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Global Pneumatic Rotary Grippers Supply, Demand and Key Producers, 2026-2032

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Abstracts

The global Pneumatic Rotary Grippers market size is expected to reach $ 538 million by 2032, rising at a market growth of 6.3% CAGR during the forecast period (2026-2032).

Pneumatic Rotary Grippers are integrated automation end-effectors that combine a pneumatic gripping mechanism with a pneumatic rotary actuator in one compact unit, enabling a workpiece to be clamped and then rotated, flipped, indexed or reoriented within the same handling cycle. Compressed air provides the driving force for both gripping and rotary motion, while the gripping structure may adopt parallel, angular or centric jaws depending on the workpiece geometry. Compared with using a separate air gripper and rotary actuator, an integrated pneumatic rotary gripper can reduce mounting space, piping complexity and mechanical interfaces while improving cycle efficiency. Key specifications typically include gripping force, jaw stroke, rotation angle, rotary torque, operating pressure, rotation time, opening and closing time, repeatability, allowable workpiece weight, finger length, air consumption and environmental protection. These products are widely used in conveyor transfer, assembly, machine tending, loading and unloading, part flipping, orientation, packaging, automotive components, electronics and other high-cycle industrial automation applications.

Key Findings

In 2025, global Rotary Grippers production reached approximately 525k units, with an average global market price of around US$650 per unit

Two-jaw structures remain the mainstream configuration of Pneumatic Rotary Grippers

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Integrated gripping and rotary motion is the defining product characteristic of the market

Automated handling machine tending and assembly are major downstream application areas

Market Trends

The Pneumatic Rotary Grippers market is evolving toward higher mechanical integration, more compact structures, improved durability and stronger process-monitoring capability while retaining the core advantages of pneumatic actuation. Mature products increasingly integrate the gripping cylinder, rotary mechanism, air passages, damping components and sensor mounting features into a single housing, reducing the number of external adapters and simplifying machine layout. SMC and SCHUNK both maintain dedicated pneumatic rotary gripping products built around integrated gripping and swiveling functions, while Zimmer also offers rotary gripping solutions for industrial handling applications. Emerson participates through its industrial automation and handling portfolio, and PHD supplies dedicated pneumatic rotary gripper products for repetitive automation. Across the market, product development is focusing on more stable gripping during air-pressure fluctuations, improved end-position damping, easier sensor installation, higher mechanical life and simplified mounting. The long-term direction is therefore not a wholesale replacement of pneumatic products by electric alternatives, but a clearer positioning of Pneumatic Rotary Grippers in applications where rapid cycling, robust operation, compact design and straightforward control remain important.

Market Dynamics

Drivers

Demand is primarily driven by the widespread need to combine workpiece gripping with orientation adjustment in automated production. Components often need to be picked from conveyors, fixtures or machine tools and then rotated, flipped or reoriented before entering assembly, inspection, machining or another transfer stage. Integrating these operations into a single pneumatic device can reduce the number of actuators, brackets and mechanical interfaces required in the machine, helping equipment designers reduce space and simplify commissioning. Existing compressed-air infrastructure in industrial plants also supports adoption because Pneumatic Rotary Grippers can be

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integrated into mature pneumatic control systems with relatively limited additional complexity. SMC and SCHUNK benefit from broad pneumatic automation and gripping technology foundations, while Zimmer, Emerson and PHD participate through specialized handling and automation products. Continued automation in automotive components, electronics, machinery, packaging and general manufacturing therefore provides a stable application base.

Restraints

The main restraint comes from alternative system architectures, including a conventional pneumatic gripper combined with a separate rotary actuator, an electric rotary gripper, or the rotational axis of an industrial robot. When machine space is not highly constrained, separate actuators may provide greater design flexibility because gripping force, rotary torque and motion range can be selected independently. Pneumatic systems also depend on compressed-air supply and may be less suitable for applications that require continuously variable angular positioning or frequent software-defined motion changes. Energy-management requirements are becoming more important in modern factories, which can also encourage users to evaluate compressed-air consumption more carefully. As a result, Pneumatic Rotary Grippers are most competitive in applications where compact integration, fast response, simple control and proven industrial reliability provide clear advantages over more flexible but more complex alternatives.

Opportunities

Market opportunities are concentrated in higher-performance pneumatic platforms rather than in basic product expansion alone. Important development directions include lighter and more compact structures, improved gripping retention during pressure loss, integrated sensing, more effective damping, modular mounting and easier adjustment of rotary motion. These features are particularly relevant in machine tending, compact assembly equipment and automated handling systems where accidental part release or unstable end-position impact can reduce productivity and increase equipment risk. SMC, SCHUNK, Zimmer, Emerson and PHD all participate in industrial automation environments where customers increasingly expect complete functional modules rather than isolated mechanical components. Another opportunity is tighter integration of sensors, pneumatic valves and mounting interfaces, allowing rotary grippers to become easier to configure and commission. This can increase product value without fundamentally changing the pneumatic operating principle and can strengthen their role

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in standardized automation platforms.

