

Global Direct-Drive Dexterous Hands Market Growth 2026-2032

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Abstracts

The global Direct-Drive Dexterous Hands market size is predicted to grow from US\$ 171 million in 2025 to US\$ 507 million in 2032; it is expected to grow at a CAGR of 16.9% from 2026 to 2032.

A direct-drive dexterous hand is a multi-degree-of-freedom robotic end effector that directly drives finger joint movements with motors, without relying on ropes, reducers, or complex mechanical transmission mechanisms. This product integrates micro-motors, torque motors, or frameless motors directly near the finger joints to achieve finger flexion, extension, rotation, grasping, and fine manipulation.

In 2025, global sales of direct-drive dexterous hands reached 19,000 units, with a production capacity of approximately 26,000 units. The average selling price was \$9,210 per unit, and the average gross profit margin was 35%-45%.

Direct-drive dexterous hands employ an integrated motor-joint drive system, resulting in a shorter drive force path. This reduces transmission errors and mechanical losses, improving response speed, control accuracy, and dynamic performance. Key features include compact structure, fast response speed, high control accuracy, good force control performance, and high reliability, making them suitable for humanoid robots, collaborative robots, medical robots, and high-precision operation scenarios.

The upstream of the industry chain mainly includes the supply of core components and basic materials, involving micro direct-drive motors, frameless torque motors, encoders, torque sensors, drive chips, controllers, high-performance magnetic materials (such as neodymium iron boron permanent magnets), lightweight metal materials, and engineering plastics. Among these, high-torque-density motors, precision sensors, and

high-performance control chips are key to product performance. The midstream involves the design, manufacturing, and system integration of direct-drive dexterous hands. Companies integrate multiple direct-drive joint modules into a bionic robot hand execution system through mechanical structure design, motor and joint integration, multi-degree-of-freedom motion control, sensor system fusion, and algorithm development, achieving precise grasping, force-controlled interaction, and complex operations. The downstream is mainly applied in humanoid robots, collaborative robots, medical robots, remote-controlled robots, scientific research and education robots, and industrial flexible manufacturing. Among these, humanoid robots and embodied intelligent robots are the application directions with the greatest growth potential in the future. As robots increasingly demand high dynamic response, high-precision control, and natural interaction capabilities, the direct-drive dexterous hand industry chain will further develop towards high-power-density motors, intelligent sensing, multi-modal control, and modular mass production.

The technological development of direct-drive dexterous hands focuses on achieving high torque density, miniaturization, high degrees of freedom, low-latency control, and multimodal sensing capabilities. While early robotic dexterous hands predominantly utilized cable-driven or gear-reduction mechanisms, direct-drive solutions integrate motors directly into the joints to deliver power. This approach minimizes mechanical transmission errors while enhancing motion response speed and control precision. Current products primarily employ micro brushless motors, frameless torque motors, or quasi-direct-drive technology, combined with encoders, torque sensors, and tactile sensors to enable integrated control of position, force, and contact states. Looking ahead, direct-drive dexterous hands will evolve toward modular joint designs, the use of lightweight materials, AI-driven motion control, and hardware-software integration to meet the demands of large-scale humanoid robot deployment.

Driven by policies supporting artificial intelligence, intelligent manufacturing, and advanced manufacturing, the global robotics industry is expanding rapidly. As a core actuation component of humanoid robots, the direct-drive dexterous hand has attracted significant attention from industrial capital and robotics enterprises. China continues to foster innovation in the robotics sector and the development of the humanoid robot industry, creating growth opportunities for manufacturers of core components such as dexterous hands, motors, and sensors; meanwhile, the United States and Europe are focusing their efforts on the integrated application of AI and robotics.

Report Scope

LP Information, Inc. (LPI) ' newest research report, the “Direct-Drive Dexterous Hands Industry Forecast” looks at past sales and reviews total world Direct-Drive Dexterous Hands sales in 2025, providing a comprehensive analysis by region and market sector of projected Direct-Drive Dexterous Hands sales for 2026 through 2032. With Direct-Drive Dexterous Hands sales broken down by region, market sector and sub-sector, this report provides a detailed analysis in US\$ millions of the world Direct-Drive Dexterous Hands industry.

This Insight Report provides a comprehensive analysis of the global Direct-Drive Dexterous Hands landscape and highlights key trends related to product segmentation, company formation, revenue, and market share, latest development, and M&A activity. This report also analyzes the strategies of leading global companies with a focus on Direct-Drive Dexterous Hands portfolios and capabilities, market entry strategies, market positions, and geographic footprints, to better understand these firms' unique position in an accelerating global Direct-Drive Dexterous Hands market.

This Insight Report evaluates the key market trends, drivers, and affecting factors shaping the global outlook for Direct-Drive Dexterous Hands and breaks down the forecast by Type, by Application, geography, and market size to highlight emerging pockets of opportunity. With a transparent methodology based on hundreds of bottom-up qualitative and quantitative market inputs, this study forecast offers a highly nuanced view of the current state and future trajectory in the global Direct-Drive Dexterous Hands.

This report presents a comprehensive overview, market shares, and growth opportunities of Direct-Drive Dexterous Hands market by product type, application, key manufacturers and key regions and countries.

Segmentation by Type:

Direct Motor Drive

Motor + Gearbox Drive

Segmentation by Degrees of Freedom:

5–10 DoF

10–20 DoF

?20 DoF

Segmentation by Application:

Humanoid Robot

Collaborative Robot

Medical Robot

Others

This report also splits the market by region:

Americas

United States

Canada

Mexico

Brazil

APAC

China

Japan

Korea

Southeast Asia

India

Australia

Europe

Germany

France

UK

Italy

Russia

Middle East & Africa

Egypt

South Africa

Israel

Turkey

GCC Countries

The below companies that are profiled have been selected based on inputs gathered from primary experts and analysing the company's coverage, product portfolio, its market penetration.

