

Global Robot Arm Gripper for Collaborative Robot Supply, Demand and Key Producers, 2026-2032

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Abstracts

The global Robot Arm Gripper for Collaborative Robot market size is expected to reach \$ 3444 million by 2032, rising at a market growth of 16.1% CAGR during the forecast period (2026-2032).

In 2025, global Robot Arm Gripper for Collaborative Robot production reached approximately 656 k units, with an average global market price of around US\$ 1,950 per unit, and a gross profit margin of approximately 20%-40%. Robot Arm Grippers for Collaborative Robots are end-of-arm gripping devices mounted on collaborative robot wrists to safely grasp, hold, move, position, and release workpieces. A typical product integrates a lightweight gripper body, electric or pneumatic actuator, fingers or suction interface, force or position sensing, control electronics, communication interface, robot mounting adapter, and programming software. Product types include electric parallel grippers, adaptive two-finger grippers, three-finger grippers, vacuum grippers, magnetic grippers, soft grippers, and application-specific gripping kits. Commercial products emphasize plug-and-play integration, fast deployment, intuitive programming, compatibility with major cobot brands, and safe use in shared human-robot workspaces. Robotiq lists adaptive grippers built for collaborative robots, while Universal Robots describes certified electric and pneumatic grippers within its cobot ecosystem.

The industrial chain of Robot Arm Grippers for Collaborative Robots includes upstream aluminum alloys, stainless steel, engineering plastics, elastomers, motors, reducers, screws, gears, pneumatic cylinders, vacuum generators, valves, magnets, sensors, encoders, controllers, PCBs, cables, connectors, communication chips, and surface-treatment materials. Midstream activities include mechanical design, gripping-force calculation, finger design, actuator integration, sensor integration, safety validation, control-software development, robot-interface adaptation, plug-and-play programming,

assembly, repeatability testing, gripping-force testing, endurance testing, environmental testing, and certification support. Downstream applications include machine tending, assembly, inspection, packaging, palletizing, laboratory automation, electronics manufacturing, food handling, pharmaceutical production, education, research, and small-batch flexible manufacturing.

The Robot Arm Gripper for Collaborative Robot market is expected to grow rapidly as small and medium-sized manufacturers adopt cobots for flexible automation tasks that require fast redeployment, simplified programming, and safe human-robot interaction. Demand is moving from basic open-close grippers toward intelligent gripping tools with adjustable force, programmable stroke, object detection, integrated sensing, plug-and-play software, and multi-brand robot compatibility. Electric adaptive grippers are gaining adoption in machine tending, light assembly, electronics, laboratory automation, and packaging because they can handle variable parts and reduce mechanical changeover work, while vacuum, magnetic, and soft grippers expand cobot use in cartons, sheet metal, food, fragile items, and irregular objects. Product development is focused on lighter structures, safer force limitation, modular fingers, tactile feedback, easier robot teach-pendant programming, energy-efficient actuation, and faster deployment. Key challenges include payload limits, price pressure, customized finger requirements, gripping reliability for irregular objects, safety certification, software compatibility, and competition from low-cost pneumatic or application-specific end effectors.

This report studies the global Robot Arm Gripper for Collaborative Robot production, demand, key manufacturers, and key regions.

This report is a detailed and comprehensive analysis of the world market for Robot Arm Gripper for Collaborative Robot and provides market size (US\$ million) and Year-over-Year (YoY) Growth, considering 2025 as the base year. This report explores demand trends and competition, as well as details the characteristics of Robot Arm Gripper for Collaborative Robot that contribute to its increasing demand across many markets.

Highlights and key features of the study

Global Robot Arm Gripper for Collaborative Robot total production and demand, 2021-2032, (K Units)

Global Robot Arm Gripper for Collaborative Robot total production value, 2021-2032, (USD Million)

Global Robot Arm Gripper for Collaborative Robot production by region & country, production, value, CAGR, 2021-2032, (USD Million) & (K Units), (based on production

site)

Global Robot Arm Gripper for Collaborative Robot consumption by region & country, CAGR, 2021-2032 & (K Units)

U.S. VS China: Robot Arm Gripper for Collaborative Robot domestic production, consumption, key domestic manufacturers and share

Global Robot Arm Gripper for Collaborative Robot production by manufacturer, production, price, value and market share 2021-2026, (USD Million) & (K Units)

Global Robot Arm Gripper for Collaborative Robot production by Type, production, value, CAGR, 2021-2032, (USD Million) & (K Units)

Global Robot Arm Gripper for Collaborative Robot production by Application, production, value, CAGR, 2021-2032, (USD Million) & (K Units)

This report profiles key players in the global Robot Arm Gripper for Collaborative Robot market based on the following parameters - company overview, production, value, price, gross margin, product portfolio, geographical presence, and key developments. Key companies covered as a part of this study include SCHUNK, Festo, Zimmer Group, SMC Corporation, Gimatic, Robotiq, EMI, OnRobot, Schmalz, Weiss Robotics, etc.

This report also provides key insights about market drivers, restraints, opportunities, new product launches or approvals.

Stakeholders would have ease in decision-making through various strategy matrices used in analyzing the World Robot Arm Gripper for Collaborative Robot market

Detailed Segmentation:

Each section contains quantitative market data including market by value (US\$ Millions), volume (production, consumption) & (K Units) and average price (US\$/Unit) by manufacturer, by Type, and by Application. Data is given for the years 2021-2032 by year with 2025 as the base year, 2026 as the estimate year, and 2027-2032 as the forecast year.

Global Robot Arm Gripper for Collaborative Robot Market, By Region:

United States

China

Europe

Japan

South Korea

ASEAN

India

Rest of World

Global Robot Arm Gripper for Collaborative Robot Market, Segmentation by Type:

Parallel Gripper

Angular Gripper

Others

Global Robot Arm Gripper for Collaborative Robot Market, Segmentation by Drive Method:

Electric Grippers

Pneumatic Grippers

Vacuum Grippers

Magnetic Grippers

Others

Global Robot Arm Gripper for Collaborative Robot Market, Segmentation by Gripping Force (N):

≤100

100-300

?300

Global Robot Arm Gripper for Collaborative Robot Market, Segmentation by Application:

Automotive Manufacturing

Pharmaceutical Manufacturing

Food and Beverage

Others

Companies Profiled:

SCHUNK

Festo

Zimmer Group

SMC Corporation

Gimatic

Robotiq

EMI

OnRobot

Schmalz

Weiss Robotics

PHD

CKD

Kitagawa Corporation

DH-Robotics

HITBOT

JODELL Robotics

HIWIN

ChangingTek Robotics

TESOLLO

KORAS Robotics

KCC

Piab

qb robotics

New Scale Robotics

Key Questions Answered:

1. How big is the global Robot Arm Gripper for Collaborative Robot market?
2. What is the demand of the global Robot Arm Gripper for Collaborative Robot market?
3. What is the year over year growth of the global Robot Arm Gripper for Collaborative Robot market?
4. What is the production and production value of the global Robot Arm Gripper for Collaborative Robot market?
5. Who are the key producers in the global Robot Arm Gripper for Collaborative Robot market?
6. What are the growth factors driving the market demand?

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