

Global Tactile Data Acquisition Service Market 2026 by Company, Regions, Type and Application, Forecast to 2032

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Abstracts

According to our (Global Info Research) latest study, the global Tactile Data Acquisition Service market size was valued at US\$ 840 million in 2025 and is forecast to a readjusted size of US\$ 3147 million by 2032 with a CAGR of 20.7% during review period.

Tactile data acquisition services are specialized data services that capture, synchronize, process, and structure tactile information—centered on physical contact between robots, objects, human bodies, and the environment—to produce deliverable datasets. This research primarily covers a service ecosystem comprising tactile sensors, force/torque sensors, vision-based tactile devices, robotic dexterous hands or grippers, teleoperation systems, acquisition software, and data processing infrastructure. Core data includes contact pressure, normal force, shear force, deformation, slip, vibration, surface texture, contact geometry, temperature, and tactile images; high-end systems further synchronize the acquisition of tactile information with visual data, robot joint states, motion trajectories, and operational commands.

Key Findings

Tactile data has become critical for dexterous manipulation.

Multimodal data acquisition is replacing single-mode force measurement.

Embodied AI is driving the demand for real-world interaction data.

High-frequency data acquisition supports training for complex contact-based manipulation.

Industrial robotics remains the primary commercial application scenario.

Industry Trends

Tactile data acquisition services are evolving from sensor-centric measurement operations into data infrastructure designed for physical interaction. Early tactile systems primarily recorded pressure, force, or contact distribution for engineering testing and quality inspection. With the rise of embodied AI, the market now demands synchronized data—encompassing tactile, visual, proprioceptive, and action states—that can feed directly into robot learning pipelines. Consequently, the value of tactile data has expanded beyond measurement and analysis to include model training, policy learning, manipulation assessment, and automated recovery.

Market Dynamics

Driving Factors

The primary growth driver for tactile data acquisition services is the increasing demand for robots capable of complex contact-based manipulation. Tasks such as grasping, insertion, fastening, pressing, manipulating flexible objects, and detecting slippage are difficult to perform reliably using vision alone; robots require additional information regarding contact occurrence, direction, force magnitude, and material deformation. Tactile information becomes particularly crucial when target positioning is imprecise, vision is obstructed, or when dealing with transparent, flexible, or complex-structured objects. XELA views industrial tasks like insertion and assembly as key applications for tactile sensing, utilizing contact and force feedback to help robots detect deviations and adjust their pose and manipulation force in real-time.

Limiting Factors

The production costs and engineering complexity associated with high-quality, real-world tactile data remain significant barriers to market expansion. Unlike image or text data, tactile data must be generated through physical contact between sensors and real

objects; thus, data acquisition efficiency is constrained by factors such as robot hardware, human operators, task execution speed, and sensor durability. High-resolution systems also require rigorous calibration and precise temporal synchronization with robot state and visual data. Data formats vary significantly across tactile technologies: vision-based tactile sensors typically generate image-like contact data, force arrays primarily output multi-dimensional force information, and electronic skins produce high-density spatiotemporal signals. This heterogeneity increases the costs associated with data cleaning and format standardization.

Market Opportunities

Training-grade tactile datasets designed for embodied foundation models, dexterous manipulation models, and humanoid robots represent the market opportunity with the greatest future potential. As robots evolve from simple pick-and-place operations to general-purpose manipulation, tactile sensing provides crucial information—such as contact states, friction, material properties, deformation, and slippage—that cameras struggle to reliably assess. Consequently, integrating tactile data with visual data, proprioceptive states, language instructions, and motion trajectories into a unified dataset offers significantly higher training value than isolated sensor recordings.

Industry Risks and Challenges

A core long-term challenge for the industry is establishing data standards that are reusable across diverse tactile technologies and robot platforms. Tactile data varies widely in terms of sensor form factor, force range, taxel density, sampling frequency, coordinate systems, contact materials, and calibration methods; this makes cross-platform data integration and joint model training significantly more complex than handling traditional visual data. Data quality is another critical issue, as repeated physical contact can lead to sensor drift, wear, changes in frictional conditions, and reduced trajectory repeatability. For AI training, simply increasing data volume does not guarantee improved model capabilities; factors such as task coverage, the diversity of contact scenarios, the accuracy of force calibration, and the quality of motion label synchronization are equally important. Furthermore, adapting tactile input for multimodal foundation models remains in the exploratory stage, with various technical approaches emerging—ranging from raw signals and tactile images to processed force vectors and learned latent space representations. Moving forward, service providers must continuously balance data precision, acquisition efficiency, hardware reliability, and data

costs.

Value Chain Analysis

The upstream segment of the tactile data acquisition service value chain comprises tactile sensing technologies, force/torque sensors, vision-based tactile sensors, electronic skin, robotic dexterous hands and grippers, data acquisition electronics, cameras, motion capture equipment, edge computing modules, teleoperation hardware, and data storage resources. These foundational components determine the types of physical information that can be captured and set the technical upper limits of the resulting datasets.

Midstream service providers create value through activities such as experimental design, object and task selection, robotic or manual operation, multimodal synchronization, sensor calibration, data cleaning, annotation, trajectory segmentation, quality control, and dataset management and delivery. The market is shifting from pure hardware sales toward a combined "hardware + software + data service" model. For instance, companies like Daimon have developed a product ecosystem encompassing vision-based tactile sensors, datasets, teleoperation data acquisition systems, and Data-as-a-Service (DaaS) offerings, while Pasini is simultaneously targeting the markets for multidimensional tactile hardware and embodied AI data clouds. Downstream customers further utilize this data for embodied foundation models, dexterous manipulation by humanoid and industrial robots, medical robotics, prosthetics and rehabilitation, service robots, and haptic research. Consequently, future value creation depends increasingly on factors such as the volume of effective interaction trajectories, multimodal completeness, annotation quality, data reproducibility, and seamless integration with model training workflows, rather than merely on the unit price of individual sensors.