Shadow Robot

Tesla

Wonik Robotics? Allegro Hand?

SharpWave

RoboterA

WUJI TECH

Zhaowei Electromechanical

LinkerBot

Unitree

Agibot

Leadshine

BrainCo

Xynova

Key Questions Addressed in this Report

What is the 10-year outlook for the global Direct-Drive Dexterous Hands market?

What factors are driving Direct-Drive Dexterous Hands market growth, globally and by region?

Which technologies are poised for the fastest growth by market and region?

How do Direct-Drive Dexterous Hands market opportunities vary by end market size?

How does Direct-Drive Dexterous Hands break out by Type, by Application?

Contents

1 SCOPE OF THE REPORT

- 1.1 Market Introduction
- 1.2 Years Considered
- 1.3 Research Objectives
- 1.4 Market Research Methodology
- 1.5 Research Process and Data Source
- 1.6 Economic Indicators
- 1.7 Currency Considered
- 1.8 Market Estimation Caveats

2 EXECUTIVE SUMMARY

2.1 World Market Overview

- 2.1.1 Global Direct-Drive Dexterous Hands Annual Sales 2021-2032
- 2.1.2 World Current & Future Analysis for Direct-Drive Dexterous Hands by Geographic Region, 2021, 2025 & 2032
- 2.1.3 World Current & Future Analysis for Direct-Drive Dexterous Hands by Country/Region, 2021, 2025 & 2032
- 2.2 Direct-Drive Dexterous Hands Segment by Type
 - 2.2.1 Direct Motor Drive
 - 2.2.2 Motor + Gearbox Drive
 - 2.2.3 Direct-Drive Dexterous Hands Sales by Type
 - 2.2.3.1 Global Direct-Drive Dexterous Hands Sales Market Share by Type (2021-2026)
 - 2.2.3.2 Global Direct-Drive Dexterous Hands Revenue and Market Share by Type (2021-2026)
 - 2.2.3.3 Global Direct-Drive Dexterous Hands Sale Price by Type (2021-2026)
- 2.3 Direct-Drive Dexterous Hands Segment by Degrees of Freedom
 - 2.3.1 5–10 DoF
 - 2.3.2 10–20 DoF
 - 2.3.3 ?20 DoF
 - 2.3.4 Direct-Drive Dexterous Hands Sales by Degrees of Freedom
 - 2.3.4.1 Global Direct-Drive Dexterous Hands Sales Market Share by Degrees of Freedom (2021-2026)
 - 2.3.4.2 Global Direct-Drive Dexterous Hands Revenue and Market Share by Degrees of Freedom (2021-2026)

2.3.4.3 Global Direct-Drive Dexterous Hands Sale Price by Degrees of Freedom (2021-2026)

2.4 Direct-Drive Dexterous Hands Segment by Application

2.4.1 Humanoid Robot

2.4.2 Collaborative Robot

2.4.3 Medical Robot

2.4.4 Others

2.4.5 Direct-Drive Dexterous Hands Sales by Application

2.4.5.1 Global Direct-Drive Dexterous Hands Sale Market Share by Application (2021-2026)

2.4.5.2 Global Direct-Drive Dexterous Hands Revenue and Market Share by Application (2021-2026)

2.4.5.3 Global Direct-Drive Dexterous Hands Sale Price by Application (2021-2026)

3 GLOBAL BY COMPANY

3.1 Global Direct-Drive Dexterous Hands Breakdown Data by Company

3.1.1 Global Direct-Drive Dexterous Hands Annual Sales by Company (2021-2026)

3.1.2 Global Direct-Drive Dexterous Hands Sales Market Share by Company (2021-2026)

3.2 Global Direct-Drive Dexterous Hands Annual Revenue by Company (2021-2026)

3.2.1 Global Direct-Drive Dexterous Hands Revenue by Company (2021-2026)

3.2.2 Global Direct-Drive Dexterous Hands Revenue Market Share by Company (2021-2026)

3.3 Global Direct-Drive Dexterous Hands Sale Price by Company

3.4 Key Manufacturers Direct-Drive Dexterous Hands Producing Area Distribution, Sales Area, Product Type

3.4.1 Key Manufacturers Direct-Drive Dexterous Hands Product Location Distribution

3.4.2 Players Direct-Drive Dexterous Hands Products Offered

3.5 Market Concentration Rate Analysis

3.5.1 Competition Landscape Analysis

3.5.2 Concentration Ratio (CR3, CR5 and CR10) & (2024-2026)

3.6 New Products and Potential Entrants

3.7 Market M&A Activity & Strategy

4 WORLD HISTORIC REVIEW FOR DIRECT-DRIVE DEXTEROUS HANDS BY GEOGRAPHIC REGION

4.1 World Historic Direct-Drive Dexterous Hands Market Size by Geographic Region

(2021-2026)

4.1.1 Global Direct-Drive Dexterous Hands Annual Sales by Geographic Region

(2021-2026)

4.1.2 Global Direct-Drive Dexterous Hands Annual Revenue by Geographic Region

(2021-2026)

4.2 World Historic Direct-Drive Dexterous Hands Market Size by Country/Region

(2021-2026)

4.2.1 Global Direct-Drive Dexterous Hands Annual Sales by Country/Region

(2021-2026)

4.2.2 Global Direct-Drive Dexterous Hands Annual Revenue by Country/Region

(2021-2026)

