hand for Robot Sale Price by Type (2021-2026) & (US$/Unit)
Table 10. Major Players of 12–15 DoF
Table 11. Major Players of 16–20 DoF
Table 12. Major Players of Over 20 DoF
Table 13. Global High-DOF Dexterous Hand for Robot Sales by DOF (2021-2026) & (Units)
Table 14. Global High-DOF Dexterous Hand for Robot Sales Market Share by DOF (2021-2026)
Table 15. Global High-DOF Dexterous Hand for Robot Revenue by DOF (2021-2026) & ($ million)
Table 16. Global High-DOF Dexterous Hand for Robot Revenue Market Share by DOF (2021-2026)
Table 17. Global High-DOF Dexterous Hand for Robot Sale Price by DOF (2021-2026) & (US$/Unit)
Table 18. Global High-DOF Dexterous Hand for Robot Sale by Application (2021-2026) & (Units)
Table 19. Global High-DOF Dexterous Hand for Robot Sale Market Share by Application (2021-2026)
Table 20. Global High-DOF Dexterous Hand for Robot Revenue by Application (2021-2026) & ($ million)

+357 96 030922
info@marketpublishers.com

Table 21. Global High-DOF Dexterous Hand for Robot Revenue Market Share by Application (2021-2026)
Table 22. Global High-DOF Dexterous Hand for Robot Sale Price by Application (2021-2026) & (US$/Unit)
Table 23. Global High-DOF Dexterous Hand for Robot Sales by Company (2021-2026) & (Units)
Table 24. Global High-DOF Dexterous Hand for Robot Sales Market Share by Company (2021-2026)
Table 25. Global High-DOF Dexterous Hand for Robot Revenue by Company (2021-2026) & ($ millions)
Table 26. Global High-DOF Dexterous Hand for Robot Revenue Market Share by Company (2021-2026)
Table 27. Global High-DOF Dexterous Hand for Robot Sale Price by Company (2021-2026) & (US$/Unit)
Table 28. Key Manufacturers High-DOF Dexterous Hand for Robot Producing Area Distribution and Sales Area
Table 29. Players High-DOF Dexterous Hand for Robot Products Offered
Table 30. High-DOF Dexterous Hand for Robot Concentration Ratio (CR3, CR5 and CR10) & (2024-2026)
Table 31. New Products and Potential Entrants
Table 32. Market M&A Activity & Strategy
Table 33. Global High-DOF Dexterous Hand for Robot Sales by Geographic Region (2021-2026) & (Units)
Table 34. Global High-DOF Dexterous Hand for Robot Sales Market Share Geographic Region (2021-2026)
Table 35. Global High-DOF Dexterous Hand for Robot Revenue by Geographic Region (2021-2026) & ($ millions)
Table 36. Global High-DOF Dexterous Hand for Robot Revenue Market Share by Geographic Region (2021-2026)
Table 37. Global High-DOF Dexterous Hand for Robot Sales by Country/Region (2021-2026) & (Units)
Table 38. Global High-DOF Dexterous Hand for Robot Sales Market Share by Country/Region (2021-2026)
Table 39. Global High-DOF Dexterous Hand for Robot Revenue by Country/Region (2021-2026) & ($ millions)
Table 40. Global High-DOF Dexterous Hand for Robot Revenue Market Share by Country/Region (2021-2026)
Table 41. Americas High-DOF Dexterous Hand for Robot Sales by Country (2021-2026) & (Units)

