

Global Handheld LiDAR 3D Scanner Market Growth 2026-2032

<https://marketpublishers.com/r/GE1A94155F0FEN.html>

Date: April 2026

Pages: 103

Price: US\$ 3,660.00 (Single User License)

ID: GE1A94155F0FEN

Abstracts

The global Handheld LiDAR 3D Scanner market size is predicted to grow from US\$ million in 2025 to US\$ million in 2032; it is expected to grow at a CAGR of % from 2026 to 2032.

United States market for Handheld LiDAR 3D Scanner is estimated to increase from US\$ million in 2025 to US\$ million by 2032, at a CAGR of % from 2026 through 2032.

China market for Handheld LiDAR 3D Scanner is estimated to increase from US\$ million in 2025 to US\$ million by 2032, at a CAGR of % from 2026 through 2032.

Europe market for Handheld LiDAR 3D Scanner is estimated to increase from US\$ million in 2025 to US\$ million by 2032, at a CAGR of % from 2026 through 2032.

Global key Handheld LiDAR 3D Scanner players cover Emesent Pty Ltd, GeoSLAM?Faro?, Hexagon (Leica), Shenzhen Feima Robotics Technology Co., Ltd., GoSLAM, etc. In terms of revenue, the global two largest companies occupied for a share nearly % in 2025.

LP Information, Inc. (LPI) ' newest research report, the "Handheld LiDAR 3D Scanner Industry Forecast" looks at past sales and reviews total world Handheld LiDAR 3D Scanner sales in 2025, providing a comprehensive analysis by region and market sector of projected Handheld LiDAR 3D Scanner sales for 2026 through 2032. With Handheld LiDAR 3D Scanner sales broken down by region, market sector and sub-sector, this report provides a detailed analysis in US\$ millions of the world Handheld LiDAR 3D Scanner industry.

This Insight Report provides a comprehensive analysis of the global Handheld LiDAR 3D Scanner landscape and highlights key trends related to product segmentation, company formation, revenue, and market share, latest development, and M&A activity. This report also analyzes the strategies of leading global companies with a focus on Handheld LiDAR 3D Scanner portfolios and capabilities, market entry strategies, market positions, and geographic footprints, to better understand these firms' unique position in an accelerating global Handheld LiDAR 3D Scanner market.

This Insight Report evaluates the key market trends, drivers, and affecting factors shaping the global outlook for Handheld LiDAR 3D Scanner and breaks down the forecast by Type, by Application, geography, and market size to highlight emerging pockets of opportunity. With a transparent methodology based on hundreds of bottom-up qualitative and quantitative market inputs, this study forecast offers a highly nuanced view of the current state and future trajectory in the global Handheld LiDAR 3D Scanner.

This report presents a comprehensive overview, market shares, and growth opportunities of Handheld LiDAR 3D Scanner market by product type, application, key manufacturers and key regions and countries.

Segmentation by Type:

Wired

Wireless

Segmentation by Application:

Industrial Design and Manufacturing

Car Traffic

Aviation and Aerospace

Teaching and Scientific Research

Factory Digitization

Digital Twin

Architectural Design

City Renewal

Other

This report also splits the market by region:

Americas

United States

Canada

Mexico

Brazil

APAC

China

Japan

Korea

Southeast Asia

India

Australia

Europe

Germany

France

UK

Italy

Russia

Middle East & Africa

Egypt

South Africa

Israel

Turkey

GCC Countries

The below companies that are profiled have been selected based on inputs gathered from primary experts and analysing the company's coverage, product portfolio, its market penetration.

Emesent Pty Ltd

GeoSLAM?Faro?

Hexagon (Leica)

Shenzhen Feima Robotics Technology Co., Ltd.

GoSLAM

Beijing Green Valley Technology. Co., Ltd.

FJ Dynamics Technology Co., Ltd.

Xgrids

Stonex

Key Questions Addressed in this Report

What is the 10-year outlook for the global Handheld LiDAR 3D Scanner market?

What factors are driving Handheld LiDAR 3D Scanner market growth, globally and by region?

Which technologies are poised for the fastest growth by market and region?

How do Handheld LiDAR 3D Scanner market opportunities vary by end market size?

How does Handheld LiDAR 3D Scanner break out by Type, by Application?

Contents

1 SCOPE OF THE REPORT

- 1.1 Market Introduction
- 1.2 Years Considered
- 1.3 Research Objectives
- 1.4 Market Research Methodology
- 1.5 Research Process and Data Source
- 1.6 Economic Indicators
- 1.7 Currency Considered
- 1.8 Market Estimation Caveats