Challenges

The principal technical challenge is to balance gripping force, rotary torque, jaw stroke, cycle speed, rotational inertia, external load and overall package size within one compact device. Higher force and torque generally require larger pistons and stronger transmission structures, while high-speed handling favors low mass and low inertia. The rotary mechanism must also withstand repeated acceleration, deceleration and end-position impact while preserving stable gripping and positioning performance. Sealing wear, air leakage, damping degradation and contamination can affect long-term reliability, particularly in demanding industrial environments. Manufacturers must therefore maintain high standards in precision machining, sealing design, bearing selection and assembly quality. At the same time, electric rotary grippers are improving in flexibility and integration, so pneumatic suppliers need to preserve clear advantages in cycle performance, robustness, maintenance simplicity and lifecycle economics.

Industry Chain Analysis

The upstream supply chain includes precision-machined aluminum and steel components, cylinders, pistons, rack-and-pinion or vane mechanisms, bearings, guides, seals, springs, damping elements, pneumatic connectors, magnetic components and position sensors. Midstream manufacturers integrate these parts into complete gripping-and-rotation modules through precision machining, rotary transmission design, jaw-guidance assembly, sealing-system engineering and product testing. Product performance depends heavily on mechanical accuracy, sealing reliability, damping characteristics and the stability of the rotary mechanism. Downstream customers include automation equipment manufacturers, machine builders, robot integrators and end users in automotive components, electronics, machinery, packaging and general industrial manufacturing. Value creation is increasingly linked not only to the pneumatic actuator itself but also to application engineering, sensor integration, mounting convenience and long-term reliability. SMC, SCHUNK, Zimmer, Emerson and PHD compete across different parts of this value chain through their respective strengths in pneumatic automation, gripping technology and industrial handling.

Segment Insights

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The analyst's Two-jaw and Three-jaw classification is suitable as the primary structural segmentation. Two-jaw Pneumatic Rotary Grippers are the more widely used configuration because parallel and angular jaw mechanisms can handle a broad range of prismatic, plate-shaped and irregular workpieces while maintaining relatively simple mechanical structures. Two-jaw designs are particularly suitable for general transfer, assembly and machine tending, where compact dimensions and repeatable opening and closing are important. SMC, SCHUNK, Zimmer and PHD all maintain product architectures based on two-jaw rotary gripping. Three-jaw Pneumatic Rotary Grippers are more specialized and are mainly used for cylindrical, round or rotationally symmetric workpieces where centric gripping improves alignment and stability. The two categories are therefore technically distinct and suitable for market segmentation without creating excessive overlap.

A secondary segmentation can be developed by gripping structure and rotary function. Parallel Rotary Grippers are suitable for regular industrial parts and general handling, Angular Rotary Grippers provide greater clearance around the workpiece, and Centric Rotary Grippers are more appropriate for round components requiring self-centering. Rotary motion can also be differentiated by fixed-angle, adjustable-angle and application-specific configurations. These secondary dimensions help explain product positioning because different structures correspond to different requirements for accessibility, workpiece geometry, torque, cycle time and equipment layout. For market modeling, finger count can remain the main classification, while gripping mechanism and rotary function can be used as supporting technical dimensions.

Downstream Market Opportunities

Automated handling, machine tending and assembly represent the most important downstream opportunities because these processes frequently require a component to be gripped and then reoriented before the next manufacturing step. Conveyor systems may require components to be flipped before inspection or packaging, while machine tending often requires parts to be turned between machining operations. Automotive component production favors robust and repeatable rotary gripping devices, whereas electronics and precision manufacturing place greater emphasis on compact dimensions and stable positioning. Packaging applications also create recurring demand for turning, orienting and repositioning products at high cycle frequency. As equipment manufacturers seek smaller machine footprints and simpler mechanical layouts, integrated Pneumatic Rotary Grippers can replace separate gripper-and-rotary-actuator combinations in suitable stations, supporting continued product adoption.

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Regional Insights

Europe remains an important technology base for Pneumatic Rotary Grippers, supported by established gripping and automation suppliers such as SCHUNK and Zimmer and by a mature industrial machinery ecosystem. These companies have strong experience in precision gripping, pneumatic actuation and integrated handling technologies. Japan is also an important market and technology center, with SMC providing established pneumatic gripping and rotary solutions for factory automation. North America has a broad industrial automation customer base and strong demand from machine building, automotive production and general manufacturing, while Emerson and PHD participate through industrial handling and pneumatic automation products. Demand across Asia is supported by continued investment in electronics, automotive components, machinery and general factory automation, although competitive conditions can vary considerably by application and customer segment.

