

Global Mobile Manipulator Grippers Supply, Demand and Key Producers, 2026-2032

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Abstracts

The global Mobile Manipulator Grippers market size is expected to reach \$ 204 million by 2032, rising at a market growth of 17.6% CAGR during the forecast period (2026-2032).

Mobile Manipulator Grippers are gripping end-effectors mounted at the wrist of a mobile manipulator, enabling the robot to grasp, pick, carry, place, and perform basic manipulation tasks after the mobile base reaches the target location. A typical product consists of mechanical fingers or soft fingertips, an actuator, force and position feedback modules, a controller, communication interfaces, flange adapters, and replaceable fingertips. Main product forms include electric parallel grippers, two-finger and three-finger adaptive grippers, soft grippers, vacuum-assisted hybrid grippers, and lightweight dexterous hands.

From an application perspective, Mobile Manipulator Grippers are not merely conventional industrial robot grippers used on a moving base. They are highly integrated end-effectors designed for mobile operation, dynamic environments, and human-adjacent deployment. Key requirements include low weight, low power consumption, fast deployment, object adaptability, and safety redundancy. Major applications include warehouse picking, mobile machine tending, laboratory automation, healthcare and commercial service robots, flexible manufacturing, inspection and maintenance, and robotics data collection. Major production and technology clusters are concentrated in the United States, Canada, Germany, Denmark, Japan, China, and South Korea.

In 2025, global Mobile Manipulator Grippers production reached approximately 11,000?15,000 sets, with demand mainly driven by warehouse picking, mobile machine

tending, research and robot training platforms, healthcare logistics, and commercial service robot applications. Mainstream FOB prices were approximately USD 3,000?7,800 per set. High-end dexterous hands and adaptive grippers with force control and multi-sensor feedback were priced significantly higher, while standard two-finger electric grippers and lightweight collaborative grippers remained the primary shipment category.

Mobile Manipulator Grippers are evolving from robotic accessories into a critical interface for mobile manipulation. In the past, mobile robots mainly handled transport, while robotic arms were usually deployed at fixed workstations. Today, manufacturers, warehouse operators, and service organizations are integrating mobile bases, collaborative arms, vision systems, and grippers into one mobile work unit, allowing robots not only to move objects across a facility but also to pick, sort, load, unload, and interact with them. For gripper suppliers, the opportunity comes from two directions: rising installations of mobile manipulators and growing demand for reliable grasping of mixed, irregular, and less-structured objects. In e-commerce logistics, semiconductor and electronics manufacturing, laboratory automation, hospital logistics, and robotics data collection, gripper reliability, compatibility, and software integration increasingly determine the practical deployment efficiency of the whole robot system.

The market still faces clear constraints. Mobile manipulators operate with more diverse objects, larger positioning uncertainty, and less controlled environments, which raises the requirements for force control, sensing, tolerance, and safety design. At the same time, customers often expect one gripper to cover more object types, but differences in size, weight, surface material, and grasping posture make it difficult for a single product to handle all use cases. On the pricing side, mobile manipulator systems remain relatively expensive, and end users continue to evaluate return on investment carefully before scaling deployments, limiting the pricing premium available to gripper suppliers. Over the next several years, competition will move beyond gripping force, stroke, and payload, shifting toward the combined capability of gripper hardware, vision, force control, software interfaces, and scenario data. Companies that can provide standardized interfaces, rapid changeover, stable grasping performance, and proven application cases will be better positioned to enter the mobile manipulation robot supply chain.

This report studies the global Mobile Manipulator Grippers production, demand, key manufacturers, and key regions.

This report is a detailed and comprehensive analysis of the world market for Mobile

Manipulator Grippers and provides market size (US\$ million) and Year-over-Year (YoY) Growth, considering 2025 as the base year. This report explores demand trends and competition, as well as details the characteristics of Mobile Manipulator Grippers that contribute to its increasing demand across many markets.

