

Global Dexterous Hands and Grippers Market Growth 2026-2032

<https://marketpublishers.com/r/G6079F722E68EN.html>

Date: July 2026

Pages: 195

Price: US\$ 3,660.00 (Single User License)

ID: G6079F722E68EN

Abstracts

The global Dexterous Hands and Grippers market size is predicted to grow from US\$ 2319 million in 2025 to US\$ 11281 million in 2032; it is expected to grow at a CAGR of 21.5% from 2026 to 2032.

The statistical analysis scope is defined as Robotic Grippers and Dexterous Hands, which belong to the grasping and dexterous manipulation segment of Robotic End Effectors, rather than the broader EOAT / End Effectors category.

Robotic grippers refer to end-mounted devices installed on industrial robots, collaborative robots, mobile manipulators, humanoid robots, or automated handling systems to perform gripping, holding, picking, placing, loading / unloading, assembly, sorting, and material handling tasks. This category includes electric grippers, pneumatic grippers, hydraulic grippers, adaptive grippers, soft grippers, vacuum grippers, magnetic grippers, and other products with independent object-grasping functionality.

Dexterous hands refer to higher DOF end effectors with multi-finger structures, anthropomorphic or semi-anthropomorphic designs, complex posture control, force control, tactile or multi-modal sensing capabilities, and the ability to perform dexterous grasping and manipulation of objects with different shapes, sizes, materials, and surface conditions. They are mainly used in humanoid robots, service robots, research platforms, complex assembly, and general-purpose manipulation scenarios.

Note: This scope excludes non-grasping EOAT products such as welding torches, spray guns, polishing heads, grinding tools, dispensing heads, cutting tools, inspection probes, cameras, sensors, tool changers, couplers, adapters, and mounting flanges. It also excludes components or integration accessories that do not provide standalone

grasping or manipulation functionality.

The market for robotic grippers and dexterous hands features a multi-tiered development landscape. Its product portfolio includes conventional mature grippers, high-end electric grippers, high-degree-of-freedom manipulators, end-effectors for humanoid robots, as well as hand systems for medical and rehabilitation applications. In 2025, various types of grippers still dominated the market, with general grippers, pneumatic mechanical grippers and electric mechanical grippers collectively holding the largest market share. Going forward, the market will experience a notable shift toward multi-fingered dexterous hands.

By 2035, the market size of external and built-in dexterous hands will each exceed 4 billion US dollars, while that of robotic electric grippers will surpass 3.8 billion US dollars. These segmented products will serve as the core drivers fueling the structural growth of the overall market. Although the market volume of traditional pneumatic grippers and other general-purpose grippers continues to expand, their relative market share keeps declining as robotic operations evolve toward higher flexibility, controllability, intelligence and integration.

In terms of application scenarios, market demand in 2025 was primarily concentrated in the industrial and medical sectors, covering medical prosthetics, rehabilitation aids, industrial robots, collaborative robots, automotive manufacturing, electronics manufacturing, food and pharmaceutical packaging, precision manufacturing and other fields. The humanoid robot segment remained a small niche in 2025, with a market size of less than 200 million US dollars. By 2035, however, humanoid robots will emerge as the largest application segment, with its market size exceeding 5 billion US dollars, marking the most profound structural transformation across the industry in the long run.

Against this backdrop, dexterous hands are evolving from dedicated operating tools and robotic end effectors into core enabling subsystems for humanoid robots and embodied AI platforms. Meanwhile, steady and substantial demand will persist in industrial robots, collaborative robots, electronics manufacturing, scientific research, teleoperation training, medical prosthetics and other fields, preventing the market from over-reliance on a single application segment.

LP Information, Inc. (LPI)'s newest research report, the "Dexterous Hands and Grippers Industry Forecast" looks at past sales and reviews total world Dexterous Hands and Grippers sales in 2025, providing a comprehensive analysis by region and market sector of projected Dexterous Hands and Grippers sales for 2026 through 2032. With

Dexterous Hands and Grippers sales broken down by region, market sector and sub-sector, this report provides a detailed analysis in US\$ millions of the world Dexterous Hands and Grippers industry.

This Insight Report provides a comprehensive analysis of the global Dexterous Hands and Grippers landscape and highlights key trends related to product segmentation, company formation, revenue, and market share, latest development, and M&A activity. This report also analyzes the strategies of leading global companies with a focus on Dexterous Hands and Grippers portfolios and capabilities, market entry strategies, market positions, and geographic footprints, to better understand these firms' unique position in an accelerating global Dexterous Hands and Grippers market.

This Insight Report evaluates the key market trends, drivers, and affecting factors shaping the global outlook for Dexterous Hands and Grippers and breaks down the forecast by Dexterous Hands, by Application, geography, and market size to highlight emerging pockets of opportunity. With a transparent methodology based on hundreds of bottom-up qualitative and quantitative market inputs, this study forecast offers a highly nuanced view of the current state and future trajectory in the global Dexterous Hands and Grippers.

This report presents a comprehensive overview, market shares, and growth opportunities of Dexterous Hands and Grippers market by product type, application, key manufacturers and key regions and countries.

Segmentation by Dexterous Hands:

Built-in Dexterous Hands

External Dexterous Hands

Hybrid Dexterous Hands

Segmentation by Grippers:

Robotic Electric Grippers

Robotic Pneumatic Grippers

Robotic Hydraulic Grippers

Other Grippers

Segmentation by Application:

Humanoid Robots

Industrial Robots

Collaborative Robots

Warehousing and Logistics

3C & Electronics Manufacturing

Automotive Manufacturing

Semiconductors & Precision Manufacturing

Food & Pharmaceuticals & Packaging

Scientific Research and Education

Medical Prostheses & Rehabilitation Aids

Others

This report also splits the market by region:

Americas

United States

Canada

Mexico

Brazil

APAC

China

Japan

Korea

Southeast Asia

India

Australia

Europe

Germany

France

UK

Italy

Russia

Middle East & Africa

Egypt

South Africa

Israel

Turkey

GCC Countries

The below companies that are profiled have been selected based on inputs gathered from primary experts and analysing the company's coverage, product portfolio, its market penetration.

Shadow Robot

Tesla

Beijing Inspire Robots Technology

Zhejiang BrainCo

SCHUNK

Shanghai OYMotion Technologies

Agile Robots

Qbrobotics

Tokyo Robotics

Paxini

Shanghai AgiBot

Beijing ROBOTERA

Beijing Linkerbot

Shenzhen Neurocean Technologies Inc

Ti5 ROBOT

Zhejiang DexRobot

Jodell Robotics

Shenzhen Daimon

Shenzhen Zhaowei Machinery & Electronics

Unitree Robotics

MagicLab

Suzhou ChangingTek

HITBOT

Shenzhen Ruiyan

Ottobock

Tesollo

Vincent Systems GmbH

?ssur

PSYONIC

DH Robotics

Aether Biomedical

Esper Bionics

Atom

Festo

Robotiq

OnRobot

SMC

Zimmer

Destaco

EMI

IAI

Effecto

Schmalz

RAD

Key Questions Addressed in this Report

What is the 10-year outlook for the global Dexterous Hands and Grippers market?

What factors are driving Dexterous Hands and Grippers market growth, globally and by region?

Which technologies are poised for the fastest growth by market and region?

How do Dexterous Hands and Grippers market opportunities vary by end market size?

How does Dexterous Hands and Grippers break out by Dexterous Hands, by Application?

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