Market Segment Analysis

Based on the number of synchronized haptic modalities, haptic data acquisition services can be categorized into: single-modal services (1 modality); basic multimodal services (2–3 modalities); advanced multimodal services (4–6 modalities); and full-modal haptic services (7 or more modalities). The market is shifting toward advanced multimodal capabilities because dexterous robots require not only the detection of contact but also the simultaneous identification of force direction and magnitude, slippage, surface

texture, and object deformation.

Downstream Market Opportunities

Embodied AI and humanoid robotics represent the most strategically valuable downstream markets for haptic data acquisition services; haptic information enhances capabilities in dexterous grasping, fine manipulation, contact state assessment, and adaptation to unknown objects. Industrial manufacturing stands out as one of the sectors with the strongest commercialization foundations; tasks such as plugging/unplugging, assembly, connector handling, grinding, press-fitting, and flexible material handling often suffer from errors when relying solely on vision, whereas haptic feedback enables robots to achieve finer control.

Report Scope

This report is a detailed and comprehensive analysis for global Tactile Data Acquisition Service market. Both quantitative and qualitative analyses are presented by company, by region & country, by Type and by Application. As the market is constantly changing, this report explores the competition, supply and demand trends, as well as key factors that contribute to its changing demands across many markets. Company profiles and product examples of selected competitors, along with market share estimates of some of the selected leaders for the year 2025, are provided.

Key Features:

Global Tactile Data Acquisition Service market size and forecasts, in consumption value (\$ Million), 2021-2032

Global Tactile Data Acquisition Service market size and forecasts by region and country, in consumption value (\$ Million), 2021-2032

Global Tactile Data Acquisition Service market size and forecasts, by Type and by Application, in consumption value (\$ Million), 2021-2032

Global Tactile Data Acquisition Service market shares of main players, in revenue (\$ Million), 2021-2026

The Primary Objectives in This Report Are:

To determine the size of the total market opportunity of global and key countries

To assess the growth potential for Tactile Data Acquisition Service

To forecast future growth in each product and end-use market

To assess competitive factors affecting the marketplace

This report profiles key players in the global Tactile Data Acquisition Service market based on the following parameters - company overview, revenue, gross margin, product portfolio, geographical presence, and key developments. Key companies covered as a part of this study include GelSight, Tekscan, ATI Industrial Automation, Pressure Profile Systems, Shadow Robot, Touchlab, Tacterion, WEISS Robotics, OnRobot, PaXini Tech, etc.

This report also provides key insights about market drivers, restraints, opportunities, new product launches or approvals.

Tactile Data Acquisition Service market is split by Type and by Application. For the period 2021-2032, the growth among segments provides accurate calculations and forecasts for Consumption Value by Type and by Application. This analysis can help you expand your business by targeting qualified niche markets.

Market segmentation

Market segment by Type

Single-Modality Acquisition Platform (1 Modality)

Basic Multimodal Platform (2–3 Modalities)

Advanced Multimodal Platform (4–6 Modalities)

Full-Modality Acquisition Platform (?7 Modalities)

Market segment by Tactile Sampling Frequency

Low-Frequency Data Acquisition Platform

Standard Data Acquisition Platform

High-Frequency Data Acquisition Platform

Ultra-High-Frequency Data Acquisition Platform

Market segment by Synchronization Delay

Offline Synchronization Type

Near-Real-Time Synchronization Type

Real-Time Synchronization Type

Ultra-Low-Latency Synchronization Type

Market segment by Application

Embodied AI and Humanoid Robots

Automotive Manufacturing Industry

Consumer Electronics Industry

Logistics Industry

Healthcare Industry

Others

Market segment by players, this report covers

GelSight

Tekscan

ATI Industrial Automation

Pressure Profile Systems

Shadow Robot

Touchlab

Tacterion

WEISS Robotics

OnRobot

PaXini Tech

Xense Robotics

Daimon Robotics

AgileTact

ViTai Robotics

SaiGan Technology

XELA Robotics

Touchence

Nitta

WACOH-TECH

Leprino

Market segment by regions, regional analysis covers

North America (United States, Canada and Mexico)

Europe (Germany, France, UK, Russia, Italy and Rest of Europe)

Asia-Pacific (China, Japan, South Korea, India, Southeast Asia and Rest of Asia-Pacific)

South America (Brazil, Rest of South America)

Middle East & Africa (Turkey, Saudi Arabia, UAE, Rest of Middle East & Africa)

Chapter Outline

Chapter 1, to describe Tactile Data Acquisition Service product scope, market overview, market estimation caveats and base year.

Chapter 2, to profile the top players of Tactile Data Acquisition Service, with revenue, gross margin, and global market share of Tactile Data Acquisition Service from 2021 to 2026.

Chapter 3, the Tactile Data Acquisition Service competitive situation, revenue, and global market share of top players are analyzed emphatically by landscape contrast.

Chapter 4 and 5, to segment the market size by Type and by Application, with consumption value and growth rate by Type, by Application, from 2021 to 2032.

Chapter 6, 7, 8, 9, and 10, to break the market size data at the country level, with revenue and market share for key countries in the world, from 2021 to 2026. and Tactile Data Acquisition Service market forecast, by regions, by Type and by Application, with consumption value, from 2027 to 2032.

Chapter 11, market dynamics, drivers, restraints, trends, Porters Five Forces analysis.

Chapter 12, the key raw materials and key suppliers, and industry chain of Tactile Data

Acquisition Service.

Chapter 13, to describe Tactile Data Acquisition Service research findings and conclusion.

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