2 EXECUTIVE SUMMARY

- 2.1 World Market Overview
 - 2.1.1 Global Handheld LiDAR 3D Scanner Annual Sales 2021-2032
 - 2.1.2 World Current & Future Analysis for Handheld LiDAR 3D Scanner by Geographic Region, 2021, 2025 & 2032
 - 2.1.3 World Current & Future Analysis for Handheld LiDAR 3D Scanner by Country/Region, 2021, 2025 & 2032
- 2.2 Handheld LiDAR 3D Scanner Segment by Type
 - 2.2.1 Wired
 - 2.2.2 Wireless
 - 2.2.3 Handheld LiDAR 3D Scanner Sales by Type
 - 2.2.3.1 Global Handheld LiDAR 3D Scanner Sales Market Share by Type (2021-2026)
 - 2.2.3.2 Global Handheld LiDAR 3D Scanner Revenue and Market Share by Type (2021-2026)
 - 2.2.3.3 Global Handheld LiDAR 3D Scanner Sale Price by Type (2021-2026)
- 2.3 Handheld LiDAR 3D Scanner Segment by Application
 - 2.3.1 Industrial Design and Manufacturing
 - 2.3.2 Car Traffic
 - 2.3.3 Aviation and Aerospace
 - 2.3.4 Teaching and Scientific Research
 - 2.3.5 Factory Digitization
 - 2.3.6 Digital Twin
 - 2.3.7 Architectural Design
 - 2.3.8 City Renewal

2.3.9 Other

2.3.10 Handheld LiDAR 3D Scanner Sales by Application

2.3.10.1 Global Handheld LiDAR 3D Scanner Sale Market Share by Application (2021-2026)

2.3.10.2 Global Handheld LiDAR 3D Scanner Revenue and Market Share by Application (2021-2026)

2.3.10.3 Global Handheld LiDAR 3D Scanner Sale Price by Application (2021-2026)

3 GLOBAL BY COMPANY

3.1 Global Handheld LiDAR 3D Scanner Breakdown Data by Company

3.1.1 Global Handheld LiDAR 3D Scanner Annual Sales by Company (2021-2026)

3.1.2 Global Handheld LiDAR 3D Scanner Sales Market Share by Company (2021-2026)

3.2 Global Handheld LiDAR 3D Scanner Annual Revenue by Company (2021-2026)

3.2.1 Global Handheld LiDAR 3D Scanner Revenue by Company (2021-2026)

3.2.2 Global Handheld LiDAR 3D Scanner Revenue Market Share by Company (2021-2026)

3.3 Global Handheld LiDAR 3D Scanner Sale Price by Company

3.4 Key Manufacturers Handheld LiDAR 3D Scanner Producing Area Distribution, Sales Area, Product Type

3.4.1 Key Manufacturers Handheld LiDAR 3D Scanner Product Location Distribution

3.4.2 Players Handheld LiDAR 3D Scanner Products Offered

3.5 Market Concentration Rate Analysis

3.5.1 Competition Landscape Analysis

3.5.2 Concentration Ratio (CR3, CR5 and CR10) & (2024-2026)

3.6 New Products and Potential Entrants

3.7 Market M&A Activity & Strategy

4 WORLD HISTORIC REVIEW FOR HANDHELD LIDAR 3D SCANNER BY GEOGRAPHIC REGION

4.1 World Historic Handheld LiDAR 3D Scanner Market Size by Geographic Region (2021-2026)

4.1.1 Global Handheld LiDAR 3D Scanner Annual Sales by Geographic Region (2021-2026)

4.1.2 Global Handheld LiDAR 3D Scanner Annual Revenue by Geographic Region (2021-2026)

4.2 World Historic Handheld LiDAR 3D Scanner Market Size by Country/Region

(2021-2026)

4.2.1 Global Handheld LiDAR 3D Scanner Annual Sales by Country/Region

(2021-2026)

4.2.2 Global Handheld LiDAR 3D Scanner Annual Revenue by Country/Region

(2021-2026)

