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Global Rotary Actuators for Robotics Market 2026 by Manufacturers, Regions, Type and Application, Forecast to 2032

https://marketpublishers.com/r/G17F3700AD7DEN.html
Date: September 2026
Pages: 115
Price: US$ 3,480.00 (Single User License)
ID: G17F3700AD7DEN

Abstracts

According to our (Global Info Research) latest study, the global Rotary Actuators for Robotics market size was valued at US$ 2531 million in 2025 and is forecast to a readjusted size of US$ 6302 million by 2032 with a CAGR of 13.9% during review period.

Rotary actuators for robotics are mechatronic motion units designed for robot joints and rotary axes, with controlled angular displacement and torque output as their core functions. A typical unit combines a brushless servo motor with a strain-wave, planetary, cycloidal, or direct-drive transmission architecture, together with bearings, encoders, and optional integrated drives, brakes, and torque sensors. Products are available in hollow-shaft and non-hollow-shaft configurations and generally support closed-loop position, velocity, and torque control through interfaces such as CAN or EtherCAT. This study focuses on rotary actuators procured as independent units for joints in industrial robots, mobile robots, medical and rehabilitation robots, commercial service robots, and special-purpose robotic systems. Key purchasing and engineering parameters include peak and rated torque, torque density, backlash, efficiency, speed, positioning accuracy, thermal capability, reliability, and integration level. The market sits at the intersection of precision gearing, servo motors, sensing, and motion control, with an estimated industry-wide comprehensive gross margin of approximately 38%.

Market Trends

Rotary actuators for robotics are shifting from separately sourced motors, reducers, and encoders toward highly integrated joint modules. Hollow cable routing, dual encoders,

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torque sensing, brakes, motor drives, and communications are increasingly combined in compact housings. Low-ratio planetary and quasi-direct-drive architectures are gaining ground in dynamic mobile and humanoid robots, while strain-wave designs retain an advantage in precision joints requiring low backlash and high reduction ratios. Higher torque density, lower mass and inertia, improved thermal management, and support for real-time buses such as CAN FD and EtherCAT are becoming the main directions of product development.

Drivers

Upgrades in manufacturing automation, rising labor costs, expansion of warehouse and logistics robots, and development of embodied-AI and humanoid platforms are expanding demand for joint actuation. Standardized rotary actuators reduce duplicated motor, gearbox, sensing, and controller development for robot OEMs and can shorten prototype iteration and volume-production introduction cycles.

Restraints

Precision reducers, thin-section bearings, high-performance magnetic materials, encoders, and torque sensors remain meaningful cost contributors. The tradeoff between high torque and low mass also complicates thermal design and lifetime validation. Some high-end applications require lengthy reliability, functional-safety, and certification processes, slowing entry by newer suppliers.

Opportunities

Humanoid robots, mobile manipulators, warehouse handling robots, rehabilitation and surgical robots, and outdoor inspection robots are creating new demand for modular joints. Actuator platforms with standardized mechanical interfaces, common communications, and scalable control software are better positioned for reuse across multiple robot models and higher-volume procurement.

Challenges

Gear life, backlash retention, bearing stiffness, and thermal derating under high-speed impact and frequent reversing loads remain core engineering challenges. As robot

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OEMs increase vertical integration, independent suppliers must sustain differentiation across torque density, control algorithms, reliability validation, interface ecosystems, and manufacturing cost.

Industry Chain Analysis

Upstream inputs include permanent-magnet materials, copper and electrical steel, frameless and servo motors, strain-wave, planetary and cycloidal reducers, precision bearings, encoders, torque sensors, power electronics and controllers, brakes, and structural components. Midstream suppliers integrate mechanical, motor, sensing, and drive-control systems and perform assembly, calibration, and lifetime testing. Downstream customers include industrial robot, mobile robot, medical and rehabilitation robot, commercial service robot, and special-purpose robot manufacturers and system integrators. Value is concentrated in precision transmission, motor power density, sensing and control, thermal management, and production consistency, while scale manufacturing is critical to cost competitiveness in the midrange market.

Segment Insights

By transmission type, planetary and low-ratio architectures are well suited to legged and mobile joints requiring impact tolerance, high dynamics, and backdrivability. Strain-wave designs remain strong in compact, low-backlash, high-ratio joints; cycloidal designs favor higher load and rigidity; and direct-drive designs offer low backlash and fast response but place greater demands on motor size, continuous torque, and cooling. Torque classes separate small distal joints from arm, leg, waist, and heavy industrial axes, while hollow-shaft and integrated-drive configurations continue to gain adoption.

Downstream Market Opportunities

Manufacturing and industrial automation retain the largest installed base and stable replacement demand, while logistics and warehousing add growth from mobile manipulation, sorting, and material handling systems with stronger requirements for impact tolerance and cost. Healthcare and rehabilitation applications place greater emphasis on low noise, smooth motion, safety redundancy, and certification, while commercial services and defense and public safety applications value lightweight construction, environmental robustness, and serviceability, creating differentiated higher-value opportunities.

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Regional Insights

Asia-Pacific is the most concentrated region for robot manufacturing and new deployments. China combines large robot production volumes, a broad component supply chain, and active investment in humanoid robotics, while Japan and South Korea have strong foundations in precision motion components and robot manufacturing. Europe emphasizes high-precision industrial automation, collaborative robotics, medical equipment, and functional safety, while North America remains active in AI robotics, warehouse automation, and new mobile and humanoid platforms. Supply-chain localization and regional volume-production capability will increasingly affect customer qualification.

