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Global Collaborating Electric Gripper Market Growth 2026-2032

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Abstracts

The global Collaborating Electric Gripper market size is predicted to grow from US$ 236 million in 2025 to US$ 658 million in 2032; it is expected to grow at a CAGR of 15.9% from 2026 to 2032.

A Collaborative Electric Gripper is an electrically actuated robotic end-effector specifically designed for collaborative robots and other lightweight robotic systems that operate in flexible, human-centered automation environments. Unlike conventional pneumatic grippers, collaborative electric grippers typically integrate servo motors, drive electronics, position and force control, sensing and communication functions into a compact unit, allowing gripping force, jaw position, opening stroke and operating speed to be digitally adjusted according to different workpieces. They are generally characterized by lightweight construction, rounded and compact mechanical design, plug-and-play compatibility with major collaborative robot brands, programmable gripping parameters, position or object-detection feedback and simplified integration with robot controllers. Depending on the mechanical configuration, products may use two-finger parallel, adaptive linkage, centric three-finger, long-stroke or other gripping structures. Collaborative electric grippers are widely used in pick-and-place, machine tending, assembly, inspection, packaging, laboratory automation, electronics manufacturing and flexible production lines, particularly where frequent product changeovers, controllable gripping force and rapid robot redeployment are required.

Key Findings

In 2025, global Collaborating Electric Gripper production reached approximately 73k units, with an average global market price of around US$3.3k per unit

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Demand is shifting from basic opening and closing toward programmable force, position feedback and intelligent workpiece detection

Machine tending, flexible handling and assembly are major commercial applications for collaborative electric grippers

Plug-and-play integration with major cobot platforms is becoming an important competitive capability

Chinese specialist suppliers are increasing competition in intelligent and cost-effective collaborative gripping solutions

Market Trends

The Collaborating Electric Gripper market is evolving from relatively simple electromechanical end-effectors toward intelligent, feedback-rich robotic tools. Product development increasingly emphasizes integrated servo control, programmable gripping force, position feedback, workpiece detection, gripping-state monitoring and direct communication with robot controllers. At the same time, lightweight design, compact envelopes, smooth exterior surfaces and collaboration-oriented mechanical structures are becoming increasingly important as grippers move closer to operators in shared production environments. Another major direction is simplified deployment: manufacturers are developing robot-specific software plug-ins, unified mechanical interfaces and standardized communication architectures to reduce engineering work during commissioning and product changeovers. OnRobot emphasizes flexible collaborative grippers and unified robot integration, Robotiq develops adaptive grippers specifically for collaborative robots, while WEISS ROBOTICS combines servo-electric gripping with force limitation, process feedback and direct robot integration. Chinese suppliers such as DH-Robotics are expanding from basic electric parallel grippers toward collaborative, adaptive, centric and intelligent gripping platforms, reinforcing the industry's transition from individual gripping components toward configurable end-of-arm automation ecosystems.

Market Dynamics

Drivers

Growth in collaborative robot deployment is the primary structural driver for Collaborating Electric Grippers because the end-effector directly determines whether a

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robot can reliably manipulate different workpieces. Flexible manufacturing, high-mix production, labor shortages and the automation of repetitive manual tasks are encouraging manufacturers to deploy cobots in machine tending, handling, inspection and assembly. Compared with conventional pneumatic solutions, electric grippers can provide programmable gripping parameters, simplified utility requirements and closer integration with robot control systems, making them particularly attractive for frequently reconfigured production lines. The growing availability of ready-to-use robot plug-ins and mechanical interfaces further reduces engineering complexity and expands adoption among smaller manufacturers and users without large automation engineering teams. SCHUNK, SMC, OnRobot and Robotiq have all developed gripper solutions specifically around collaborative robot ecosystems, supporting broader commercialization of this product category.

Restraints

The main restraint is that collaborative electric grippers face competition from pneumatic grippers, vacuum grippers and conventional electric gripping products that can perform many basic handling tasks at lower system complexity or with advantages in specific applications. High-speed repetitive production, very heavy workpieces, harsh environments and applications requiring extremely simple gripping mechanisms may continue to favor traditional technologies. Collaborative operation also does not depend on the gripper alone; the robot, tool, workpiece, operating speed and overall application must be evaluated as an integrated system. Consequently, investment in a collaboration-oriented gripper does not automatically eliminate the need for system-level safety assessment and engineering. Compatibility fragmentation across robot controllers, mechanical interfaces and communication protocols can also increase integration effort, particularly when users operate mixed-brand robot fleets.