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Table 42. Americas High-DOF Dexterous Hand for Robot Sales Market Share by Country (2021-2026)
Table 43. Americas High-DOF Dexterous Hand for Robot Revenue by Country (2021-2026) & ($ millions)
Table 44. Americas High-DOF Dexterous Hand for Robot Sales by Type (2021-2026) & (Units)
Table 45. Americas High-DOF Dexterous Hand for Robot Sales by Application (2021-2026) & (Units)
Table 46. APAC High-DOF Dexterous Hand for Robot Sales by Region (2021-2026) & (Units)
Table 47. APAC High-DOF Dexterous Hand for Robot Sales Market Share by Region (2021-2026)
Table 48. APAC High-DOF Dexterous Hand for Robot Revenue by Region (2021-2026) & ($ millions)
Table 49. APAC High-DOF Dexterous Hand for Robot Sales by Type (2021-2026) & (Units)
Table 50. APAC High-DOF Dexterous Hand for Robot Sales by Application (2021-2026) & (Units)
Table 51. Europe High-DOF Dexterous Hand for Robot Sales by Country (2021-2026) & (Units)
Table 52. Europe High-DOF Dexterous Hand for Robot Revenue by Country (2021-2026) & ($ millions)
Table 53. Europe High-DOF Dexterous Hand for Robot Sales by Type (2021-2026) & (Units)
Table 54. Europe High-DOF Dexterous Hand for Robot Sales by Application (2021-2026) & (Units)
Table 55. Middle East & Africa High-DOF Dexterous Hand for Robot Sales by Country (2021-2026) & (Units)
Table 56. Middle East & Africa High-DOF Dexterous Hand for Robot Revenue Market Share by Country (2021-2026)
Table 57. Middle East & Africa High-DOF Dexterous Hand for Robot Sales by Type (2021-2026) & (Units)
Table 58. Middle East & Africa High-DOF Dexterous Hand for Robot Sales by Application (2021-2026) & (Units)
Table 59. Key Market Drivers & Growth Opportunities of High-DOF Dexterous Hand for Robot
Table 60. Key Market Challenges & Risks of High-DOF Dexterous Hand for Robot
Table 61. Key Industry Trends of High-DOF Dexterous Hand for Robot
Table 62. High-DOF Dexterous Hand for Robot Raw Material

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Table 63. Key Suppliers of Raw Materials
Table 64. High-DOF Dexterous Hand for Robot Distributors List
Table 65. High-DOF Dexterous Hand for Robot Customer List
Table 66. Global High-DOF Dexterous Hand for Robot Sales Forecast by Region (2027-2032) & (Units)
Table 67. Global High-DOF Dexterous Hand for Robot Revenue Forecast by Region (2027-2032) & ($ millions)
Table 68. Americas High-DOF Dexterous Hand for Robot Sales Forecast by Country (2027-2032) & (Units)
Table 69. Americas High-DOF Dexterous Hand for Robot Annual Revenue Forecast by Country (2027-2032) & ($ millions)
Table 70. APAC High-DOF Dexterous Hand for Robot Sales Forecast by Region (2027-2032) & (Units)
Table 71. APAC High-DOF Dexterous Hand for Robot Annual Revenue Forecast by Region (2027-2032) & ($ millions)
Table 72. Europe High-DOF Dexterous Hand for Robot Sales Forecast by Country (2027-2032) & (Units)
Table 73. Europe High-DOF Dexterous Hand for Robot Revenue Forecast by Country (2027-2032) & ($ millions)
Table 74. Middle East & Africa High-DOF Dexterous Hand for Robot Sales Forecast by Country (2027-2032) & (Units)
Table 75. Middle East & Africa High-DOF Dexterous Hand for Robot Revenue Forecast by Country (2027-2032) & ($ millions)
Table 76. Global High-DOF Dexterous Hand for Robot Sales Forecast by Type (2027-2032) & (Units)
Table 77. Global High-DOF Dexterous Hand for Robot Revenue Forecast by Type (2027-2032) & ($ millions)
Table 78. Global High-DOF Dexterous Hand for Robot Sales Forecast by Application (2027-2032) & (Units)
Table 79. Global High-DOF Dexterous Hand for Robot Revenue Forecast by Application (2027-2032) & ($ millions)
Table 80. LinkerBot Basic Information, High-DOF Dexterous Hand for Robot Manufacturing Base, Sales Area and Its Competitors
Table 81. LinkerBot High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
Table 82. LinkerBot High-DOF Dexterous Hand for Robot Sales (Units), Revenue ($ Million), Price (US$/Unit) and Gross Margin (2021-2026)
Table 83. LinkerBot Main Business
Table 84. LinkerBot Latest Developments