4.3 Americas Handheld LiDAR 3D Scanner Sales Growth

4.4 APAC Handheld LiDAR 3D Scanner Sales Growth

4.5 Europe Handheld LiDAR 3D Scanner Sales Growth

4.6 Middle East & Africa Handheld LiDAR 3D Scanner Sales Growth

5 AMERICAS

5.1 Americas Handheld LiDAR 3D Scanner Sales by Country

5.1.1 Americas Handheld LiDAR 3D Scanner Sales by Country (2021-2026)

5.1.2 Americas Handheld LiDAR 3D Scanner Revenue by Country (2021-2026)

5.2 Americas Handheld LiDAR 3D Scanner Sales by Type (2021-2026)

5.3 Americas Handheld LiDAR 3D Scanner Sales by Application (2021-2026)

5.4 United States

5.5 Canada

5.6 Mexico

5.7 Brazil

6 APAC

6.1 APAC Handheld LiDAR 3D Scanner Sales by Region

6.1.1 APAC Handheld LiDAR 3D Scanner Sales by Region (2021-2026)

6.1.2 APAC Handheld LiDAR 3D Scanner Revenue by Region (2021-2026)

6.2 APAC Handheld LiDAR 3D Scanner Sales by Type (2021-2026)

6.3 APAC Handheld LiDAR 3D Scanner Sales by Application (2021-2026)

6.4 China

6.5 Japan

6.6 South Korea

6.7 Southeast Asia

6.8 India

6.9 Australia

6.10 China Taiwan

7 EUROPE

7.1 Europe Handheld LiDAR 3D Scanner by Country

7.1.1 Europe Handheld LiDAR 3D Scanner Sales by Country (2021-2026)

7.1.2 Europe Handheld LiDAR 3D Scanner Revenue by Country (2021-2026)

7.2 Europe Handheld LiDAR 3D Scanner Sales by Type (2021-2026)

7.3 Europe Handheld LiDAR 3D Scanner Sales by Application (2021-2026)

7.4 Germany

7.5 France

7.6 UK

7.7 Italy

7.8 Russia

8 MIDDLE EAST & AFRICA

8.1 Middle East & Africa Handheld LiDAR 3D Scanner by Country

8.1.1 Middle East & Africa Handheld LiDAR 3D Scanner Sales by Country (2021-2026)

8.1.2 Middle East & Africa Handheld LiDAR 3D Scanner Revenue by Country (2021-2026)

8.2 Middle East & Africa Handheld LiDAR 3D Scanner Sales by Type (2021-2026)

8.3 Middle East & Africa Handheld LiDAR 3D Scanner Sales by Application (2021-2026)

8.4 Egypt

8.5 South Africa

8.6 Israel

8.7 Turkey

8.8 GCC Countries

9 MARKET DRIVERS, CHALLENGES AND TRENDS

9.1 Market Drivers & Growth Opportunities

9.2 Market Challenges & Risks

9.3 Industry Trends

10 MANUFACTURING COST STRUCTURE ANALYSIS

10.1 Raw Material and Suppliers

10.2 Manufacturing Cost Structure Analysis of Handheld LiDAR 3D Scanner

10.3 Manufacturing Process Analysis of Handheld LiDAR 3D Scanner

10.4 Industry Chain Structure of Handheld LiDAR 3D Scanner

11 MARKETING, DISTRIBUTORS AND CUSTOMER

11.1 Sales Channel

11.1.1 Direct Channels

11.1.2 Indirect Channels

11.2 Handheld LiDAR 3D Scanner Distributors

11.3 Handheld LiDAR 3D Scanner Customer

12 WORLD FORECAST REVIEW FOR HANDHELD LIDAR 3D SCANNER BY GEOGRAPHIC REGION

12.1 Global Handheld LiDAR 3D Scanner Market Size Forecast by Region

12.1.1 Global Handheld LiDAR 3D Scanner Forecast by Region (2027-2032)

12.1.2 Global Handheld LiDAR 3D Scanner Annual Revenue Forecast by Region (2027-2032)

12.2 Americas Forecast by Country (2027-2032)

12.3 APAC Forecast by Region (2027-2032)

12.4 Europe Forecast by Country (2027-2032)

12.5 Middle East & Africa Forecast by Country (2027-2032)

12.6 Global Handheld LiDAR 3D Scanner Forecast by Type (2027-2032)

12.7 Global Handheld LiDAR 3D Scanner Forecast by Application (2027-2032)

13 KEY PLAYERS ANALYSIS

13.1 Emesent Pty Ltd

13.1.1 Emesent Pty Ltd Company Information

13.1.2 Emesent Pty Ltd Handheld LiDAR 3D Scanner Product Portfolios and Specifications

13.1.3 Emesent Pty Ltd Handheld LiDAR 3D Scanner Sales, Revenue, Price and Gross Margin (2021-2026)

13.1.4 Emesent Pty Ltd Main Business Overview

13.1.5 Emesent Pty Ltd Latest Developments

13.2 GeoSLAM?Faro?

13.2.1 GeoSLAM?Faro? Company Information

13.2.2 GeoSLAM?Faro? Handheld LiDAR 3D Scanner Product Portfolios and Specifications

13.2.3 GeoSLAM?Faro? Handheld LiDAR 3D Scanner Sales, Revenue, Price and Gross Margin (2021-2026)

13.2.4 GeoSLAM?Faro? Main Business Overview

13.2.5 GeoSLAM?Faro? Latest Developments

13.3 Hexagon (Leica)

13.3.1 Hexagon (Leica) Company Information

13.3.2 Hexagon (Leica) Handheld LiDAR 3D Scanner Product Portfolios and Specifications

13.3.3 Hexagon (Leica) Handheld LiDAR 3D Scanner Sales, Revenue, Price and Gross Margin (2021-2026)

13.3.4 Hexagon (Leica) Main Business Overview

13.3.5 Hexagon (Leica) Latest Developments

13.4 Shenzhen Feima Robotics Technology Co., Ltd.

13.4.1 Shenzhen Feima Robotics Technology Co., Ltd. Company Information

13.4.2 Shenzhen Feima Robotics Technology Co., Ltd. Handheld LiDAR 3D Scanner Product Portfolios and Specifications

13.4.3 Shenzhen Feima Robotics Technology Co., Ltd. Handheld LiDAR 3D Scanner Sales, Revenue, Price and Gross Margin (2021-2026)