4.3 Americas Direct-Drive Dexterous Hands Sales Growth

4.4 APAC Direct-Drive Dexterous Hands Sales Growth

4.5 Europe Direct-Drive Dexterous Hands Sales Growth

4.6 Middle East & Africa Direct-Drive Dexterous Hands Sales Growth

5 AMERICAS

5.1 Americas Direct-Drive Dexterous Hands Sales by Country

5.1.1 Americas Direct-Drive Dexterous Hands Sales by Country (2021-2026)

5.1.2 Americas Direct-Drive Dexterous Hands Revenue by Country (2021-2026)

5.2 Americas Direct-Drive Dexterous Hands Sales by Type (2021-2026)

5.3 Americas Direct-Drive Dexterous Hands Sales by Application (2021-2026)

5.4 United States

5.5 Canada

5.6 Mexico

5.7 Brazil

6 APAC

6.1 APAC Direct-Drive Dexterous Hands Sales by Region

6.1.1 APAC Direct-Drive Dexterous Hands Sales by Region (2021-2026)

6.1.2 APAC Direct-Drive Dexterous Hands Revenue by Region (2021-2026)

6.2 APAC Direct-Drive Dexterous Hands Sales by Type (2021-2026)

6.3 APAC Direct-Drive Dexterous Hands Sales by Application (2021-2026)

6.4 China

6.5 Japan

6.6 South Korea

6.7 Southeast Asia

- 6.8 India
- 6.9 Australia
- 6.10 China Taiwan

7 EUROPE

- 7.1 Europe Direct-Drive Dexterous Hands by Country
 - 7.1.1 Europe Direct-Drive Dexterous Hands Sales by Country (2021-2026)
 - 7.1.2 Europe Direct-Drive Dexterous Hands Revenue by Country (2021-2026)
- 7.2 Europe Direct-Drive Dexterous Hands Sales by Type (2021-2026)
- 7.3 Europe Direct-Drive Dexterous Hands Sales by Application (2021-2026)
- 7.4 Germany
- 7.5 France
- 7.6 UK
- 7.7 Italy
- 7.8 Russia

8 MIDDLE EAST & AFRICA

- 8.1 Middle East & Africa Direct-Drive Dexterous Hands by Country
 - 8.1.1 Middle East & Africa Direct-Drive Dexterous Hands Sales by Country (2021-2026)
 - 8.1.2 Middle East & Africa Direct-Drive Dexterous Hands Revenue by Country (2021-2026)
- 8.2 Middle East & Africa Direct-Drive Dexterous Hands Sales by Type (2021-2026)
- 8.3 Middle East & Africa Direct-Drive Dexterous Hands Sales by Application (2021-2026)
- 8.4 Egypt
- 8.5 South Africa
- 8.6 Israel
- 8.7 Turkey
- 8.8 GCC Countries

9 MARKET DRIVERS, CHALLENGES AND TRENDS

- 9.1 Market Drivers & Growth Opportunities
- 9.2 Market Challenges & Risks
- 9.3 Industry Trends

10 MANUFACTURING COST STRUCTURE ANALYSIS

- 10.1 Raw Material and Suppliers
- 10.2 Manufacturing Cost Structure Analysis of Direct-Drive Dexterous Hands
- 10.3 Manufacturing Process Analysis of Direct-Drive Dexterous Hands
- 10.4 Industry Chain Structure of Direct-Drive Dexterous Hands

11 MARKETING, DISTRIBUTORS AND CUSTOMER

- 11.1 Sales Channel
 - 11.1.1 Direct Channels
 - 11.1.2 Indirect Channels
- 11.2 Direct-Drive Dexterous Hands Distributors
- 11.3 Direct-Drive Dexterous Hands Customer

12 WORLD FORECAST REVIEW FOR DIRECT-DRIVE DEXTEROUS HANDS BY GEOGRAPHIC REGION

- 12.1 Global Direct-Drive Dexterous Hands Market Size Forecast by Region
 - 12.1.1 Global Direct-Drive Dexterous Hands Forecast by Region (2027-2032)
 - 12.1.2 Global Direct-Drive Dexterous Hands Annual Revenue Forecast by Region (2027-2032)
- 12.2 Americas Forecast by Country (2027-2032)
- 12.3 APAC Forecast by Region (2027-2032)
- 12.4 Europe Forecast by Country (2027-2032)
- 12.5 Middle East & Africa Forecast by Country (2027-2032)
- 12.6 Global Direct-Drive Dexterous Hands Forecast by Type (2027-2032)
- 12.7 Global Direct-Drive Dexterous Hands Forecast by Application (2027-2032)

13 KEY PLAYERS ANALYSIS

- 13.1 Shadow Robot
 - 13.1.1 Shadow Robot Company Information
 - 13.1.2 Shadow Robot Direct-Drive Dexterous Hands Product Portfolios and Specifications
 - 13.1.3 Shadow Robot Direct-Drive Dexterous Hands Sales, Revenue, Price and Gross Margin (2021-2026)
 - 13.1.4 Shadow Robot Main Business Overview
 - 13.1.5 Shadow Robot Latest Developments