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Table 85. AGIBOT Basic Information, High-DOF Dexterous Hand for Robot Manufacturing Base, Sales Area and Its Competitors
Table 86. AGIBOT High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
Table 87. AGIBOT High-DOF Dexterous Hand for Robot Sales (Units), Revenue ($ Million), Price (US$/Unit) and Gross Margin (2021-2026)
Table 88. AGIBOT Main Business
Table 89. AGIBOT Latest Developments
Table 90. RobotEra Basic Information, High-DOF Dexterous Hand for Robot Manufacturing Base, Sales Area and Its Competitors
Table 91. RobotEra High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
Table 92. RobotEra High-DOF Dexterous Hand for Robot Sales (Units), Revenue ($ Million), Price (US$/Unit) and Gross Margin (2021-2026)
Table 93. RobotEra Main Business
Table 94. RobotEra Latest Developments
Table 95. DexRobot Basic Information, High-DOF Dexterous Hand for Robot Manufacturing Base, Sales Area and Its Competitors
Table 96. DexRobot High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
Table 97. DexRobot High-DOF Dexterous Hand for Robot Sales (Units), Revenue ($ Million), Price (US$/Unit) and Gross Margin (2021-2026)
Table 98. DexRobot Main Business
Table 99. DexRobot Latest Developments
Table 100. PaXini Basic Information, High-DOF Dexterous Hand for Robot Manufacturing Base, Sales Area and Its Competitors
Table 101. PaXini High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
Table 102. PaXini High-DOF Dexterous Hand for Robot Sales (Units), Revenue ($ Million), Price (US$/Unit) and Gross Margin (2021-2026)
Table 103. PaXini Main Business
Table 104. PaXini Latest Developments
Table 105. WUJI TECH Basic Information, High-DOF Dexterous Hand for Robot Manufacturing Base, Sales Area and Its Competitors
Table 106. WUJI TECH High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
Table 107. WUJI TECH High-DOF Dexterous Hand for Robot Sales (Units), Revenue ($ Million), Price (US$/Unit) and Gross Margin (2021-2026)
Table 108. WUJI TECH Main Business

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Table 109. WUJI TECH Latest Developments
Table 110. Shadow Robot Basic Information, High-DOF Dexterous Hand for Robot Manufacturing Base, Sales Area and Its Competitors
Table 111. Shadow Robot High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
Table 112. Shadow Robot High-DOF Dexterous Hand for Robot Sales (Units), Revenue ($ Million), Price (US$/Unit) and Gross Margin (2021-2026)
Table 113. Shadow Robot Main Business
Table 114. Shadow Robot Latest Developments
Table 115. Agile Robots Basic Information, High-DOF Dexterous Hand for Robot Manufacturing Base, Sales Area and Its Competitors
Table 116. Agile Robots High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
Table 117. Agile Robots High-DOF Dexterous Hand for Robot Sales (Units), Revenue ($ Million), Price (US$/Unit) and Gross Margin (2021-2026)
Table 118. Agile Robots Main Business
Table 119. Agile Robots Latest Developments
Table 120. Seed Robotics Basic Information, High-DOF Dexterous Hand for Robot Manufacturing Base, Sales Area and Its Competitors
Table 121. Seed Robotics High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
Table 122. Seed Robotics High-DOF Dexterous Hand for Robot Sales (Units), Revenue ($ Million), Price (US$/Unit) and Gross Margin (2021-2026)
Table 123. Seed Robotics Main Business
Table 124. Seed Robotics Latest Developments
Table 125. Sharpa Robotics Basic Information, High-DOF Dexterous Hand for Robot Manufacturing Base, Sales Area and Its Competitors
Table 126. Sharpa Robotics High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
Table 127. Sharpa Robotics High-DOF Dexterous Hand for Robot Sales (Units), Revenue ($ Million), Price (US$/Unit) and Gross Margin (2021-2026)
Table 128. Sharpa Robotics Main Business
Table 129. Sharpa Robotics Latest Developments
Table 130. Tokyo Robotics Basic Information, High-DOF Dexterous Hand for Robot Manufacturing Base, Sales Area and Its Competitors
Table 131. Tokyo Robotics High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
Table 132. Tokyo Robotics High-DOF Dexterous Hand for Robot Sales (Units), Revenue ($ Million), Price (US$/Unit) and Gross Margin (2021-2026)