Opportunities

The strongest opportunities lie in intelligent gripping, flexible automation and increasingly complex human–robot production environments. Future products can create more value through force sensing, tactile feedback, adaptive grasping, automatic workpiece recognition, gripping-quality monitoring and data interfaces that allow the gripper to participate directly in closed-loop robotic control. Electronics, precision assembly, laboratory automation, medical-device manufacturing and other applications involving delicate or frequently changing workpieces provide attractive opportunities for higher-value gripping solutions. Machine tending and flexible manufacturing also remain important because programmable grippers allow a single robot cell to handle multiple components without extensive mechanical changeover. The expansion of robot

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software ecosystems creates another opportunity: suppliers capable of combining hardware, software plug-ins, quick changers, sensing and application packages can move beyond component sales toward complete end-of-arm solutions.

Challenges

The industry faces the challenge of balancing gripping performance, safety, compactness, reliability and cost within a small end-effector. Higher gripping force and longer stroke tend to increase weight and mechanical complexity, while collaborative applications favor low mass, smooth geometry and predictable force behavior. Manufacturers must also maintain stable force and position control over repeated cycles and across changing workpieces while providing reliable communication with different robot brands. Competitive pressure is increasing as established European, Japanese and North American automation suppliers compete with rapidly developing Chinese specialist manufacturers. Product differentiation is therefore shifting toward control algorithms, sensing, software integration, reliability, application engineering and ecosystem compatibility rather than basic gripping motion alone.

Industry Chain Analysis

The upstream industry chain for Collaborating Electric Grippers consists mainly of miniature servo motors and brushless motors, precision gear and screw transmission components, bearings and guides, aluminum alloy and engineering-plastic structural parts, encoders, force and position sensors, control boards, connectors and industrial communication components. Midstream manufacturers integrate these components into electric parallel, adaptive, centric and other collaborative gripping products while developing motion control, force control, workpiece detection and robot-interface software. Downstream customers include collaborative robot manufacturers, industrial automation integrators, machine builders and end users in electronics, automotive components, machinery, consumer products, packaging, life sciences and general manufacturing. Value creation is progressively moving away from the mechanical gripper body toward integrated mechatronics, sensing, control algorithms, robot compatibility, software tools and application engineering, which increases the strategic importance of suppliers capable of delivering complete end-of-arm automation solutions.

Segment Insights

By gripping architecture, two-finger products remain the principal segment because

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parallel and adaptive mechanisms cover a broad range of general-purpose handling tasks while maintaining relatively simple structures, compact dimensions and straightforward control. Parallel electric grippers are particularly suitable for regular components, machine tending and precision positioning, while adaptive designs offer greater flexibility for irregular shapes and high-mix applications. Three-finger and centric grippers are more specialized and are better suited to cylindrical parts, centering operations and applications where multi-point contact improves gripping stability. The analyst's original two-finger and three-finger classification is therefore valid at the finger-count level, but a more useful commercial segmentation is Parallel Electric Grippers, Adaptive Electric Grippers, Centric or Multi-finger Electric Grippers and Other Collaborative Electric Grippers. DH-Robotics' product architecture illustrates this distinction by separating collaborative parallel, adaptive and centric electric grippers into dedicated product families.

Downstream Market Opportunities

Machine tending is one of the most commercially attractive downstream opportunities because collaborative robots can be deployed beside machining centers and production equipment with relatively limited changes to the existing manufacturing environment, while programmable electric grippers allow rapid adaptation to different workpieces. Assembly and electronics manufacturing favor controllable gripping force and precise positioning for delicate components, while packaging and general material handling benefit from flexible stroke and fast product changeover. Quality inspection and laboratory automation create additional demand for compact, feedback-enabled grippers capable of repeatable manipulation. As end users increasingly seek automation systems that can be redeployed rather than dedicated to a single product, collaborative electric grippers are becoming an important enabling component of flexible robotic cells.

Regional Insights

Europe has a strong technology and supplier base in collaborative gripping, supported by established automation companies such as SCHUNK, SMC's European operations, Festo, Zimmer Group, Gimatic and WEISS ROBOTICS, together with a mature ecosystem of collaborative robot integrators and machine builders. North America represents another important market, where Robotiq, OnRobot and major robot ecosystems are widely used in machine tending, packaging and flexible manufacturing. China is becoming increasingly important both as a demand market and as a manufacturing base, supported by rapid expansion of collaborative robots and domestic

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end-of-arm tooling suppliers such as DH-Robotics. Japan maintains a strong position through industrial automation and component suppliers including SMC and IAI, while Korea, Taiwan and Southeast Asia offer further opportunities as electronics, semiconductor, machinery and export-oriented manufacturing continue to adopt flexible automation.