Highlights and key features of the study

Global Mobile Manipulator Grippers total production and demand, 2021-2032, (Sets)

Global Mobile Manipulator Grippers total production value, 2021-2032, (USD Million)

Global Mobile Manipulator Grippers production by region & country, production, value, CAGR, 2021-2032, (USD Million) & (Sets), (based on production site)

Global Mobile Manipulator Grippers consumption by region & country, CAGR, 2021-2032 & (Sets)

U.S. VS China: Mobile Manipulator Grippers domestic production, consumption, key domestic manufacturers and share

Global Mobile Manipulator Grippers production by manufacturer, production, price, value and market share 2021-2026, (USD Million) & (Sets)

Global Mobile Manipulator Grippers production by Type, production, value, CAGR, 2021-2032, (USD Million) & (Sets)

Global Mobile Manipulator Grippers production by Application, production, value, CAGR, 2021-2032, (USD Million) & (Sets)

This report profiles key players in the global Mobile Manipulator Grippers market based on the following parameters - company overview, production, value, price, gross margin, product portfolio, geographical presence, and key developments. Key companies covered as a part of this study include SCHUNK SE & Co. KG, Zimmer Group, Festo SE & Co. KG, J. Schmalz GmbH, Stabilus SE (DESTACO), OnRobot A/S, Piab Group, Robotiq Inc., PHD, Inc., New Scale Robotics, Inc., etc.

This report also provides key insights about market drivers, restraints, opportunities, new product launches or approvals.

Stakeholders would have ease in decision-making through various strategy matrices used in analyzing the World Mobile Manipulator Grippers market

Detailed Segmentation:

Each section contains quantitative market data including market by value (US\$ Millions), volume (production, consumption) & (Sets) and average price (US\$/Set) by manufacturer, by Type, and by Application. Data is given for the years 2021-2032 by

year with 2025 as the base year, 2026 as the estimate year, and 2027-2032 as the forecast year.

Global Mobile Manipulator Grippers Market, By Region:

United States

China

Europe

Japan

South Korea

ASEAN

India

Rest of World

Global Mobile Manipulator Grippers Market, Segmentation by Type:

Electric Finger Grippers

Vacuum Grippers

Adaptive and Soft Grippers

Dexterous Hands

Others

Global Mobile Manipulator Grippers Market, Segmentation by Actuation Method:

Electric Servo Actuation

Pneumatic Actuation

Vacuum Actuation

Magnetic and Passive Actuation

Global Mobile Manipulator Grippers Market, Segmentation by Payload Class:

Below 1 kg

1 kg to 5 kg

5 kg to 10 kg

Above 10 kg

Global Mobile Manipulator Grippers Market, Segmentation by Gripper Structure:

Parallel Jaw Structure

Two Finger Adaptive Structure

Three Finger and Multi Finger Structure

Suction Cup and Foam Pad Structure

Global Mobile Manipulator Grippers Market, Segmentation by Application:

Logistics and E Commerce

Industrial Manufacturing

Research Education and Robot Training

Healthcare Commercial Service

Others

Companies Profiled:

SCHUNK SE & Co. KG

Zimmer Group

Festo SE & Co. KG

J. Schmalz GmbH

Stabilus SE (DESTACO)

OnRobot A/S

Piab Group

Robotiq Inc.

PHD, Inc.

New Scale Robotics, Inc.

SMC Corporation

IAI Corporation

CKD Corporation

Oriental Motor Co., Ltd.

Koganei Corporation

DH-Robotics Technology Co., Ltd.

Hitbot Technology (Shenzhen) Co., Ltd.

Beijing Inspire Robots Technology Co., Ltd.

Linkerbot Beijing Technology Co., Ltd.

Soft Robot Tech Co., Ltd. (SRT)

Suzhou Rochu Robotics Co., Ltd.

HIWIN Technologies Corp.

TESOLLO INC.

ROBOTIS Co., Ltd.

Janatics India Private Limited

Key Questions Answered:

1. How big is the global Mobile Manipulator Grippers market?
2. What is the demand of the global Mobile Manipulator Grippers market?
3. What is the year over year growth of the global Mobile Manipulator Grippers market?
4. What is the production and production value of the global Mobile Manipulator Grippers market?
5. Who are the key producers in the global Mobile Manipulator Grippers market?
6. What are the growth factors driving the market demand?

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