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Table 133. Tokyo Robotics Main Business
Table 134. Tokyo Robotics Latest Developments
Table 135. Inspire Robots Technology Basic Information, High-DOF Dexterous Hand for Robot Manufacturing Base, Sales Area and Its Competitors
Table 136. Inspire Robots Technology High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
Table 137. Inspire Robots Technology High-DOF Dexterous Hand for Robot Sales (Units), Revenue ($ Million), Price (US$/Unit) and Gross Margin (2021-2026)
Table 138. Inspire Robots Technology Main Business
Table 139. Inspire Robots Technology Latest Developments
Table 140. Zhejiang BrainCo Basic Information, High-DOF Dexterous Hand for Robot Manufacturing Base, Sales Area and Its Competitors
Table 141. Zhejiang BrainCo High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
Table 142. Zhejiang BrainCo High-DOF Dexterous Hand for Robot Sales (Units), Revenue ($ Million), Price (US$/Unit) and Gross Margin (2021-2026)
Table 143. Zhejiang BrainCo Main Business
Table 144. Zhejiang BrainCo Latest Developments
Table 145. Jodell Robotics Basic Information, High-DOF Dexterous Hand for Robot Manufacturing Base, Sales Area and Its Competitors
Table 146. Jodell Robotics High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
Table 147. Jodell Robotics High-DOF Dexterous Hand for Robot Sales (Units), Revenue ($ Million), Price (US$/Unit) and Gross Margin (2021-2026)
Table 148. Jodell Robotics Main Business
Table 149. Jodell Robotics Latest Developments
Table 150. ZWHAND Basic Information, High-DOF Dexterous Hand for Robot Manufacturing Base, Sales Area and Its Competitors
Table 151. ZWHAND High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
Table 152. ZWHAND High-DOF Dexterous Hand for Robot Sales (Units), Revenue ($ Million), Price (US$/Unit) and Gross Margin (2021-2026)
Table 153. ZWHAND Main Business
Table 154. ZWHAND Latest Developments
Table 155. Leadshine Basic Information, High-DOF Dexterous Hand for Robot Manufacturing Base, Sales Area and Its Competitors
Table 156. Leadshine High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
Table 157. Leadshine High-DOF Dexterous Hand for Robot Sales (Units), Revenue ($

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Million), Price (US$/Unit) and Gross Margin (2021-2026)
Table 158. Leadshine Main Business
Table 159. Leadshine Latest Developments
Table 160. Unitree Robotics Basic Information, High-DOF Dexterous Hand for Robot Manufacturing Base, Sales Area and Its Competitors
Table 161. Unitree Robotics High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
Table 162. Unitree Robotics High-DOF Dexterous Hand for Robot Sales (Units), Revenue ($ Million), Price (US$/Unit) and Gross Margin (2021-2026)
Table 163. Unitree Robotics Main Business
Table 164. Unitree Robotics Latest Developments
Table 165. ENCOS Basic Information, High-DOF Dexterous Hand for Robot Manufacturing Base, Sales Area and Its Competitors
Table 166. ENCOS High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
Table 167. ENCOS High-DOF Dexterous Hand for Robot Sales (Units), Revenue ($ Million), Price (US$/Unit) and Gross Margin (2021-2026)
Table 168. ENCOS Main Business
Table 169. ENCOS Latest Developments
Table 170. PsiBot Basic Information, High-DOF Dexterous Hand for Robot Manufacturing Base, Sales Area and Its Competitors
Table 171. PsiBot High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
Table 172. PsiBot High-DOF Dexterous Hand for Robot Sales (Units), Revenue ($ Million), Price (US$/Unit) and Gross Margin (2021-2026)
Table 173. PsiBot Main Business
Table 174. PsiBot Latest Developments
Table 175. Stella-Robot Basic Information, High-DOF Dexterous Hand for Robot Manufacturing Base, Sales Area and Its Competitors
Table 176. Stella-Robot High-DOF Dexterous Hand for Robot Product Portfolios and Specifications
Table 177. Stella-Robot High-DOF Dexterous Hand for Robot Sales (Units), Revenue ($ Million), Price (US$/Unit) and Gross Margin (2021-2026)
Table 178. Stella-Robot Main Business
Table 179. Stella-Robot Latest Developments
Table 180. AIDIN Robotics Basic Information, High-DOF Dexterous Hand for Robot Manufacturing Base, Sales Area and Its Competitors
Table 181. AIDIN Robotics High-DOF Dexterous Hand for Robot Product Portfolios and Specifications

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Table 182. AIDIN Robotics High-DOF Dexterous Hand for Robot Sales (Units), Revenue ($ Million), Price (US$/Unit) and Gross Margin (2021-2026)
Table 183. AIDIN Robotics Main Business
Table 184. AIDIN Robotics Latest Developments