Competitive Landscape Analysis

Competition is led by two broad supplier groups: established motion-control companies with deep expertise in precision gearing, servo motors, and industrial reliability, and integrated-actuator specialists built around modular robotics. Established suppliers are stronger in lifetime performance, precision, and industrial qualification, while specialists tend to compete on integration, software interfaces, fast iteration, and cost. Future differentiation will center on torque density, backlash, efficiency, thermal performance, lifetime, safety functions, communications compatibility, and volume pricing, while increasing vertical integration by robot OEMs will pressure standalone actuator suppliers to deliver clearer system-level value.

Report Scope

This report is a detailed and comprehensive analysis for global Rotary Actuators for Robotics market. Both quantitative and qualitative analyses are presented by manufacturers, by region & country, by Type and by Application. As the market is constantly changing, this report explores the competition, supply and demand trends, as well as key factors that contribute to its changing demands across many markets. Company profiles and product examples of selected competitors, along with market share estimates of some of the selected leaders for the year 2025, are provided.

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Key Features:

Global Rotary Actuators for Robotics market size and forecasts, in consumption value ($ Million), sales quantity (Units), and average selling prices (US$/Unit), 2021-2032

Global Rotary Actuators for Robotics market size and forecasts by region and country, in consumption value ($ Million), sales quantity (Units), and average selling prices (US$/Unit), 2021-2032

Global Rotary Actuators for Robotics market size and forecasts, by Type and by Application, in consumption value ($ Million), sales quantity (Units), and average selling prices (US$/Unit), 2021-2032

Global Rotary Actuators for Robotics market shares of main players, shipments in revenue ($ Million), sales quantity (Units), and ASP (US$/Unit), 2021-2026

The Primary Objectives in This Report Are:

To determine the size of the total market opportunity of global and key countries

To assess the growth potential for Rotary Actuators for Robotics

To forecast future growth in each product and end-use market

To assess competitive factors affecting the marketplace

This report profiles key players in the global Rotary Actuators for Robotics market based on the following parameters - company overview, sales quantity, revenue, price, gross margin, product portfolio, geographical presence, and key developments. Key companies covered as a part of this study include Harmonic Drive Systems, Nabtesco, Nidec Drive Technology, Maxon, ROBOTIS, HEBI Robotics, Wittenstein, Synapticon, MAB Robotics, Nanchang Kude Intelligent Technology, etc.

This report also provides key insights about market drivers, restraints, opportunities, new product launches or approvals.

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Rotary Actuators for Robotics market is split by Type and by Application. For the period 2021-2032, the growth among segments provides accurate calculations and forecasts for consumption value by Type, and by Application in terms of volume and value. This analysis can help you expand your business by targeting qualified niche markets.

Market Segmentation

Market segment by Type

Strain-Wave Actuators

Planetary Gear Actuators

Cycloidal Gear Actuators

Direct-Drive Actuators

Other Actuators

Market segment by Peak Torque

?20 Nm

>20–50 Nm

>50–100 Nm

>100 Nm

Market segment by Center Bore

Hollow-Shaft Actuators

Non-Hollow-Shaft Actuators

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Market segment by Drive Integration

Integrated-Drive Actuators

External-Drive Actuators

Market segment by Application

Manufacturing and Industrial Automation

Logistics and Warehousing

Healthcare and Rehabilitation

Commercial Services

Defense and Public Safety

Others

Major players covered

Harmonic Drive Systems

Nabtesco

Nidec Drive Technology

Maxon

ROBOTIS

HEBI Robotics

Wittenstein

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Synapticon

MAB Robotics

Nanchang Kude Intelligent Technology

Suzhou Micro Actuator Technology

RobStride Dynamics

Oriental Motor

Market segment by region, regional analysis covers

North America (United States, Canada, and Mexico)

Europe (Germany, France, United Kingdom, Russia, Italy, and Rest of Europe)

Asia-Pacific (China, Japan, Korea, India, Southeast Asia, and Australia)

South America (Brazil, Argentina, Colombia, and Rest of South America)

Middle East & Africa (Saudi Arabia, UAE, Egypt, South Africa, and Rest of Middle East & Africa)

Chapter Outline

Chapter 1, to describe Rotary Actuators for Robotics product scope, market overview, market estimation caveats and base year.

Chapter 2, to profile the top manufacturers of Rotary Actuators for Robotics, with price, sales quantity, revenue, and global market share of Rotary Actuators for Robotics from 2021 to 2026.

Chapter 3, the Rotary Actuators for Robotics competitive situation, sales quantity, revenue, and global market share of top manufacturers are analyzed emphatically by

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landscape contrast.

Chapter 4, the Rotary Actuators for Robotics breakdown data are shown at the regional level, to show the sales quantity, consumption value, and growth by regions, from 2021 to 2032.

Chapter 5 and 6, to segment the sales by Type and by Application, with sales market share and growth rate by Type, by Application, from 2021 to 2032.

Chapter 7, 8, 9, 10 and 11, to break the sales data at the country level, with sales quantity, consumption value, and market share for key countries in the world, from 2021 to 2026.and Rotary Actuators for Robotics market forecast, by regions, by Type, and by Application, with sales and revenue, from 2027 to 2032.

Chapter 12, market dynamics, drivers, restraints, trends, and Porters Five Forces analysis.

Chapter 13, the key raw materials and key suppliers, and industry chain of Rotary Actuators for Robotics.

Chapter 14 and 15, to describe Rotary Actuators for Robotics sales channel, distributors, customers, research findings and conclusion.

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