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Global Robot Six-axis Force Torque Sensor Market 2026 by Manufacturers, Regions, Type and Application, Forecast to 2032

https://marketpublishers.com/r/G5CF5D3F0B63EN.html
Date: August 2026
Pages: 104
Price: US$ 3,480.00 (Single User License)
ID: G5CF5D3F0B63EN

Abstracts

According to our (Global Info Research) latest study, the global Robot Six-axis Force Torque Sensor market size was valued at US$ 885 million in 2025 and is forecast to a readjusted size of US$ 2863 million by 2032 with a CAGR of 18.2% during review period.

In 2025, global Robot Six-axis Force Torque Sensor production reached approximately 905,263 units, with an average global market price of around USD 950 per unit.

The gross profit margin of major companies in the industry is between 31.64%?57.28%.

In 2025, the global production capacity of Robot Six-axis Force Torque Sensor was approximately 1.19 million units.

Robot Six-axis Force Torque Sensor is a precision sensor installed at robot wrists, joints or end-effectors to measure forces and torques along three linear axes and three rotational axes. It enables force control, compliant motion, assembly feedback, collision detection, polishing, grinding, teaching and human-robot interaction. The product is used in industrial robots, collaborative robots, surgical robots, humanoid robots, testing systems and automation equipment. The market includes six-axis force torque sensing units and integrated robot force sensors, but excludes single-axis load cells, ordinary torque sensors and robot controllers without force sensing functions.

The industry chain includes strain gauges, elastomer structures, semiconductor sensing elements, signal conditioning chips, printed circuit boards, connectors, housings, calibration equipment and software algorithms. Midstream production covers

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mechanical structure design, sensing element bonding, circuit integration, temperature compensation, multi-axis calibration, accuracy testing and reliability validation. Downstream demand comes from collaborative robots, industrial automation, humanoid robots, medical robots, precision assembly, surface finishing and research laboratories. Growth is driven by robotic dexterity, force-controlled automation, human-robot collaboration and intelligent manufacturing.

This report is a detailed and comprehensive analysis for global Robot Six-axis Force Torque Sensor market. Both quantitative and qualitative analyses are presented by manufacturers, by region & country, by Type and by Application. As the market is constantly changing, this report explores the competition, supply and demand trends, as well as key factors that contribute to its changing demands across many markets. Company profiles and product examples of selected competitors, along with market share estimates of some of the selected leaders for the year 2025, are provided.

Key Features:

Global Robot Six-axis Force Torque Sensor market size and forecasts, in consumption value ($ Million), sales quantity (K Units), and average selling prices (US$/Unit), 2021-2032

Global Robot Six-axis Force Torque Sensor market size and forecasts by region and country, in consumption value ($ Million), sales quantity (K Units), and average selling prices (US$/Unit), 2021-2032

Global Robot Six-axis Force Torque Sensor market size and forecasts, by Type and by Application, in consumption value ($ Million), sales quantity (K Units), and average selling prices (US$/Unit), 2021-2032

Global Robot Six-axis Force Torque Sensor market shares of main players, shipments in revenue ($ Million), sales quantity (K Units), and ASP (US$/Unit), 2021-2026

The Primary Objectives in This Report Are:

To determine the size of the total market opportunity of global and key countries

To assess the growth potential for Robot Six-axis Force Torque Sensor

To forecast future growth in each product and end-use market

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To assess competitive factors affecting the marketplace

This report profiles key players in the global Robot Six-axis Force Torque Sensor market based on the following parameters - company overview, sales quantity, revenue, price, gross margin, product portfolio, geographical presence, and key developments. Key companies covered as a part of this study include ATI Industrial Automation, Novanta, Bota Systems, HBM, Kunwei Technology, Link-touch, Xiamen Lisheng, Pasinic, BlueDot Touch, etc.

This report also provides key insights about market drivers, restraints, opportunities, new product launches or approvals.

Market Segmentation

Robot Six-axis Force Torque Sensor market is split by Type and by Application. For the period 2021-2032, the growth among segments provides accurate calculations and forecasts for consumption value by Type, and by Application in terms of volume and value. This analysis can help you expand your business by targeting qualified niche markets.

Market segment by Type

Strain Gauge Sensors

Capacitive Sensors

Piezoelectric Sensors

Market segment by Installation Position

Wrist-Mounted Sensors

End-Effector Integrated Sensors

Base-Mounted Sensors

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Market segment by Force Measurement Range

- Small Range??100 N?
- Medium Range?101?1000 N?
- Large Range??1000 N?

Market segment by Application

- Force-Controlled Assembly
- Grinding and Polishing
- Precision Handling and Manipulation
- Other

Major players covered

- ATI Industrial Automation
- Novanta
- Bota Systems
- HBM
- Kunwei Technology
- Link-touch
- Xiamen Lisheng
- Pasinic
- BlueDot Touch

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Market segment by region, regional analysis covers

North America (United States, Canada, and Mexico)

Europe (Germany, France, United Kingdom, Russia, Italy, and Rest of Europe)

Asia-Pacific (China, Japan, Korea, India, Southeast Asia, and Australia)

South America (Brazil, Argentina, Colombia, and Rest of South America)

Middle East & Africa (Saudi Arabia, UAE, Egypt, South Africa, and Rest of Middle East & Africa)

The content of the study subjects, includes a total of 15 chapters:

Chapter 1, to describe Robot Six-axis Force Torque Sensor product scope, market overview, market estimation caveats and base year.

Chapter 2, to profile the top manufacturers of Robot Six-axis Force Torque Sensor, with price, sales quantity, revenue, and global market share of Robot Six-axis Force Torque Sensor from 2021 to 2026.

Chapter 3, the Robot Six-axis Force Torque Sensor competitive situation, sales quantity, revenue, and global market share of top manufacturers are analyzed emphatically by landscape contrast.

Chapter 4, the Robot Six-axis Force Torque Sensor breakdown data are shown at the regional level, to show the sales quantity, consumption value, and growth by regions, from 2021 to 2032.

Chapter 5 and 6, to segment the sales by Type and by Application, with sales market share and growth rate by Type, by Application, from 2021 to 2032.

Chapter 7, 8, 9, 10 and 11, to break the sales data at the country level, with sales quantity, consumption value, and market share for key countries in the world, from 2021 to 2026.and Robot Six-axis Force Torque Sensor market forecast, by regions, by Type,

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and by Application, with sales and revenue, from 2027 to 2032.

Chapter 12, market dynamics, drivers, restraints, trends, and Porters Five Forces analysis.

Chapter 13, the key raw materials and key suppliers, and industry chain of Robot Six-axis Force Torque Sensor.

Chapter 14 and 15, to describe Robot Six-axis Force Torque Sensor sales channel, distributors, customers, research findings and conclusion.

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