13.4.4 Shenzhen Feima Robotics Technology Co., Ltd. Main Business Overview

13.4.5 Shenzhen Feima Robotics Technology Co., Ltd. Latest Developments

13.5 GoSLAM

13.5.1 GoSLAM Company Information

13.5.2 GoSLAM Handheld LiDAR 3D Scanner Product Portfolios and Specifications

13.5.3 GoSLAM Handheld LiDAR 3D Scanner Sales, Revenue, Price and Gross Margin (2021-2026)

13.5.4 GoSLAM Main Business Overview

13.5.5 GoSLAM Latest Developments

13.6 Beijing Green Valley Technology. Co., Ltd.

13.6.1 Beijing Green Valley Technology. Co., Ltd. Company Information

13.6.2 Beijing Green Valley Technology. Co., Ltd. Handheld LiDAR 3D Scanner Product Portfolios and Specifications

13.6.3 Beijing Green Valley Technology. Co., Ltd. Handheld LiDAR 3D Scanner Sales, Revenue, Price and Gross Margin (2021-2026)

13.6.4 Beijing Green Valley Technology. Co., Ltd. Main Business Overview

13.6.5 Beijing Green Valley Technology. Co., Ltd. Latest Developments

13.7 FJ Dynamics Technology Co., Ltd.

13.7.1 FJ Dynamics Technology Co., Ltd. Company Information

13.7.2 FJ Dynamics Technology Co., Ltd. Handheld LiDAR 3D Scanner Product Portfolios and Specifications

13.7.3 FJ Dynamics Technology Co., Ltd. Handheld LiDAR 3D Scanner Sales, Revenue, Price and Gross Margin (2021-2026)

13.7.4 FJ Dynamics Technology Co., Ltd. Main Business Overview

13.7.5 FJ Dynamics Technology Co., Ltd. Latest Developments

13.8 Xgrids

13.8.1 Xgrids Company Information

13.8.2 Xgrids Handheld LiDAR 3D Scanner Product Portfolios and Specifications

13.8.3 Xgrids Handheld LiDAR 3D Scanner Sales, Revenue, Price and Gross Margin
(2021-2026)

13.8.4 Xgrids Main Business Overview

13.8.5 Xgrids Latest Developments

13.9 Stonex

13.9.1 Stonex Company Information

13.9.2 Stonex Handheld LiDAR 3D Scanner Product Portfolios and Specifications

13.9.3 Stonex Handheld LiDAR 3D Scanner Sales, Revenue, Price and Gross Margin
(2021-2026)

13.9.4 Stonex Main Business Overview

13.9.5 Stonex Latest Developments

14 RESEARCH FINDINGS AND CONCLUSION

List Of Tables

LIST OF TABLES

Table 1. Handheld LiDAR 3D Scanner Annual Sales CAGR by Geographic Region (2021, 2025 & 2032) & (\$ millions)

Table 2. Handheld LiDAR 3D Scanner Annual Sales CAGR by Country/Region (2021, 2025 & 2032) & (\$ millions)

Table 3. Major Players of Wired

Table 4. Major Players of Wireless

Table 5. Global Handheld LiDAR 3D Scanner Sales by Type (2021-2026) & (Units)

Table 6. Global Handheld LiDAR 3D Scanner Sales Market Share by Type (2021-2026)

Table 7. Global Handheld LiDAR 3D Scanner Revenue by Type (2021-2026) & (\$ million)

Table 8. Global Handheld LiDAR 3D Scanner Revenue Market Share by Type (2021-2026)

Table 9. Global Handheld LiDAR 3D Scanner Sale Price by Type (2021-2026) & (US\$/Unit)

Table 10. Global Handheld LiDAR 3D Scanner Sale by Application (2021-2026) & (Units)

Table 11. Global Handheld LiDAR 3D Scanner Sale Market Share by Application (2021-2026)

Table 12. Global Handheld LiDAR 3D Scanner Revenue by Application (2021-2026) & (\$ million)

Table 13. Global Handheld LiDAR 3D Scanner Revenue Market Share by Application (2021-2026)

Table 14. Global Handheld LiDAR 3D Scanner Sale Price by Application (2021-2026) & (US\$/Unit)

Table 15. Global Handheld LiDAR 3D Scanner Sales by Company (2021-2026) & (Units)

Table 16. Global Handheld LiDAR 3D Scanner Sales Market Share by Company (2021-2026)

Table 17. Global Handheld LiDAR 3D Scanner Revenue by Company (2021-2026) & (\$ millions)

Table 18. Global Handheld LiDAR 3D Scanner Revenue Market Share by Company (2021-2026)

Table 19. Global Handheld LiDAR 3D Scanner Sale Price by Company (2021-2026) & (US\$/Unit)

Table 20. Key Manufacturers Handheld LiDAR 3D Scanner Producing Area Distribution

and Sales Area

Table 21. Players Handheld LiDAR 3D Scanner Products Offered

Table 22. Handheld LiDAR 3D Scanner Concentration Ratio (CR3, CR5 and CR10) & (2024-2026)

Table 23. New Products and Potential Entrants

Table 24. Market M&A Activity & Strategy

Table 25. Global Handheld LiDAR 3D Scanner Sales by Geographic Region (2021-2026) & (Units)