13.2 Tesla

13.2.1 Tesla Company Information

13.2.2 Tesla Direct-Drive Dexterous Hands Product Portfolios and Specifications

13.2.3 Tesla Direct-Drive Dexterous Hands Sales, Revenue, Price and Gross Margin (2021-2026)

13.2.4 Tesla Main Business Overview

13.2.5 Tesla Latest Developments

13.3 Wonik Robotics?Allegro Hand?

13.3.1 Wonik Robotics?Allegro Hand? Company Information

13.3.2 Wonik Robotics?Allegro Hand? Direct-Drive Dexterous Hands Product Portfolios and Specifications

13.3.3 Wonik Robotics?Allegro Hand? Direct-Drive Dexterous Hands Sales, Revenue, Price and Gross Margin (2021-2026)

13.3.4 Wonik Robotics?Allegro Hand? Main Business Overview

13.3.5 Wonik Robotics?Allegro Hand? Latest Developments

13.4 SharpWave

13.4.1 SharpWave Company Information

13.4.2 SharpWave Direct-Drive Dexterous Hands Product Portfolios and Specifications

13.4.3 SharpWave Direct-Drive Dexterous Hands Sales, Revenue, Price and Gross Margin (2021-2026)

13.4.4 SharpWave Main Business Overview

13.4.5 SharpWave Latest Developments

13.5 Robotera

13.5.1 Robotera Company Information

13.5.2 Robotera Direct-Drive Dexterous Hands Product Portfolios and Specifications

13.5.3 Robotera Direct-Drive Dexterous Hands Sales, Revenue, Price and Gross Margin (2021-2026)

13.5.4 Robotera Main Business Overview

13.5.5 Robotera Latest Developments

13.6 WUJI TECH

13.6.1 WUJI TECH Company Information

13.6.2 WUJI TECH Direct-Drive Dexterous Hands Product Portfolios and Specifications

13.6.3 WUJI TECH Direct-Drive Dexterous Hands Sales, Revenue, Price and Gross Margin (2021-2026)

13.6.4 WUJI TECH Main Business Overview

13.6.5 WUJI TECH Latest Developments

13.7 Zhaowei Electromechanical

13.7.1 Zhaowei Electromechanical Company Information

13.7.2 Zhaowei Electromechanical Direct-Drive Dexterous Hands Product Portfolios and Specifications

13.7.3 Zhaowei Electromechanical Direct-Drive Dexterous Hands Sales, Revenue, Price and Gross Margin (2021-2026)

13.7.4 Zhaowei Electromechanical Main Business Overview

13.7.5 Zhaowei Electromechanical Latest Developments

13.8 LinkerBot

13.8.1 LinkerBot Company Information

13.8.2 LinkerBot Direct-Drive Dexterous Hands Product Portfolios and Specifications

13.8.3 LinkerBot Direct-Drive Dexterous Hands Sales, Revenue, Price and Gross Margin (2021-2026)

13.8.4 LinkerBot Main Business Overview

13.8.5 LinkerBot Latest Developments

13.9 Unitree

13.9.1 Unitree Company Information

13.9.2 Unitree Direct-Drive Dexterous Hands Product Portfolios and Specifications

13.9.3 Unitree Direct-Drive Dexterous Hands Sales, Revenue, Price and Gross Margin (2021-2026)

13.9.4 Unitree Main Business Overview

13.9.5 Unitree Latest Developments

13.10 Agibot

13.10.1 Agibot Company Information

13.10.2 Agibot Direct-Drive Dexterous Hands Product Portfolios and Specifications

13.10.3 Agibot Direct-Drive Dexterous Hands Sales, Revenue, Price and Gross Margin (2021-2026)

13.10.4 Agibot Main Business Overview

13.10.5 Agibot Latest Developments

13.11 Leadshine

13.11.1 Leadshine Company Information

13.11.2 Leadshine Direct-Drive Dexterous Hands Product Portfolios and Specifications

13.11.3 Leadshine Direct-Drive Dexterous Hands Sales, Revenue, Price and Gross Margin (2021-2026)

13.11.4 Leadshine Main Business Overview

13.11.5 Leadshine Latest Developments

13.12 BrainCo

13.12.1 BrainCo Company Information

13.12.2 BrainCo Direct-Drive Dexterous Hands Product Portfolios and Specifications

13.12.3 BrainCo Direct-Drive Dexterous Hands Sales, Revenue, Price and Gross Margin (2021-2026)

13.12.4 BrainCo Main Business Overview

13.12.5 BrainCo Latest Developments

13.13 Xynova

13.13.1 Xynova Company Information

13.13.2 Xynova Direct-Drive Dexterous Hands Product Portfolios and Specifications

13.13.3 Xynova Direct-Drive Dexterous Hands Sales, Revenue, Price and Gross
Margin (2021-2026)

13.13.4 Xynova Main Business Overview

13.13.5 Xynova Latest Developments

14 RESEARCH FINDINGS AND CONCLUSION

List Of Tables

LIST OF TABLES

Table 1. Direct-Drive Dexterous Hands Annual Sales CAGR by Geographic Region (2021, 2025 & 2032) & (\$ millions)

Table 2. Direct-Drive Dexterous Hands Annual Sales CAGR by Country/Region (2021, 2025 & 2032) & (\$ millions)

Table 3. Major Players of Direct Motor Drive

Table 4. Major Players of Motor + Gearbox Drive

Table 5. Global Direct-Drive Dexterous Hands Sales by Type (2021-2026) & (Units)

Table 6. Global Direct-Drive Dexterous Hands Sales Market Share by Type (2021-2026)

Table 7. Global Direct-Drive Dexterous Hands Revenue by Type (2021-2026) & (\$ million)

Table 8. Global Direct-Drive Dexterous Hands Revenue Market Share by Type (2021-2026)

Table 9. Global Direct-Drive Dexterous Hands Sale Price by Type (2021-2026) & (US\$/Unit)

Table 10. Major Players of 5–10 DoF

Table 11. Major Players of 10–20 DoF

Table 12. Major Players of ?20 DoF

Table 13. Global Direct-Drive Dexterous Hands Sales by Degrees of Freedom (2021-2026) & (Units)

Table 14. Global Direct-Drive Dexterous Hands Sales Market Share by Degrees of Freedom (2021-2026)