Competitive Landscape Analysis

The competitive landscape is characterized by a combination of broad pneumatic automation suppliers and specialist gripping and handling technology manufacturers. SMC has strong capabilities in pneumatic components and integrated gripping-and-rotation products, benefiting from broad factory-automation coverage and standardized product platforms. SCHUNK competes through deep expertise in industrial gripping, modular rotary gripping solutions and application engineering. Zimmer focuses on precision gripping and mechatronic handling technology and participates in pneumatic rotary gripping applications through specialized end-effector products. Emerson contributes through its industrial automation and handling portfolio, while PHD is an established pneumatic motion and gripping specialist with dedicated rotary gripper solutions. Competition among these suppliers is primarily based on product reliability, compactness, gripping performance, rotary stability, damping design, sensor integration, service life, application support and compatibility with broader automation systems rather than on a single standardized performance metric.

Report Scope

This report studies the global Pneumatic Rotary Grippers production, demand, key

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manufacturers, and key regions.

This report is a detailed and comprehensive analysis of the world market for Pneumatic Rotary Grippers and provides market size (US$ million) and Year-over-Year (YoY) Growth, considering 2025 as the base year. This report explores demand trends and competition, as well as details the characteristics of Pneumatic Rotary Grippers that contribute to its increasing demand across many markets.

Highlights and key features of the study

Global Pneumatic Rotary Grippers total production and demand, 2021-2032, (K Units)

Global Pneumatic Rotary Grippers total production value, 2021-2032, (USD Million)

Global Pneumatic Rotary Grippers production by region & country, production, value, CAGR, 2021-2032, (USD Million) & (K Units), (based on production site)

Global Pneumatic Rotary Grippers consumption by region & country, CAGR, 2021-2032 & (K Units)

U.S. VS China: Pneumatic Rotary Grippers domestic production, consumption, key domestic manufacturers and share

Global Pneumatic Rotary Grippers production by manufacturer, production, price, value and market share 2021-2026, (USD Million) & (K Units)

Global Pneumatic Rotary Grippers production by Type, production, value, CAGR, 2021-2032, (USD Million) & (K Units)

Global Pneumatic Rotary Grippers production by Application, production, value, CAGR, 2021-2032, (USD Million) & (K Units)

This report profiles key players in the global Pneumatic Rotary Grippers market based on the following parameters - company overview, production, value, price, gross margin, product portfolio, geographical presence, and key developments. Key companies

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covered as a part of this study include SMC Corporation, Onrobot, FESTO, SCHUNK, Zimmer Group, Weiss Robotics, Robotiq, Gimatic, Kawasaki Robotics, Koganei, etc.

This report also provides key insights about market drivers, restraints, opportunities, new product launches or approvals.

Stakeholders would have ease in decision-making through various strategy matrices used in analyzing the World Pneumatic Rotary Grippers market

Detailed Segmentation:

Each section contains quantitative market data including market by value (US$ Millions), volume (production, consumption) & (K Units) and average price (US$/Unit) by manufacturer, by Type, and by Application. Data is given for the years 2021-2032 by year with 2025 as the base year, 2026 as the estimate year, and 2027-2032 as the forecast year.

Global Pneumatic Rotary Grippers Market, By Region:

United States

China

Europe

Japan

South Korea

ASEAN

India

Rest of World

Market Segmentation

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Global Pneumatic Rotary Grippers Market, Segmentation by Type:

2-finger Grippers

3-finger Grippers

Others

Global Pneumatic Rotary Grippers Market, Segmentation by Gripping Mechanism:

Parallel

Angular

Centric

Global Pneumatic Rotary Grippers Market, Segmentation by Gripping Force:

<50 N

50–100 N

100–200 N

>200 N

Global Pneumatic Rotary Grippers Market, Segmentation by Application:

Food Processing

Industrial Manufacturing

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Logistics and Warehousing

Others

Companies Profiled:

SMC Corporation

Onrobot

FESTO

SCHUNK

Zimmer Group

Weiss Robotics

Robotiq

Gimatic

Kawasaki Robotics

Koganei

Garcia Marin System

Emerson Electric

IAI America

Destaco

IMI Bimba

PHD Inc

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DH ROBOTICS

RobusMotion

Huiling-tech

Fito Automation

Wommer

Mindman Industrial

Chelic

Key Questions Answered

1. How big is the global Pneumatic Rotary Grippers market?
2. What is the demand of the global Pneumatic Rotary Grippers market?
3. What is the year over year growth of the global Pneumatic Rotary Grippers market?
4. What is the total value of the global Pneumatic Rotary Grippers market?
5. Who are the Major Players in the global Pneumatic Rotary Grippers market?
6. What are the growth factors driving the market demand?

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