Table 26. Global Handheld LiDAR 3D Scanner Sales Market Share Geographic Region (2021-2026)

Table 27. Global Handheld LiDAR 3D Scanner Revenue by Geographic Region (2021-2026) & (\$ millions)

Table 28. Global Handheld LiDAR 3D Scanner Revenue Market Share by Geographic Region (2021-2026)

Table 29. Global Handheld LiDAR 3D Scanner Sales by Country/Region (2021-2026) & (Units)

Table 30. Global Handheld LiDAR 3D Scanner Sales Market Share by Country/Region (2021-2026)

Table 31. Global Handheld LiDAR 3D Scanner Revenue by Country/Region (2021-2026) & (\$ millions)

Table 32. Global Handheld LiDAR 3D Scanner Revenue Market Share by Country/Region (2021-2026)

Table 33. Americas Handheld LiDAR 3D Scanner Sales by Country (2021-2026) & (Units)

Table 34. Americas Handheld LiDAR 3D Scanner Sales Market Share by Country (2021-2026)

Table 35. Americas Handheld LiDAR 3D Scanner Revenue by Country (2021-2026) & (\$ millions)

Table 36. Americas Handheld LiDAR 3D Scanner Sales by Type (2021-2026) & (Units)

Table 37. Americas Handheld LiDAR 3D Scanner Sales by Application (2021-2026) & (Units)

Table 38. APAC Handheld LiDAR 3D Scanner Sales by Region (2021-2026) & (Units)

Table 39. APAC Handheld LiDAR 3D Scanner Sales Market Share by Region (2021-2026)

Table 40. APAC Handheld LiDAR 3D Scanner Revenue by Region (2021-2026) & (\$ millions)

Table 41. APAC Handheld LiDAR 3D Scanner Sales by Type (2021-2026) & (Units)

Table 42. APAC Handheld LiDAR 3D Scanner Sales by Application (2021-2026) & (Units)

Table 43. Europe Handheld LiDAR 3D Scanner Sales by Country (2021-2026) & (Units)

Table 44. Europe Handheld LiDAR 3D Scanner Revenue by Country (2021-2026) & (\$ millions)

Table 45. Europe Handheld LiDAR 3D Scanner Sales by Type (2021-2026) & (Units)

Table 46. Europe Handheld LiDAR 3D Scanner Sales by Application (2021-2026) & (Units)

Table 47. Middle East & Africa Handheld LiDAR 3D Scanner Sales by Country (2021-2026) & (Units)

Table 48. Middle East & Africa Handheld LiDAR 3D Scanner Revenue Market Share by Country (2021-2026)

Table 49. Middle East & Africa Handheld LiDAR 3D Scanner Sales by Type (2021-2026) & (Units)

Table 50. Middle East & Africa Handheld LiDAR 3D Scanner Sales by Application (2021-2026) & (Units)

Table 51. Key Market Drivers & Growth Opportunities of Handheld LiDAR 3D Scanner

Table 52. Key Market Challenges & Risks of Handheld LiDAR 3D Scanner

Table 53. Key Industry Trends of Handheld LiDAR 3D Scanner

Table 54. Handheld LiDAR 3D Scanner Raw Material

Table 55. Key Suppliers of Raw Materials

Table 56. Handheld LiDAR 3D Scanner Distributors List

Table 57. Handheld LiDAR 3D Scanner Customer List

Table 58. Global Handheld LiDAR 3D Scanner Sales Forecast by Region (2027-2032) & (Units)

Table 59. Global Handheld LiDAR 3D Scanner Revenue Forecast by Region (2027-2032) & (\$ millions)

Table 60. Americas Handheld LiDAR 3D Scanner Sales Forecast by Country (2027-2032) & (Units)

Table 61. Americas Handheld LiDAR 3D Scanner Annual Revenue Forecast by Country (2027-2032) & (\$ millions)

Table 62. APAC Handheld LiDAR 3D Scanner Sales Forecast by Region (2027-2032) & (Units)

Table 63. APAC Handheld LiDAR 3D Scanner Annual Revenue Forecast by Region (2027-2032) & (\$ millions)

Table 64. Europe Handheld LiDAR 3D Scanner Sales Forecast by Country (2027-2032) & (Units)

Table 65. Europe Handheld LiDAR 3D Scanner Revenue Forecast by Country (2027-2032) & (\$ millions)

Table 66. Middle East & Africa Handheld LiDAR 3D Scanner Sales Forecast by Country (2027-2032) & (Units)

Table 67. Middle East & Africa Handheld LiDAR 3D Scanner Revenue Forecast by Country (2027-2032) & (\$ millions)

Table 68. Global Handheld LiDAR 3D Scanner Sales Forecast by Type (2027-2032) & (Units)

Table 69. Global Handheld LiDAR 3D Scanner Revenue Forecast by Type (2027-2032) & (\$ millions)

Table 70. Global Handheld LiDAR 3D Scanner Sales Forecast by Application (2027-2032) & (Units)

Table 71. Global Handheld LiDAR 3D Scanner Revenue Forecast by Application (2027-2032) & (\$ millions)