Table 15. Global Direct-Drive Dexterous Hands Revenue by Degrees of Freedom (2021-2026) & (\$ million)

Table 16. Global Direct-Drive Dexterous Hands Revenue Market Share by Degrees of Freedom (2021-2026)

Table 17. Global Direct-Drive Dexterous Hands Sale Price by Degrees of Freedom (2021-2026) & (US\$/Unit)

Table 18. Global Direct-Drive Dexterous Hands Sale by Application (2021-2026) & (Units)

Table 19. Global Direct-Drive Dexterous Hands Sale Market Share by Application (2021-2026)

Table 20. Global Direct-Drive Dexterous Hands Revenue by Application (2021-2026) & (\$ million)

Table 21. Global Direct-Drive Dexterous Hands Revenue Market Share by Application (2021-2026)

Table 22. Global Direct-Drive Dexterous Hands Sale Price by Application (2021-2026) & (US\$/Unit)

Table 23. Global Direct-Drive Dexterous Hands Sales by Company (2021-2026) & (Units)

Table 24. Global Direct-Drive Dexterous Hands Sales Market Share by Company (2021-2026)

Table 25. Global Direct-Drive Dexterous Hands Revenue by Company (2021-2026) & (\$ millions)

Table 26. Global Direct-Drive Dexterous Hands Revenue Market Share by Company (2021-2026)

Table 27. Global Direct-Drive Dexterous Hands Sale Price by Company (2021-2026) & (US\$/Unit)

Table 28. Key Manufacturers Direct-Drive Dexterous Hands Producing Area Distribution and Sales Area

Table 29. Players Direct-Drive Dexterous Hands Products Offered

Table 30. Direct-Drive Dexterous Hands Concentration Ratio (CR3, CR5 and CR10) & (2024-2026)

Table 31. New Products and Potential Entrants

Table 32. Market M&A Activity & Strategy

Table 33. Global Direct-Drive Dexterous Hands Sales by Geographic Region (2021-2026) & (Units)

Table 34. Global Direct-Drive Dexterous Hands Sales Market Share Geographic Region (2021-2026)

Table 35. Global Direct-Drive Dexterous Hands Revenue by Geographic Region (2021-2026) & (\$ millions)

Table 36. Global Direct-Drive Dexterous Hands Revenue Market Share by Geographic Region (2021-2026)

Table 37. Global Direct-Drive Dexterous Hands Sales by Country/Region (2021-2026) & (Units)

Table 38. Global Direct-Drive Dexterous Hands Sales Market Share by Country/Region (2021-2026)

Table 39. Global Direct-Drive Dexterous Hands Revenue by Country/Region (2021-2026) & (\$ millions)

Table 40. Global Direct-Drive Dexterous Hands Revenue Market Share by Country/Region (2021-2026)

Table 41. Americas Direct-Drive Dexterous Hands Sales by Country (2021-2026) & (Units)

Table 42. Americas Direct-Drive Dexterous Hands Sales Market Share by Country (2021-2026)

Table 43. Americas Direct-Drive Dexterous Hands Revenue by Country (2021-2026) & (\$ millions)

Table 44. Americas Direct-Drive Dexterous Hands Sales by Type (2021-2026) & (Units)

Table 45. Americas Direct-Drive Dexterous Hands Sales by Application (2021-2026) & (Units)

Table 46. APAC Direct-Drive Dexterous Hands Sales by Region (2021-2026) & (Units)

Table 47. APAC Direct-Drive Dexterous Hands Sales Market Share by Region (2021-2026)

Table 48. APAC Direct-Drive Dexterous Hands Revenue by Region (2021-2026) & (\$ millions)

Table 49. APAC Direct-Drive Dexterous Hands Sales by Type (2021-2026) & (Units)

Table 50. APAC Direct-Drive Dexterous Hands Sales by Application (2021-2026) & (Units)

Table 51. Europe Direct-Drive Dexterous Hands Sales by Country (2021-2026) & (Units)

Table 52. Europe Direct-Drive Dexterous Hands Revenue by Country (2021-2026) & (\$ millions)

Table 53. Europe Direct-Drive Dexterous Hands Sales by Type (2021-2026) & (Units)

Table 54. Europe Direct-Drive Dexterous Hands Sales by Application (2021-2026) & (Units)

Table 55. Middle East & Africa Direct-Drive Dexterous Hands Sales by Country (2021-2026) & (Units)

Table 56. Middle East & Africa Direct-Drive Dexterous Hands Revenue Market Share by Country (2021-2026)

Table 57. Middle East & Africa Direct-Drive Dexterous Hands Sales by Type (2021-2026) & (Units)

Table 58. Middle East & Africa Direct-Drive Dexterous Hands Sales by Application (2021-2026) & (Units)

Table 59. Key Market Drivers & Growth Opportunities of Direct-Drive Dexterous Hands

Table 60. Key Market Challenges & Risks of Direct-Drive Dexterous Hands

Table 61. Key Industry Trends of Direct-Drive Dexterous Hands

Table 62. Direct-Drive Dexterous Hands Raw Material

Table 63. Key Suppliers of Raw Materials

Table 64. Direct-Drive Dexterous Hands Distributors List

Table 65. Direct-Drive Dexterous Hands Customer List

Table 66. Global Direct-Drive Dexterous Hands Sales Forecast by Region (2027-2032) & (Units)

Table 67. Global Direct-Drive Dexterous Hands Revenue Forecast by Region (2027-2032) & (\$ millions)

