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Global Six-Dimensional Force Sensor Calibration Equipment Market 2026 by Manufacturers, Regions, Type and Application, Forecast to 2032

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Abstracts

According to our (Global Info Research) latest study, the global Six-Dimensional Force Sensor Calibration Equipment market size was valued at US$ 331 million in 2025 and is forecast to a readjusted size of US$ 577 million by 2032 with a CAGR of 8.2% during review period.

In 2025, global Six-Dimensional Force Sensor Calibration Equipment production reached approximately 2k units , with an average global market price of around US$160k per unit.

Six-dimensional force sensor calibration equipment is specialized testing equipment used for mechanical loading, signal acquisition, accuracy calibration, and decoupling-matrix calculation of six-axis force/torque sensors. It is designed to calibrate sensor outputs under three orthogonal forces, Fx, Fy, Fz, and three torques, Mx, My, and Mz. The equipment typically consists of a high-rigidity mechanical loading platform, standard force sources or weight-loading mechanisms, torque-loading mechanisms, precision displacement adjustment units, fixtures, reference sensors, data acquisition systems, signal-conditioning modules, control software, and calibration algorithms. It can perform single-axis loading, multi-axis coupled loading, forward and reverse loading, repeatability testing, linearity testing, hysteresis testing, zero-drift testing, and temperature compensation testing. Because six-dimensional force sensors have complex multi-axis coupling characteristics, ordinary single-axis calibration devices cannot complete full calibration, so dedicated six-axis loading and decoupling calibration systems are required. Such equipment is widely used for robotic six-axis force sensors, collaborative robot wrist sensors, humanoid robot force-sensing modules, medical robots, aerospace testing, precision assembly, research institutes, and sensor

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manufacturers. It is a core process tool for ensuring the measurement accuracy, consistency, and reliability of six-dimensional force sensors.

The upstream supply chain of six-dimensional force sensor calibration equipment mainly includes high-strength steel, aluminum alloy, stainless steel, granite bases, precision linear guides, ball screws, servo motors, reducers, loading actuators, standard weights, reference force sensors, torque sensors, displacement sensors, encoders, data acquisition cards, signal-conditioning modules, industrial computers, motion control cards, fixtures, temperature-control modules, and calibration software algorithms. High-rigidity mechanical structures, reference force accuracy, loading-control stability, data acquisition precision, and decoupling algorithms directly determine calibration performance. Representative upstream companies include HBK, Vishay, TE Connectivity, ATI Industrial Automation, Kistler, Interface, FUTEK, MTS, ZwickRoell, Instron, THK, HIWIN, NSK, SKF, Siemens, Schneider Electric, Omron, Keyence, National Instruments, and Advantech. The midstream sector consists of calibration equipment manufacturers, precision measurement equipment companies, robot testing equipment suppliers, automation system integrators, and scientific instrument manufacturers responsible for mechanical loading system design, reference instrument configuration, control system development, calibration software, customized fixtures, and final equipment delivery. Downstream applications mainly include six-axis force sensor manufacturers, robot companies, collaborative robot manufacturers, humanoid robot companies, medical robot companies, aerospace research institutions, automotive testing laboratories, semiconductor equipment companies, university laboratories, and metrology institutes. Representative users include ATI Industrial Automation, SRI Sensor, Kunwei Technology, Link-Touch, XJCSENSOR, Keli Sensing, ABB, FANUC, Yaskawa, KUKA, Universal Robots, Tesla, Figure AI, Agility Robotics, Boston Dynamics, Intuitive Surgical, Applied Materials, ASML, Tokyo Electron, Siemens, Bosch, national metrology institutes, and university research laboratories.

The six-dimensional force sensor calibration equipment market is currently characterized by small-batch demand, high precision requirements, and strong customization. Demand mainly comes from six-axis force sensor manufacturers, robot companies, research institutes, metrology organizations, and high-end equipment manufacturers. Key market trends include automated loading, multi-axis coupled calibration, use of high-precision reference instruments, intelligent decoupling algorithms, traceable calibration data, and improved production-line calibration capability. Growth is driven by rising demand for six-axis force sensors in collaborative robots, humanoid robots, medical robots, and precision manufacturing, as well as the expansion of domestic six-axis force sensor manufacturers requiring factory calibration

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equipment. Major challenges include limited market size, fragmented customer requirements, high customization, long R&D and validation cycles, incomplete standardization, and high cost of precision reference instruments. Overall, the market is expected to evolve from laboratory standalone calibration devices toward automated, batch-oriented, software-driven, and production-line-integrated calibration systems.