Table 72. Emesent Pty Ltd Basic Information, Handheld LiDAR 3D Scanner Manufacturing Base, Sales Area and Its Competitors

Table 73. Emesent Pty Ltd Handheld LiDAR 3D Scanner Product Portfolios and Specifications

Table 74. Emesent Pty Ltd Handheld LiDAR 3D Scanner Sales (Units), Revenue (\$ Million), Price (US\$/Unit) and Gross Margin (2021-2026)

Table 75. Emesent Pty Ltd Main Business

Table 76. Emesent Pty Ltd Latest Developments

Table 77. GeoSLAM?Faro? Basic Information, Handheld LiDAR 3D Scanner Manufacturing Base, Sales Area and Its Competitors

Table 78. GeoSLAM?Faro? Handheld LiDAR 3D Scanner Product Portfolios and Specifications

Table 79. GeoSLAM?Faro? Handheld LiDAR 3D Scanner Sales (Units), Revenue (\$ Million), Price (US\$/Unit) and Gross Margin (2021-2026)

Table 80. GeoSLAM?Faro? Main Business

Table 81. GeoSLAM?Faro? Latest Developments

Table 82. Hexagon (Leica) Basic Information, Handheld LiDAR 3D Scanner Manufacturing Base, Sales Area and Its Competitors

Table 83. Hexagon (Leica) Handheld LiDAR 3D Scanner Product Portfolios and Specifications

Table 84. Hexagon (Leica) Handheld LiDAR 3D Scanner Sales (Units), Revenue (\$ Million), Price (US\$/Unit) and Gross Margin (2021-2026)

Table 85. Hexagon (Leica) Main Business

Table 86. Hexagon (Leica) Latest Developments

Table 87. Shenzhen Feima Robotics Technology Co., Ltd. Basic Information, Handheld LiDAR 3D Scanner Manufacturing Base, Sales Area and Its Competitors

Table 88. Shenzhen Feima Robotics Technology Co., Ltd. Handheld LiDAR 3D Scanner Product Portfolios and Specifications

Table 89. Shenzhen Feima Robotics Technology Co., Ltd. Handheld LiDAR 3D Scanner

Sales (Units), Revenue (\$ Million), Price (US\$/Unit) and Gross Margin (2021-2026)

Table 90. Shenzhen Feima Robotics Technology Co., Ltd. Main Business

Table 91. Shenzhen Feima Robotics Technology Co., Ltd. Latest Developments

Table 92. GoSLAM Basic Information, Handheld LiDAR 3D Scanner Manufacturing Base, Sales Area and Its Competitors

Table 93. GoSLAM Handheld LiDAR 3D Scanner Product Portfolios and Specifications

Table 94. GoSLAM Handheld LiDAR 3D Scanner Sales (Units), Revenue (\$ Million), Price (US\$/Unit) and Gross Margin (2021-2026)

Table 95. GoSLAM Main Business

Table 96. GoSLAM Latest Developments

Table 97. Beijing Green Valley Technology. Co., Ltd. Basic Information, Handheld LiDAR 3D Scanner Manufacturing Base, Sales Area and Its Competitors

Table 98. Beijing Green Valley Technology. Co., Ltd. Handheld LiDAR 3D Scanner Product Portfolios and Specifications

Table 99. Beijing Green Valley Technology. Co., Ltd. Handheld LiDAR 3D Scanner Sales (Units), Revenue (\$ Million), Price (US\$/Unit) and Gross Margin (2021-2026)

Table 100. Beijing Green Valley Technology. Co., Ltd. Main Business

Table 101. Beijing Green Valley Technology. Co., Ltd. Latest Developments

Table 102. FJ Dynamics Technology Co., Ltd. Basic Information, Handheld LiDAR 3D Scanner Manufacturing Base, Sales Area and Its Competitors

Table 103. FJ Dynamics Technology Co., Ltd. Handheld LiDAR 3D Scanner Product Portfolios and Specifications

Table 104. FJ Dynamics Technology Co., Ltd. Handheld LiDAR 3D Scanner Sales (Units), Revenue (\$ Million), Price (US\$/Unit) and Gross Margin (2021-2026)

Table 105. FJ Dynamics Technology Co., Ltd. Main Business

Table 106. FJ Dynamics Technology Co., Ltd. Latest Developments

Table 107. Xgrids Basic Information, Handheld LiDAR 3D Scanner Manufacturing Base, Sales Area and Its Competitors

Table 108. Xgrids Handheld LiDAR 3D Scanner Product Portfolios and Specifications

Table 109. Xgrids Handheld LiDAR 3D Scanner Sales (Units), Revenue (\$ Million), Price (US\$/Unit) and Gross Margin (2021-2026)

Table 110. Xgrids Main Business

Table 111. Xgrids Latest Developments

Table 112. Stonex Basic Information, Handheld LiDAR 3D Scanner Manufacturing Base, Sales Area and Its Competitors

Table 113. Stonex Handheld LiDAR 3D Scanner Product Portfolios and Specifications