Competitive Landscape Analysis

The competitive landscape combines established gripping and automation companies with specialist collaborative end-effector suppliers. SCHUNK is a core participant with dedicated human–robot collaboration grippers and a broad mechatronic gripping portfolio, while SMC provides electric grippers specifically designed for collaborative robots and compatibility with multiple robot platforms. OnRobot and Robotiq are highly focused on collaborative robot end-of-arm tooling and emphasize plug-and-play deployment, software integration and application flexibility. WEISS ROBOTICS is another specialist supplier with servo-electric grippers developed specifically for collaborative applications, while DH-Robotics has built a broad electric gripper portfolio covering collaborative parallel, adaptive and centric architectures. Zimmer Group, Festo, IAI and Gimatic are relevant extended competitors through their broader electric gripping, mechatronic handling and robotic end-effector portfolios. DESTACO has strong robotic tooling and automation capabilities but should be treated more cautiously in a narrowly defined collaborative electric gripper market unless individual electric collaborative products are confirmed. Overall competition is shifting from mechanical gripping performance toward integrated sensing, software compatibility, ease of deployment, safety-oriented design and complete end-of-arm ecosystems.

Report Scope

LP Information, Inc. (LPI) ' newest research report, the “Collaborating Electric Gripper Industry Forecast” looks at past sales and reviews total world Collaborating Electric Gripper sales in 2025, providing a comprehensive analysis by region and market sector of projected Collaborating Electric Gripper sales for 2026 through 2032. With Collaborating Electric Gripper sales broken down by region, market sector and sub-sector, this report provides a detailed analysis in US$ millions of the world Collaborating Electric Gripper industry.

This Insight Report provides a comprehensive analysis of the global Collaborating Electric Gripper landscape and highlights key trends related to product segmentation, company formation, revenue, and market share, latest development, and M&A activity.

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This report also analyzes the strategies of leading global companies with a focus on Collaborating Electric Gripper portfolios and capabilities, market entry strategies, market positions, and geographic footprints, to better understand these firms' unique position in an accelerating global Collaborating Electric Gripper market.

This Insight Report evaluates the key market trends, drivers, and affecting factors shaping the global outlook for Collaborating Electric Gripper and breaks down the forecast by Type, by Application, geography, and market size to highlight emerging pockets of opportunity. With a transparent methodology based on hundreds of bottom-up qualitative and quantitative market inputs, this study forecast offers a highly nuanced view of the current state and future trajectory in the global Collaborating Electric Gripper.

This report presents a comprehensive overview, market shares, and growth opportunities of Collaborating Electric Gripper market by product type, application, key manufacturers and key regions and countries.

Market Segmentation

Segmentation by Type:

Two-finger

Three-finger

Others

Segmentation by Gripping Force:

1-50 N

50-100 N

100-150 N

150-200 N

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Others

Segmentation by Stroke:

Below 50 mm

50–100 mm

Above 100 mm

Segmentation by Application:

3C Electronics

Automotive

Machining

Logistics

Others

This report also splits the market by region:

Americas

United States

Canada

Mexico

Brazil

APAC

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China

Japan

Korea

Southeast Asia

India

Australia

Europe

Germany

France

UK

Italy

Russia

Middle East & Africa

Egypt

South Africa

Israel

Turkey

GCC Countries

The below companies that are profiled have been selected based on inputs gathered

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from primary experts and analysing the company's coverage, product portfolio, its market penetration.

SMC Corporation

Onrobot

FESTO

SCHUNK

Zimmer Group

Weiss Robotics

Weiss Robotics

Robotiq

Gimatic

Kawasaki Robotics

Koganei

Garcia Marin System

Emerson Electric

IAI America

Destaco

IMI Bimba

PHD Inc

DH ROBOTICS

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RobusMotion

Huiling-tech

Fito Automation

Wommer

Mindman Industrial

Chelic

Key Questions Addressed in this Report

What is the 10-year outlook for the global Collaborating Electric Gripper market?

What factors are driving Collaborating Electric Gripper market growth, globally and by region?

Which technologies are poised for the fastest growth by market and region?

How do Collaborating Electric Gripper market opportunities vary by end market size?

How does Collaborating Electric Gripper break out by Type, by Application?

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