This report is a detailed and comprehensive analysis for global Six-Dimensional Force Sensor Calibration Equipment market. Both quantitative and qualitative analyses are presented by manufacturers, by region & country, by Type and by Application. As the market is constantly changing, this report explores the competition, supply and demand trends, as well as key factors that contribute to its changing demands across many markets. Company profiles and product examples of selected competitors, along with market share estimates of some of the selected leaders for the year 2025, are provided.

Key Features:

Global Six-Dimensional Force Sensor Calibration Equipment market size and forecasts, in consumption value ($ Million), sales quantity (Units), and average selling prices (US$/Unit), 2021-2032

Global Six-Dimensional Force Sensor Calibration Equipment market size and forecasts by region and country, in consumption value ($ Million), sales quantity (Units), and average selling prices (US$/Unit), 2021-2032

Global Six-Dimensional Force Sensor Calibration Equipment market size and forecasts, by Type and by Application, in consumption value ($ Million), sales quantity (Units), and average selling prices (US$/Unit), 2021-2032

Global Six-Dimensional Force Sensor Calibration Equipment market shares of main players, shipments in revenue ($ Million), sales quantity (Units), and ASP (US$/Unit), 2021-2026

The Primary Objectives in This Report Are:

To determine the size of the total market opportunity of global and key countries

To assess the growth potential for Six-Dimensional Force Sensor Calibration Equipment

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To forecast future growth in each product and end-use market

To assess competitive factors affecting the marketplace

This report profiles key players in the global Six-Dimensional Force Sensor Calibration Equipment market based on the following parameters - company overview, sales quantity, revenue, price, gross margin, product portfolio, geographical presence, and key developments. Key companies covered as a part of this study include ATI Industrial Automation, HBK, Kistler, Interface, FUTEK, AMETEK, Kunwei Sensing Technology, Right Measurement and Control system, Starsin Sensing Technology, etc.

This report also provides key insights about market drivers, restraints, opportunities, new product launches or approvals.

Market Segmentation

Six-Dimensional Force Sensor Calibration Equipment market is split by Type and by Application. For the period 2021-2032, the growth among segments provides accurate calculations and forecasts for consumption value by Type, and by Application in terms of volume and value. This analysis can help you expand your business by targeting qualified niche markets.

Market segment by Type

Vertical

Horizontal

Gantry

Others

Market segment by Automation Level

Semi-Automatic

Fully Automatic

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Market segment by Torque Range

- 0.5 N?m - 50 N?m
- 50 N?m - 500 N?m
- Others

Market segment by Application

- Robotics
- Aerospace
- Scientific Research
- Sensor Manufacturing Enterprises
- Others

Major players covered

- ATI Industrial Automation
- HBK
- Kistler
- Interface
- FUTEK
- AMETEK
- Kunwei Sensing Technology

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Right Measurement and Control system

Starsin Sensing Technology

Market segment by region, regional analysis covers

North America (United States, Canada, and Mexico)

Europe (Germany, France, United Kingdom, Russia, Italy, and Rest of Europe)

Asia-Pacific (China, Japan, Korea, India, Southeast Asia, and Australia)

South America (Brazil, Argentina, Colombia, and Rest of South America)

Middle East & Africa (Saudi Arabia, UAE, Egypt, South Africa, and Rest of Middle East & Africa)

The content of the study subjects, includes a total of 15 chapters:

Chapter 1, to describe Six-Dimensional Force Sensor Calibration Equipment product scope, market overview, market estimation caveats and base year.

Chapter 2, to profile the top manufacturers of Six-Dimensional Force Sensor Calibration Equipment, with price, sales quantity, revenue, and global market share of Six-Dimensional Force Sensor Calibration Equipment from 2021 to 2026.

Chapter 3, the Six-Dimensional Force Sensor Calibration Equipment competitive situation, sales quantity, revenue, and global market share of top manufacturers are analyzed emphatically by landscape contrast.

Chapter 4, the Six-Dimensional Force Sensor Calibration Equipment breakdown data are shown at the regional level, to show the sales quantity, consumption value, and growth by regions, from 2021 to 2032.

Chapter 5 and 6, to segment the sales by Type and by Application, with sales market share and growth rate by Type, by Application, from 2021 to 2032.

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Chapter 7, 8, 9, 10 and 11, to break the sales data at the country level, with sales quantity, consumption value, and market share for key countries in the world, from 2021 to 2026.and Six-Dimensional Force Sensor Calibration Equipment market forecast, by regions, by Type, and by Application, with sales and revenue, from 2027 to 2032.

Chapter 12, market dynamics, drivers, restraints, trends, and Porters Five Forces analysis.

Chapter 13, the key raw materials and key suppliers, and industry chain of Six-Dimensional Force Sensor Calibration Equipment.

Chapter 14 and 15, to describe Six-Dimensional Force Sensor Calibration Equipment sales channel, distributors, customers, research findings and conclusion.

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