Table 114. Stonex Handheld LiDAR 3D Scanner Sales (Units), Revenue (\$ Million), Price (US\$/Unit) and Gross Margin (2021-2026)

Table 115. Stonex Main Business

Table 116. Stonex Latest Developments

List Of Figures

LIST OF FIGURES

- Figure 1. Picture of Handheld LiDAR 3D Scanner
- Figure 2. Handheld LiDAR 3D Scanner Report Years Considered
- Figure 3. Research Objectives
- Figure 4. Research Methodology
- Figure 5. Research Process and Data Source
- Figure 6. Global Handheld LiDAR 3D Scanner Sales Growth Rate 2021-2032 (Units)
- Figure 7. Global Handheld LiDAR 3D Scanner Revenue Growth Rate 2021-2032 (\$ millions)
- Figure 8. Handheld LiDAR 3D Scanner Sales by Geographic Region (2021, 2025 & 2032) & (\$ millions)
- Figure 9. Handheld LiDAR 3D Scanner Sales Market Share by Country/Region (2025)
- Figure 10. Handheld LiDAR 3D Scanner Sales Market Share by Country/Region (2021, 2025 & 2032)
- Figure 11. Product Picture of Wired
- Figure 12. Product Picture of Wireless
- Figure 13. Global Handheld LiDAR 3D Scanner Sales Market Share by Type in 2026
- Figure 14. Global Handheld LiDAR 3D Scanner Revenue Market Share by Type (2021-2026)
- Figure 15. Handheld LiDAR 3D Scanner Consumed in Industrial Design and Manufacturing
- Figure 16. Global Handheld LiDAR 3D Scanner Market: Industrial Design and Manufacturing (2021-2026) & (Units)
- Figure 17. Handheld LiDAR 3D Scanner Consumed in Car Traffic
- Figure 18. Global Handheld LiDAR 3D Scanner Market: Car Traffic (2021-2026) & (Units)
- Figure 19. Handheld LiDAR 3D Scanner Consumed in Aviation and Aerospace
- Figure 20. Global Handheld LiDAR 3D Scanner Market: Aviation and Aerospace (2021-2026) & (Units)
- Figure 21. Handheld LiDAR 3D Scanner Consumed in Teaching and Scientific Research
- Figure 22. Global Handheld LiDAR 3D Scanner Market: Teaching and Scientific Research (2021-2026) & (Units)
- Figure 23. Handheld LiDAR 3D Scanner Consumed in Factory Digitization
- Figure 24. Global Handheld LiDAR 3D Scanner Market: Factory Digitization (2021-2026) & (Units)

Figure 25. Handheld LiDAR 3D Scanner Consumed in Digital Twin

Figure 26. Global Handheld LiDAR 3D Scanner Market: Digital Twin (2021-2026) & (Units)

Figure 27. Handheld LiDAR 3D Scanner Consumed in Architectural Design

Figure 28. Global Handheld LiDAR 3D Scanner Market: Architectural Design (2021-2026) & (Units)

Figure 29. Handheld LiDAR 3D Scanner Consumed in City Renewal

Figure 30. Global Handheld LiDAR 3D Scanner Market: City Renewal (2021-2026) & (Units)

Figure 31. Handheld LiDAR 3D Scanner Consumed in Other

Figure 32. Global Handheld LiDAR 3D Scanner Market: Other (2021-2026) & (Units)

Figure 33. Global Handheld LiDAR 3D Scanner Sale Market Share by Application (2025)

Figure 34. Global Handheld LiDAR 3D Scanner Revenue Market Share by Application in 2026

Figure 35. Handheld LiDAR 3D Scanner Sales by Company in 2026 (Units)

Figure 36. Global Handheld LiDAR 3D Scanner Sales Market Share by Company in 2026

Figure 37. Handheld LiDAR 3D Scanner Revenue by Company in 2026 (\$ millions)

Figure 38. Global Handheld LiDAR 3D Scanner Revenue Market Share by Company in 2026

Figure 39. Global Handheld LiDAR 3D Scanner Sales Market Share by Geographic Region (2021-2026)

Figure 40. Global Handheld LiDAR 3D Scanner Revenue Market Share by Geographic Region in 2026

Figure 41. Americas Handheld LiDAR 3D Scanner Sales 2021-2026 (Units)

Figure 42. Americas Handheld LiDAR 3D Scanner Revenue 2021-2026 (\$ millions)

Figure 43. APAC Handheld LiDAR 3D Scanner Sales 2021-2026 (Units)

Figure 44. APAC Handheld LiDAR 3D Scanner Revenue 2021-2026 (\$ millions)

Figure 45. Europe Handheld LiDAR 3D Scanner Sales 2021-2026 (Units)

Figure 46. Europe Handheld LiDAR 3D Scanner Revenue 2021-2026 (\$ millions)

Figure 47. Middle East & Africa Handheld LiDAR 3D Scanner Sales 2021-2026 (Units)

Figure 48. Middle East & Africa Handheld LiDAR 3D Scanner Revenue 2021-2026 (\$ millions)

Figure 49. Americas Handheld LiDAR 3D Scanner Sales Market Share by Country in 2026