Table 68. Americas Direct-Drive Dexterous Hands Sales Forecast by Country (2027-2032) & (Units)
Table 69. Americas Direct-Drive Dexterous Hands Annual Revenue Forecast by Country (2027-2032) & (\$ millions)
Table 70. APAC Direct-Drive Dexterous Hands Sales Forecast by Region (2027-2032) & (Units)
Table 71. APAC Direct-Drive Dexterous Hands Annual Revenue Forecast by Region (2027-2032) & (\$ millions)
Table 72. Europe Direct-Drive Dexterous Hands Sales Forecast by Country (2027-2032) & (Units)
Table 73. Europe Direct-Drive Dexterous Hands Revenue Forecast by Country (2027-2032) & (\$ millions)
Table 74. Middle East & Africa Direct-Drive Dexterous Hands Sales Forecast by Country (2027-2032) & (Units)
Table 75. Middle East & Africa Direct-Drive Dexterous Hands Revenue Forecast by Country (2027-2032) & (\$ millions)
Table 76. Global Direct-Drive Dexterous Hands Sales Forecast by Type (2027-2032) & (Units)
Table 77. Global Direct-Drive Dexterous Hands Revenue Forecast by Type (2027-2032) & (\$ millions)
Table 78. Global Direct-Drive Dexterous Hands Sales Forecast by Application (2027-2032) & (Units)
Table 79. Global Direct-Drive Dexterous Hands Revenue Forecast by Application (2027-2032) & (\$ millions)
Table 80. Shadow Robot Basic Information, Direct-Drive Dexterous Hands Manufacturing Base, Sales Area and Its Competitors
Table 81. Shadow Robot Direct-Drive Dexterous Hands Product Portfolios and Specifications
Table 82. Shadow Robot Direct-Drive Dexterous Hands Sales (Units), Revenue (\$ Million), Price (US\$/Unit) and Gross Margin (2021-2026)
Table 83. Shadow Robot Main Business
Table 84. Shadow Robot Latest Developments
Table 85. Tesla Basic Information, Direct-Drive Dexterous Hands Manufacturing Base, Sales Area and Its Competitors
Table 86. Tesla Direct-Drive Dexterous Hands Product Portfolios and Specifications
Table 87. Tesla Direct-Drive Dexterous Hands Sales (Units), Revenue (\$ Million), Price (US\$/Unit) and Gross Margin (2021-2026)
Table 88. Tesla Main Business
Table 89. Tesla Latest Developments

Table 90. Wonik Robotics?Allegro Hand? Basic Information, Direct-Drive Dexterous Hands Manufacturing Base, Sales Area and Its Competitors

Table 91. Wonik Robotics?Allegro Hand? Direct-Drive Dexterous Hands Product Portfolios and Specifications

Table 92. Wonik Robotics?Allegro Hand? Direct-Drive Dexterous Hands Sales (Units), Revenue (\$ Million), Price (US\$/Unit) and Gross Margin (2021-2026)

Table 93. Wonik Robotics?Allegro Hand? Main Business

Table 94. Wonik Robotics?Allegro Hand? Latest Developments

Table 95. SharpWave Basic Information, Direct-Drive Dexterous Hands Manufacturing Base, Sales Area and Its Competitors

Table 96. SharpWave Direct-Drive Dexterous Hands Product Portfolios and Specifications

Table 97. SharpWave Direct-Drive Dexterous Hands Sales (Units), Revenue (\$ Million), Price (US\$/Unit) and Gross Margin (2021-2026)

Table 98. SharpWave Main Business

Table 99. SharpWave Latest Developments

Table 100. Robotera Basic Information, Direct-Drive Dexterous Hands Manufacturing Base, Sales Area and Its Competitors

Table 101. Robotera Direct-Drive Dexterous Hands Product Portfolios and Specifications

Table 102. Robotera Direct-Drive Dexterous Hands Sales (Units), Revenue (\$ Million), Price (US\$/Unit) and Gross Margin (2021-2026)

Table 103. Robotera Main Business

Table 104. Robotera Latest Developments

Table 105. WUJI TECH Basic Information, Direct-Drive Dexterous Hands Manufacturing Base, Sales Area and Its Competitors

Table 106. WUJI TECH Direct-Drive Dexterous Hands Product Portfolios and Specifications

Table 107. WUJI TECH Direct-Drive Dexterous Hands Sales (Units), Revenue (\$ Million), Price (US\$/Unit) and Gross Margin (2021-2026)

Table 108. WUJI TECH Main Business

Table 109. WUJI TECH Latest Developments

Table 110. Zhaowei Electromechanical Basic Information, Direct-Drive Dexterous Hands Manufacturing Base, Sales Area and Its Competitors

Table 111. Zhaowei Electromechanical Direct-Drive Dexterous Hands Product Portfolios and Specifications

Table 112. Zhaowei Electromechanical Direct-Drive Dexterous Hands Sales (Units), Revenue (\$ Million), Price (US\$/Unit) and Gross Margin (2021-2026)

Table 113. Zhaowei Electromechanical Main Business

Table 114. Zhaowei Electromechanical Latest Developments

Table 115. LinkerBot Basic Information, Direct-Drive Dexterous Hands Manufacturing Base, Sales Area and Its Competitors

Table 116. LinkerBot Direct-Drive Dexterous Hands Product Portfolios and Specifications

Table 117. LinkerBot Direct-Drive Dexterous Hands Sales (Units), Revenue (\$ Million), Price (US\$/Unit) and Gross Margin (2021-2026)

Table 118. LinkerBot Main Business

Table 119. LinkerBot Latest Developments

Table 120. Unitree Basic Information, Direct-Drive Dexterous Hands Manufacturing Base, Sales Area and Its Competitors

Table 121. Unitree Direct-Drive Dexterous Hands Product Portfolios and Specifications