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List Of Figures

LIST OF FIGURES

Figure 1. Picture of High-DOF Dexterous Hand for Robot
Figure 2. High-DOF Dexterous Hand for Robot Report Years Considered
Figure 3. Research Objectives
Figure 4. Research Methodology
Figure 5. Research Process and Data Source
Figure 6. Global High-DOF Dexterous Hand for Robot Sales Growth Rate 2021-2032 (Units)
Figure 7. Global High-DOF Dexterous Hand for Robot Revenue Growth Rate 2021-2032 ($ millions)
Figure 8. High-DOF Dexterous Hand for Robot Sales by Geographic Region (2021, 2025 & 2032) & ($ millions)
Figure 9. High-DOF Dexterous Hand for Robot Sales Market Share by Country/Region (2025)
Figure 10. High-DOF Dexterous Hand for Robot Sales Market Share by Country/Region (2021, 2025 & 2032)
Figure 11. Product Picture of Four-Fingered Dexterous Hand
Figure 12. Product Picture of Five-Fingered Dexterous Hand
Figure 13. Global High-DOF Dexterous Hand for Robot Sales Market Share by Type in 2026
Figure 14. Global High-DOF Dexterous Hand for Robot Revenue Market Share by Type (2021-2026)
Figure 15. Product Picture of 12–15 DoF
Figure 16. Product Picture of 16–20 DoF
Figure 17. Product Picture of Over 20 DoF
Figure 18. Global High-DOF Dexterous Hand for Robot Sales Market Share by DOF in 2026
Figure 19. Global High-DOF Dexterous Hand for Robot Revenue Market Share by DOF (2021-2026)
Figure 20. High-DOF Dexterous Hand for Robot Consumed in Collaborative Robots
Figure 21. Global High-DOF Dexterous Hand for Robot Market: Collaborative Robots (2021-2026) & (Units)
Figure 22. High-DOF Dexterous Hand for Robot Consumed in Humanoid Robots
Figure 23. Global High-DOF Dexterous Hand for Robot Market: Humanoid Robots (2021-2026) & (Units)
Figure 24. High-DOF Dexterous Hand for Robot Consumed in Medical and Surgical

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Robots
Figure 25. Global High-DOF Dexterous Hand for Robot Market: Medical and Surgical Robots (2021-2026) & (Units)
Figure 26. High-DOF Dexterous Hand for Robot Consumed in Others
Figure 27. Global High-DOF Dexterous Hand for Robot Market: Others (2021-2026) & (Units)
Figure 28. Global High-DOF Dexterous Hand for Robot Sale Market Share by Application (2025)
Figure 29. Global High-DOF Dexterous Hand for Robot Revenue Market Share by Application in 2025
Figure 30. High-DOF Dexterous Hand for Robot Sales by Company in 2025 (Units)
Figure 31. Global High-DOF Dexterous Hand for Robot Sales Market Share by Company in 2025
Figure 32. High-DOF Dexterous Hand for Robot Revenue by Company in 2025 ($ millions)
Figure 33. Global High-DOF Dexterous Hand for Robot Revenue Market Share by Company in 2025
Figure 34. Global High-DOF Dexterous Hand for Robot Sales Market Share by Geographic Region (2021-2026)
Figure 35. Global High-DOF Dexterous Hand for Robot Revenue Market Share by Geographic Region in 2025
Figure 36. Americas High-DOF Dexterous Hand for Robot Sales 2021-2026 (Units)
Figure 37. Americas High-DOF Dexterous Hand for Robot Revenue 2021-2026 ($ millions)
Figure 38. APAC High-DOF Dexterous Hand for Robot Sales 2021-2026 (Units)
Figure 39. APAC High-DOF Dexterous Hand for Robot Revenue 2021-2026 ($ millions)
Figure 40. Europe High-DOF Dexterous Hand for Robot Sales 2021-2026 (Units)
Figure 41. Europe High-DOF Dexterous Hand for Robot Revenue 2021-2026 ($ millions)
Figure 42. Middle East & Africa High-DOF Dexterous Hand for Robot Sales 2021-2026 (Units)
Figure 43. Middle East & Africa High-DOF Dexterous Hand for Robot Revenue 2021-2026 ($ millions)
Figure 44. Americas High-DOF Dexterous Hand for Robot Sales Market Share by Country in 2025
Figure 45. Americas High-DOF Dexterous Hand for Robot Revenue Market Share by Country (2021-2026)
Figure 46. Americas High-DOF Dexterous Hand for Robot Sales Market Share by Type (2021-2026)