Figure 50. Americas Handheld LiDAR 3D Scanner Revenue Market Share by Country (2021-2026)

Figure 51. Americas Handheld LiDAR 3D Scanner Sales Market Share by Type

(2021-2026)

Figure 52. Americas Handheld LiDAR 3D Scanner Sales Market Share by Application (2021-2026)

Figure 53. United States Handheld LiDAR 3D Scanner Revenue Growth 2021-2026 (\$ millions)

Figure 54. Canada Handheld LiDAR 3D Scanner Revenue Growth 2021-2026 (\$ millions)

Figure 55. Mexico Handheld LiDAR 3D Scanner Revenue Growth 2021-2026 (\$ millions)

Figure 56. Brazil Handheld LiDAR 3D Scanner Revenue Growth 2021-2026 (\$ millions)

Figure 57. APAC Handheld LiDAR 3D Scanner Sales Market Share by Region in 2026

Figure 58. APAC Handheld LiDAR 3D Scanner Revenue Market Share by Region (2021-2026)

Figure 59. APAC Handheld LiDAR 3D Scanner Sales Market Share by Type (2021-2026)

Figure 60. APAC Handheld LiDAR 3D Scanner Sales Market Share by Application (2021-2026)

Figure 61. China Handheld LiDAR 3D Scanner Revenue Growth 2021-2026 (\$ millions)

Figure 62. Japan Handheld LiDAR 3D Scanner Revenue Growth 2021-2026 (\$ millions)

Figure 63. South Korea Handheld LiDAR 3D Scanner Revenue Growth 2021-2026 (\$ millions)

Figure 64. Southeast Asia Handheld LiDAR 3D Scanner Revenue Growth 2021-2026 (\$ millions)

Figure 65. India Handheld LiDAR 3D Scanner Revenue Growth 2021-2026 (\$ millions)

Figure 66. Australia Handheld LiDAR 3D Scanner Revenue Growth 2021-2026 (\$ millions)

Figure 67. China Taiwan Handheld LiDAR 3D Scanner Revenue Growth 2021-2026 (\$ millions)

Figure 68. Europe Handheld LiDAR 3D Scanner Sales Market Share by Country in 2026

Figure 69. Europe Handheld LiDAR 3D Scanner Revenue Market Share by Country (2021-2026)

Figure 70. Europe Handheld LiDAR 3D Scanner Sales Market Share by Type (2021-2026)

Figure 71. Europe Handheld LiDAR 3D Scanner Sales Market Share by Application (2021-2026)

Figure 72. Germany Handheld LiDAR 3D Scanner Revenue Growth 2021-2026 (\$ millions)

Figure 73. France Handheld LiDAR 3D Scanner Revenue Growth 2021-2026 (\$

millions)

Figure 74. UK Handheld LiDAR 3D Scanner Revenue Growth 2021-2026 (\$ millions)

Figure 75. Italy Handheld LiDAR 3D Scanner Revenue Growth 2021-2026 (\$ millions)

Figure 76. Russia Handheld LiDAR 3D Scanner Revenue Growth 2021-2026 (\$ millions)

Figure 77. Middle East & Africa Handheld LiDAR 3D Scanner Sales Market Share by Country (2021-2026)

Figure 78. Middle East & Africa Handheld LiDAR 3D Scanner Sales Market Share by Type (2021-2026)

Figure 79. Middle East & Africa Handheld LiDAR 3D Scanner Sales Market Share by Application (2021-2026)

Figure 80. Egypt Handheld LiDAR 3D Scanner Revenue Growth 2021-2026 (\$ millions)

Figure 81. South Africa Handheld LiDAR 3D Scanner Revenue Growth 2021-2026 (\$ millions)

Figure 82. Israel Handheld LiDAR 3D Scanner Revenue Growth 2021-2026 (\$ millions)

Figure 83. Turkey Handheld LiDAR 3D Scanner Revenue Growth 2021-2026 (\$ millions)

Figure 84. GCC Countries Handheld LiDAR 3D Scanner Revenue Growth 2021-2026 (\$ millions)

Figure 85. Manufacturing Cost Structure Analysis of Handheld LiDAR 3D Scanner in 2026

Figure 86. Manufacturing Process Analysis of Handheld LiDAR 3D Scanner

Figure 87. Industry Chain Structure of Handheld LiDAR 3D Scanner

Figure 88. Channels of Distribution

Figure 89. Global Handheld LiDAR 3D Scanner Sales Market Forecast by Region (2027-2032)

Figure 90. Global Handheld LiDAR 3D Scanner Revenue Market Share Forecast by Region (2027-2032)

Figure 91. Global Handheld LiDAR 3D Scanner Sales Market Share Forecast by Type (2027-2032)

Figure 92. Global Handheld LiDAR 3D Scanner Revenue Market Share Forecast by Type (2027-2032)

Figure 93. Global Handheld LiDAR 3D Scanner Sales Market Share Forecast by Application (2027-2032)

Figure 94. Global Handheld LiDAR 3D Scanner Revenue Market Share Forecast by Application (2027-2032)

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