Table 122. Unitree Direct-Drive Dexterous Hands Sales (Units), Revenue (\$ Million), Price (US\$/Unit) and Gross Margin (2021-2026)

Table 123. Unitree Main Business

Table 124. Unitree Latest Developments

Table 125. Agibot Basic Information, Direct-Drive Dexterous Hands Manufacturing Base, Sales Area and Its Competitors

Table 126. Agibot Direct-Drive Dexterous Hands Product Portfolios and Specifications

Table 127. Agibot Direct-Drive Dexterous Hands Sales (Units), Revenue (\$ Million), Price (US\$/Unit) and Gross Margin (2021-2026)

Table 128. Agibot Main Business

Table 129. Agibot Latest Developments

Table 130. Leadshine Basic Information, Direct-Drive Dexterous Hands Manufacturing Base, Sales Area and Its Competitors

Table 131. Leadshine Direct-Drive Dexterous Hands Product Portfolios and Specifications

Table 132. Leadshine Direct-Drive Dexterous Hands Sales (Units), Revenue (\$ Million), Price (US\$/Unit) and Gross Margin (2021-2026)

Table 133. Leadshine Main Business

Table 134. Leadshine Latest Developments

Table 135. BrainCo Basic Information, Direct-Drive Dexterous Hands Manufacturing Base, Sales Area and Its Competitors

Table 136. BrainCo Direct-Drive Dexterous Hands Product Portfolios and Specifications

Table 137. BrainCo Direct-Drive Dexterous Hands Sales (Units), Revenue (\$ Million), Price (US\$/Unit) and Gross Margin (2021-2026)

Table 138. BrainCo Main Business

Table 139. BrainCo Latest Developments

Table 140. Xynova Basic Information, Direct-Drive Dexterous Hands Manufacturing

Base, Sales Area and Its Competitors

Table 141. Xynova Direct-Drive Dexterous Hands Product Portfolios and Specifications

Table 142. Xynova Direct-Drive Dexterous Hands Sales (Units), Revenue (\$ Million),
Price (US\$/Unit) and Gross Margin (2021-2026)

Table 143. Xynova Main Business

Table 144. Xynova Latest Developments

List Of Figures

LIST OF FIGURES

- Figure 1. Picture of Direct-Drive Dexterous Hands
- Figure 2. Direct-Drive Dexterous Hands Report Years Considered
- Figure 3. Research Objectives
- Figure 4. Research Methodology
- Figure 5. Research Process and Data Source
- Figure 6. Global Direct-Drive Dexterous Hands Sales Growth Rate 2021-2032 (Units)
- Figure 7. Global Direct-Drive Dexterous Hands Revenue Growth Rate 2021-2032 (\$ millions)
- Figure 8. Direct-Drive Dexterous Hands Sales by Geographic Region (2021, 2025 & 2032) & (\$ millions)
- Figure 9. Direct-Drive Dexterous Hands Sales Market Share by Country/Region (2025)
- Figure 10. Direct-Drive Dexterous Hands Sales Market Share by Country/Region (2021, 2025 & 2032)
- Figure 11. Product Picture of Direct Motor Drive
- Figure 12. Product Picture of Motor + Gearbox Drive
- Figure 13. Global Direct-Drive Dexterous Hands Sales Market Share by Type in 2026
- Figure 14. Global Direct-Drive Dexterous Hands Revenue Market Share by Type (2021-2026)
- Figure 15. Product Picture of 5–10 DoF
- Figure 16. Product Picture of 10–20 DoF
- Figure 17. Product Picture of ?20 DoF
- Figure 18. Global Direct-Drive Dexterous Hands Sales Market Share by Degrees of Freedom in 2026
- Figure 19. Global Direct-Drive Dexterous Hands Revenue Market Share by Degrees of Freedom (2021-2026)
- Figure 20. Direct-Drive Dexterous Hands Consumed in Humanoid Robot
- Figure 21. Global Direct-Drive Dexterous Hands Market: Humanoid Robot (2021-2026) & (Units)
- Figure 22. Direct-Drive Dexterous Hands Consumed in Collaborative Robot
- Figure 23. Global Direct-Drive Dexterous Hands Market: Collaborative Robot (2021-2026) & (Units)
- Figure 24. Direct-Drive Dexterous Hands Consumed in Medical Robot
- Figure 25. Global Direct-Drive Dexterous Hands Market: Medical Robot (2021-2026) & (Units)
- Figure 26. Direct-Drive Dexterous Hands Consumed in Others

Figure 27. Global Direct-Drive Dexterous Hands Market: Others (2021-2026) & (Units)

Figure 28. Global Direct-Drive Dexterous Hands Sale Market Share by Application (2025)

Figure 29. Global Direct-Drive Dexterous Hands Revenue Market Share by Application in 2025

Figure 30. Direct-Drive Dexterous Hands Sales by Company in 2025 (Units)

Figure 31. Global Direct-Drive Dexterous Hands Sales Market Share by Company in 2025

Figure 32. Direct-Drive Dexterous Hands Revenue by Company in 2025 (\$ millions)

Figure 33. Global Direct-Drive Dexterous Hands Revenue Market Share by Company in 2025

Figure 34. Global Direct-Drive Dexterous Hands Sales Market Share by Geographic Region (2021-2026)

Figure 35. Global Direct-Drive Dexterous Hands Revenue Market Share by Geographic Region in 2025

Figure 36. Americas Direct-Drive Dexterous Hands Sales 2021-2026 (Units)

Figure 37. Americas Direct-Drive Dexterous Hands Revenue 2021-2026 (\$ millions)

