

Global Reducer for Humanoid Robots Rotary Joints Market 2026 by Manufacturers, Regions, Type and Application, Forecast to 2032

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Abstracts

According to our (Global Info Research) latest study, the global Reducer for Humanoid Robots Rotary Joints market size was valued at US\$ 219 million in 2025 and is forecast to a readjusted size of US\$ 1725 million by 2032 with a CAGR of 34.2% during review period.

The reducer for humanoid robots' rotary joints is a core precision transmission component connecting the power source and the actuator, converting the high-speed rotation of the motor into low-speed, high-torque output to ensure high precision and stability of joint motion, while optimizing transmission efficiency and load capacity, achieving a balance among weight, inertia, and dynamic performance to meet the control requirements of complex movements of humanoid robots. In 2025, global Reducer for Humanoid Robots Rotary Joints production reached approximately 1.01 million units with an average global market price of around US\$210 per unit.

The future development of Reducers for Humanoid Robots Rotary Joints will exhibit a trend of technological diversification and the deepening of domestic substitution, with corporate profit models transforming from the supply of individual components to high-integration joint modules. According to official announcements from Kedali Company, enterprises are proactively laying out the rotary joint track centered on reducers, entering the dexterous hand and core component markets by establishing joint ventures, thereby driving products from technological breakthroughs toward large-scale application. On the technological roadmap, quasi-direct drive has become the mainstream solution, driving reducers to evolve towards high torque density, high impact resistance, and lightweight design to meet the stringent requirements for dynamic performance and load capacity. Meanwhile, as a key component affecting

hardware costs, the domestication process of precision reducers is accelerating significantly; the craftsmanship level of leading domestic enterprises is improving, and their supply capabilities are increasingly robust, gradually breaking the foreign monopoly. The focus of industry competition will center on optimizing the balance between transmission efficiency and accuracy through structural innovation and material application to adapt to the mass production requirements of embodied intelligent robots, thereby bringing continuous growth space and profit enhancement for enterprises.

This report is a detailed and comprehensive analysis for global Reducer for Humanoid Robots Rotary Joints market. Both quantitative and qualitative analyses are presented by manufacturers, by region & country, by Type and by Application. As the market is constantly changing, this report explores the competition, supply and demand trends, as well as key factors that contribute to its changing demands across many markets. Company profiles and product examples of selected competitors, along with market share estimates of some of the selected leaders for the year 2025, are provided.

Key Features:

Global Reducer for Humanoid Robots Rotary Joints market size and forecasts, in consumption value (\$ Million), sales quantity (Units), and average selling prices (US\$/Unit), 2021-2032

Global Reducer for Humanoid Robots Rotary Joints market size and forecasts by region and country, in consumption value (\$ Million), sales quantity (Units), and average selling prices (US\$/Unit), 2021-2032

Global Reducer for Humanoid Robots Rotary Joints market size and forecasts, by Type and by Application, in consumption value (\$ Million), sales quantity (Units), and average selling prices (US\$/Unit), 2021-2032

Global Reducer for Humanoid Robots Rotary Joints market shares of main players, shipments in revenue (\$ Million), sales quantity (Units), and ASP (US\$/Unit), 2021-2026

The Primary Objectives in This Report Are:

To determine the size of the total market opportunity of global and key countries

To assess the growth potential for Reducer for Humanoid Robots Rotary Joints

To forecast future growth in each product and end-use market

To assess competitive factors affecting the marketplace

This report profiles key players in the global Reducer for Humanoid Robots Rotary Joints market based on the following parameters - company overview, sales quantity, revenue, price, gross margin, product portfolio, geographical presence, and key developments. Key companies covered as a part of this study include WITTENSTEIN, Nidec, Neugart, Rossi, LS Electric, SEW-Eurodrive, Flender, STOBBER, Harmonic Drive Systems, Schaeffler, etc.

This report also provides key insights about market drivers, restraints, opportunities, new product launches or approvals.

Market Segmentation

Reducer for Humanoid Robots Rotary Joints market is split by Type and by Application. For the period 2021-2032, the growth among segments provides accurate calculations and forecasts for consumption value by Type, and by Application in terms of volume and value. This analysis can help you expand your business by targeting qualified niche markets.

Market segment by Type

Harmonic Drive Reducer

Rotary Vector Reducer

Planetary Gear Reducer

Cycloidal Pinwheel Planetary Reducer

Market segment by Frame Size

≥22 mm

22?60 mm

60?120 mm

120?300 mm

?300 mm

Market segment by Reduction Ratio

3:1?10:1

10:1?50:1

50:1?200:1

?200:1

Market segment by Application

Industrial Manufacturing

Scientific Research and Education

Home Services

Others

Major players covered

WITTENSTEIN

Nidec

Neugart

Rossi

LS Electric

SEW-Eurodrive

Flender

STOBER

Harmonic Drive Systems

Schaeffler

GAM Enterprises

Sesame Motor

APEX Dynamics

LI MING Machinery

Newstart

Hubei Kofon Intelligent Transmission

Ningbo Zhongda Leader Intelligent Transmission

WANSHSIN Seikou (Hunan)

Shanghai Lian Heng Precision Machinery

Shenzhen Stonker Technology

Jiangsu Guomao Reducer

Leader Harmonious Drive Systems

Market segment by region, regional analysis covers

North America (United States, Canada, and Mexico)

Europe (Germany, France, United Kingdom, Russia, Italy, and Rest of Europe)

Asia-Pacific (China, Japan, Korea, India, Southeast Asia, and Australia)

South America (Brazil, Argentina, Colombia, and Rest of South America)

Middle East & Africa (Saudi Arabia, UAE, Egypt, South Africa, and Rest of Middle East & Africa)

The content of the study subjects, includes a total of 15 chapters:

Chapter 1, to describe Reducer for Humanoid Robots Rotary Joints product scope, market overview, market estimation caveats and base year.

Chapter 2, to profile the top manufacturers of Reducer for Humanoid Robots Rotary Joints, with price, sales quantity, revenue, and global market share of Reducer for Humanoid Robots Rotary Joints from 2021 to 2026.

Chapter 3, the Reducer for Humanoid Robots Rotary Joints competitive situation, sales quantity, revenue, and global market share of top manufacturers are analyzed emphatically by landscape contrast.

Chapter 4, the Reducer for Humanoid Robots Rotary Joints breakdown data are shown at the regional level, to show the sales quantity, consumption value, and growth by regions, from 2021 to 2032.

Chapter 5 and 6, to segment the sales by Type and by Application, with sales market share and growth rate by Type, by Application, from 2021 to 2032.

Chapter 7, 8, 9, 10 and 11, to break the sales data at the country level, with sales quantity, consumption value, and market share for key countries in the world, from 2021 to 2026. and Reducer for Humanoid Robots Rotary Joints market forecast, by regions, by Type, and by Application, with sales and revenue, from 2027 to 2032.

Chapter 12, market dynamics, drivers, restraints, trends, and Porters Five Forces analysis.

Chapter 13, the key raw materials and key suppliers, and industry chain of Reducer for Humanoid Robots Rotary Joints.

Chapter 14 and 15, to describe Reducer for Humanoid Robots Rotary Joints sales channel, distributors, customers, research findings and conclusion.

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