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Figure 47. Americas High-DOF Dexterous Hand for Robot Sales Market Share by Application (2021-2026)
Figure 48. United States High-DOF Dexterous Hand for Robot Revenue Growth 2021-2026 ($ millions)
Figure 49. Canada High-DOF Dexterous Hand for Robot Revenue Growth 2021-2026 ($ millions)
Figure 50. Mexico High-DOF Dexterous Hand for Robot Revenue Growth 2021-2026 ($ millions)
Figure 51. Brazil High-DOF Dexterous Hand for Robot Revenue Growth 2021-2026 ($ millions)
Figure 52. APAC High-DOF Dexterous Hand for Robot Sales Market Share by Region in 2025
Figure 53. APAC High-DOF Dexterous Hand for Robot Revenue Market Share by Region (2021-2026)
Figure 54. APAC High-DOF Dexterous Hand for Robot Sales Market Share by Type (2021-2026)
Figure 55. APAC High-DOF Dexterous Hand for Robot Sales Market Share by Application (2021-2026)
Figure 56. China High-DOF Dexterous Hand for Robot Revenue Growth 2021-2026 ($ millions)
Figure 57. Japan High-DOF Dexterous Hand for Robot Revenue Growth 2021-2026 ($ millions)
Figure 58. South Korea High-DOF Dexterous Hand for Robot Revenue Growth 2021-2026 ($ millions)
Figure 59. Southeast Asia High-DOF Dexterous Hand for Robot Revenue Growth 2021-2026 ($ millions)
Figure 60. India High-DOF Dexterous Hand for Robot Revenue Growth 2021-2026 ($ millions)
Figure 61. Australia High-DOF Dexterous Hand for Robot Revenue Growth 2021-2026 ($ millions)
Figure 62. China Taiwan High-DOF Dexterous Hand for Robot Revenue Growth 2021-2026 ($ millions)
Figure 63. Europe High-DOF Dexterous Hand for Robot Sales Market Share by Country in 2025
Figure 64. Europe High-DOF Dexterous Hand for Robot Revenue Market Share by Country (2021-2026)
Figure 65. Europe High-DOF Dexterous Hand for Robot Sales Market Share by Type (2021-2026)
Figure 66. Europe High-DOF Dexterous Hand for Robot Sales Market Share by

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Application (2021-2026)
Figure 67. Germany High-DOF Dexterous Hand for Robot Revenue Growth 2021-2026 ($ millions)
Figure 68. France High-DOF Dexterous Hand for Robot Revenue Growth 2021-2026 ($ millions)
Figure 69. UK High-DOF Dexterous Hand for Robot Revenue Growth 2021-2026 ($ millions)
Figure 70. Italy High-DOF Dexterous Hand for Robot Revenue Growth 2021-2026 ($ millions)
Figure 71. Russia High-DOF Dexterous Hand for Robot Revenue Growth 2021-2026 ($ millions)
Figure 72. Middle East & Africa High-DOF Dexterous Hand for Robot Sales Market Share by Country (2021-2026)
Figure 73. Middle East & Africa High-DOF Dexterous Hand for Robot Sales Market Share by Type (2021-2026)
Figure 74. Middle East & Africa High-DOF Dexterous Hand for Robot Sales Market Share by Application (2021-2026)
Figure 75. Egypt High-DOF Dexterous Hand for Robot Revenue Growth 2021-2026 ($ millions)
Figure 76. South Africa High-DOF Dexterous Hand for Robot Revenue Growth 2021-2026 ($ millions)
Figure 77. Israel High-DOF Dexterous Hand for Robot Revenue Growth 2021-2026 ($ millions)
Figure 78. Turkey High-DOF Dexterous Hand for Robot Revenue Growth 2021-2026 ($ millions)
Figure 79. GCC Countries High-DOF Dexterous Hand for Robot Revenue Growth 2021-2026 ($ millions)
Figure 80. Manufacturing Cost Structure Analysis of High-DOF Dexterous Hand for Robot in 2026
Figure 81. Manufacturing Process Analysis of High-DOF Dexterous Hand for Robot
Figure 82. Industry Chain Structure of High-DOF Dexterous Hand for Robot
Figure 83. Channels of Distribution
Figure 84. Global High-DOF Dexterous Hand for Robot Sales Market Forecast by Region (2027-2032)
Figure 85. Global High-DOF Dexterous Hand for Robot Revenue Market Share Forecast by Region (2027-2032)
Figure 86. Global High-DOF Dexterous Hand for Robot Sales Market Share Forecast by Type (2027-2032)
Figure 87. Global High-DOF Dexterous Hand for Robot Revenue Market Share

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Forecast by Type (2027-2032)
Figure 88. Global High-DOF Dexterous Hand for Robot Sales Market Share Forecast by Application (2027-2032)
Figure 89. Global High-DOF Dexterous Hand for Robot Revenue Market Share Forecast by Application (2027-2032)

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