

Global 3D Vision Sensor for Embodied Intelligent Robots Market Growth (Status and Outlook) 2026-2032

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Abstracts

The global 3D Vision Sensor for Embodied Intelligent Robots market size is predicted to grow from US\$ 146 million in 2025 to US\$ 2862 million in 2032; it is expected to grow at a CAGR of 53.9% from 2026 to 2032.

3D vision sensors mainly obtain the spatial coordinate information of objects through 3D reconstruction technology, so that they can accurately perceive the distance, volume and size of objects, providing embodied intelligent robots with three-dimensional perception capabilities similar to human vision. The current main technologies for 3D reconstruction include structured light, iToF, dToF, stereo vision, Lidar, industrial three-dimensional measurement, etc. Humanoid robot visual sensing technology mainly uses multi-eye stereo vision and iToF methods.

This report presents a comprehensive overview, market shares, and growth opportunities of 3D Vision Sensor for Embodied Intelligent Robots market by product type, application, key players and key regions and countries.

Segmentation by Type:

Based on Multi-Eye Stereo Vision

Based on iToF

Segmentation by Application:

Base-Type Robot

Wheeled Robot

Tracked Robot

Quadruped Robot

Humanoid Robot

Bionic Robot

This report also splits the market by region:

United States

China

Europe

Other regions

Japan

South Korea

Southeast Asia

Rest of world

The report also presents the market competition landscape and a corresponding detailed analysis of the major players in the market. The key players covered in this report:

Cognex (USA)

Basler (Germany)

Keyence (Japan)

Omron (Japan)

Obi Zhongguang (China)

Weijing Intelligent (China)

Distant space and time (China)

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