Figure 38. APAC Direct-Drive Dexterous Hands Sales 2021-2026 (Units)

Figure 39. APAC Direct-Drive Dexterous Hands Revenue 2021-2026 (\$ millions)

Figure 40. Europe Direct-Drive Dexterous Hands Sales 2021-2026 (Units)

Figure 41. Europe Direct-Drive Dexterous Hands Revenue 2021-2026 (\$ millions)

Figure 42. Middle East & Africa Direct-Drive Dexterous Hands Sales 2021-2026 (Units)

Figure 43. Middle East & Africa Direct-Drive Dexterous Hands Revenue 2021-2026 (\$ millions)

Figure 44. Americas Direct-Drive Dexterous Hands Sales Market Share by Country in 2025

Figure 45. Americas Direct-Drive Dexterous Hands Revenue Market Share by Country (2021-2026)

Figure 46. Americas Direct-Drive Dexterous Hands Sales Market Share by Type (2021-2026)

Figure 47. Americas Direct-Drive Dexterous Hands Sales Market Share by Application (2021-2026)

Figure 48. United States Direct-Drive Dexterous Hands Revenue Growth 2021-2026 (\$ millions)

Figure 49. Canada Direct-Drive Dexterous Hands Revenue Growth 2021-2026 (\$ millions)

Figure 50. Mexico Direct-Drive Dexterous Hands Revenue Growth 2021-2026 (\$ millions)

Figure 51. Brazil Direct-Drive Dexterous Hands Revenue Growth 2021-2026 (\$ millions)

Figure 52. APAC Direct-Drive Dexterous Hands Sales Market Share by Region in 2025

Figure 53. APAC Direct-Drive Dexterous Hands Revenue Market Share by Region (2021-2026)

Figure 54. APAC Direct-Drive Dexterous Hands Sales Market Share by Type (2021-2026)

Figure 55. APAC Direct-Drive Dexterous Hands Sales Market Share by Application (2021-2026)

Figure 56. China Direct-Drive Dexterous Hands Revenue Growth 2021-2026 (\$ millions)

Figure 57. Japan Direct-Drive Dexterous Hands Revenue Growth 2021-2026 (\$ millions)

Figure 58. South Korea Direct-Drive Dexterous Hands Revenue Growth 2021-2026 (\$ millions)

Figure 59. Southeast Asia Direct-Drive Dexterous Hands Revenue Growth 2021-2026 (\$ millions)

Figure 60. India Direct-Drive Dexterous Hands Revenue Growth 2021-2026 (\$ millions)

Figure 61. Australia Direct-Drive Dexterous Hands Revenue Growth 2021-2026 (\$ millions)

Figure 62. China Taiwan Direct-Drive Dexterous Hands Revenue Growth 2021-2026 (\$ millions)

Figure 63. Europe Direct-Drive Dexterous Hands Sales Market Share by Country in 2025

Figure 64. Europe Direct-Drive Dexterous Hands Revenue Market Share by Country (2021-2026)

Figure 65. Europe Direct-Drive Dexterous Hands Sales Market Share by Type (2021-2026)

Figure 66. Europe Direct-Drive Dexterous Hands Sales Market Share by Application (2021-2026)

Figure 67. Germany Direct-Drive Dexterous Hands Revenue Growth 2021-2026 (\$ millions)

Figure 68. France Direct-Drive Dexterous Hands Revenue Growth 2021-2026 (\$ millions)

Figure 69. UK Direct-Drive Dexterous Hands Revenue Growth 2021-2026 (\$ millions)

Figure 70. Italy Direct-Drive Dexterous Hands Revenue Growth 2021-2026 (\$ millions)

Figure 71. Russia Direct-Drive Dexterous Hands Revenue Growth 2021-2026 (\$ millions)

Figure 72. Middle East & Africa Direct-Drive Dexterous Hands Sales Market Share by Country (2021-2026)

Figure 73. Middle East & Africa Direct-Drive Dexterous Hands Sales Market Share by Type (2021-2026)

Figure 74. Middle East & Africa Direct-Drive Dexterous Hands Sales Market Share by Application (2021-2026)

Figure 75. Egypt Direct-Drive Dexterous Hands Revenue Growth 2021-2026 (\$ millions)

Figure 76. South Africa Direct-Drive Dexterous Hands Revenue Growth 2021-2026 (\$ millions)

Figure 77. Israel Direct-Drive Dexterous Hands Revenue Growth 2021-2026 (\$ millions)

Figure 78. Turkey Direct-Drive Dexterous Hands Revenue Growth 2021-2026 (\$ millions)

Figure 79. GCC Countries Direct-Drive Dexterous Hands Revenue Growth 2021-2026 (\$ millions)

Figure 80. Manufacturing Cost Structure Analysis of Direct-Drive Dexterous Hands in 2026

Figure 81. Manufacturing Process Analysis of Direct-Drive Dexterous Hands

Figure 82. Industry Chain Structure of Direct-Drive Dexterous Hands

Figure 83. Channels of Distribution

Figure 84. Global Direct-Drive Dexterous Hands Sales Market Forecast by Region (2027-2032)

Figure 85. Global Direct-Drive Dexterous Hands Revenue Market Share Forecast by Region (2027-2032)

Figure 86. Global Direct-Drive Dexterous Hands Sales Market Share Forecast by Type (2027-2032)

Figure 87. Global Direct-Drive Dexterous Hands Revenue Market Share Forecast by Type (2027-2032)

Figure 88. Global Direct-Drive Dexterous Hands Sales Market Share Forecast by Application (2027-2032)

Figure 89. Global Direct-Drive Dexterous Hands Revenue Market Share Forecast by Application (2027-2032)

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