

Global Mobile Manipulator Grippers Market 2026 by Manufacturers, Regions, Type and Application, Forecast to 2032

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Abstracts

According to our (Global Info Research) latest study, the global Mobile Manipulator Grippers market size was valued at US\$ 61.74 million in 2025 and is forecast to a readjusted size of US\$ 204 million by 2032 with a CAGR of 17.6% during review period.

Mobile Manipulator Grippers are gripping end-effectors mounted at the wrist of a mobile manipulator, enabling the robot to grasp, pick, carry, place, and perform basic manipulation tasks after the mobile base reaches the target location. A typical product consists of mechanical fingers or soft fingertips, an actuator, force and position feedback modules, a controller, communication interfaces, flange adapters, and replaceable fingertips. Main product forms include electric parallel grippers, two-finger and three-finger adaptive grippers, soft grippers, vacuum-assisted hybrid grippers, and lightweight dexterous hands.

From an application perspective, Mobile Manipulator Grippers are not merely conventional industrial robot grippers used on a moving base. They are highly integrated end-effectors designed for mobile operation, dynamic environments, and human-adjacent deployment. Key requirements include low weight, low power consumption, fast deployment, object adaptability, and safety redundancy. Major applications include warehouse picking, mobile machine tending, laboratory automation, healthcare and commercial service robots, flexible manufacturing, inspection and maintenance, and robotics data collection. Major production and technology clusters are concentrated in the United States, Canada, Germany, Denmark, Japan, China, and South Korea.

In 2025, global Mobile Manipulator Grippers production reached approximately

11,000?15,000 sets, with demand mainly driven by warehouse picking, mobile machine tending, research and robot training platforms, healthcare logistics, and commercial service robot applications. Mainstream FOB prices were approximately USD 3,000?7,800 per set. High-end dexterous hands and adaptive grippers with force control and multi-sensor feedback were priced significantly higher, while standard two-finger electric grippers and lightweight collaborative grippers remained the primary shipment category.

Mobile Manipulator Grippers are evolving from robotic accessories into a critical interface for mobile manipulation. In the past, mobile robots mainly handled transport, while robotic arms were usually deployed at fixed workstations. Today, manufacturers, warehouse operators, and service organizations are integrating mobile bases, collaborative arms, vision systems, and grippers into one mobile work unit, allowing robots not only to move objects across a facility but also to pick, sort, load, unload, and interact with them. For gripper suppliers, the opportunity comes from two directions: rising installations of mobile manipulators and growing demand for reliable grasping of mixed, irregular, and less-structured objects. In e-commerce logistics, semiconductor and electronics manufacturing, laboratory automation, hospital logistics, and robotics data collection, gripper reliability, compatibility, and software integration increasingly determine the practical deployment efficiency of the whole robot system.

The market still faces clear constraints. Mobile manipulators operate with more diverse objects, larger positioning uncertainty, and less controlled environments, which raises the requirements for force control, sensing, tolerance, and safety design. At the same time, customers often expect one gripper to cover more object types, but differences in size, weight, surface material, and grasping posture make it difficult for a single product to handle all use cases. On the pricing side, mobile manipulator systems remain relatively expensive, and end users continue to evaluate return on investment carefully before scaling deployments, limiting the pricing premium available to gripper suppliers. Over the next several years, competition will move beyond gripping force, stroke, and payload, shifting toward the combined capability of gripper hardware, vision, force control, software interfaces, and scenario data. Companies that can provide standardized interfaces, rapid changeover, stable grasping performance, and proven application cases will be better positioned to enter the mobile manipulation robot supply chain.

This report is a detailed and comprehensive analysis for global Mobile Manipulator Grippers market. Both quantitative and qualitative analyses are presented by manufacturers, by region & country, by Type and by Application. As the market is

constantly changing, this report explores the competition, supply and demand trends, as well as key factors that contribute to its changing demands across many markets. Company profiles and product examples of selected competitors, along with market share estimates of some of the selected leaders for the year 2025, are provided.

Key Features:

Global Mobile Manipulator Grippers market size and forecasts, in consumption value (\$ Million), sales quantity (Sets), and average selling prices (US\$/Set), 2021-2032

Global Mobile Manipulator Grippers market size and forecasts by region and country, in consumption value (\$ Million), sales quantity (Sets), and average selling prices (US\$/Set), 2021-2032

Global Mobile Manipulator Grippers market size and forecasts, by Type and by Application, in consumption value (\$ Million), sales quantity (Sets), and average selling prices (US\$/Set), 2021-2032

Global Mobile Manipulator Grippers market shares of main players, shipments in revenue (\$ Million), sales quantity (Sets), and ASP (US\$/Set), 2021-2026

The Primary Objectives in This Report Are:

- To determine the size of the total market opportunity of global and key countries

- To assess the growth potential for Mobile Manipulator Grippers

- To forecast future growth in each product and end-use market

- To assess competitive factors affecting the marketplace

This report profiles key players in the global Mobile Manipulator Grippers market based on the following parameters - company overview, sales quantity, revenue, price, gross margin, product portfolio, geographical presence, and key developments. Key companies covered as a part of this study include SCHUNK SE & Co. KG, Zimmer Group, Festo SE & Co. KG, J. Schmalz GmbH, Stabilus SE (DESTACO), OnRobot A/S, Piab Group, Robotiq Inc., PHD, Inc., New Scale Robotics, Inc., etc.

This report also provides key insights about market drivers, restraints, opportunities, new product launches or approvals.

Market Segmentation

Mobile Manipulator Grippers market is split by Type and by Application. For the period 2021-2032, the growth among segments provides accurate calculations and forecasts for consumption value by Type, and by Application in terms of volume and value. This analysis can help you expand your business by targeting qualified niche markets.

Market segment by Type

Electric Finger Grippers

Vacuum Grippers

Adaptive and Soft Grippers

Dexterous Hands

Others

Market segment by Actuation Method

Electric Servo Actuation

Pneumatic Actuation

Vacuum Actuation

Magnetic and Passive Actuation

Market segment by Payload Class

Below 1 kg

1 kg to 5 kg

5 kg to 10 kg

Above 10 kg

Market segment by Gripper Structure

Parallel Jaw Structure

Two Finger Adaptive Structure

Three Finger and Multi Finger Structure

Suction Cup and Foam Pad Structure

Market segment by Application

Logistics and E Commerce

Industrial Manufacturing

Research Education and Robot Training

Healthcare Commercial Service

Others

Major players covered

SCHUNK SE & Co. KG

Zimmer Group

Festo SE & Co. KG

J. Schmalz GmbH

Stabilus SE (DESTACO)

OnRobot A/S

Piab Group

Robotiq Inc.

PHD, Inc.

New Scale Robotics, Inc.

SMC Corporation

IAI Corporation

CKD Corporation

Oriental Motor Co., Ltd.

Koganei Corporation

DH-Robotics Technology Co., Ltd.

Hitbot Technology (Shenzhen) Co., Ltd.

Beijing Inspire Robots Technology Co., Ltd.

Linkerbot Beijing Technology Co., Ltd.

Soft Robot Tech Co., Ltd. (SRT)

Suzhou Rochu Robotics Co., Ltd.

HIWIN Technologies Corp.

TESOLLO INC.

ROBOTIS Co., Ltd.

Janatics India Private Limited

Market segment by region, regional analysis covers

North America (United States, Canada, and Mexico)

Europe (Germany, France, United Kingdom, Russia, Italy, and Rest of Europe)

Asia-Pacific (China, Japan, Korea, India, Southeast Asia, and Australia)

South America (Brazil, Argentina, Colombia, and Rest of South America)

Middle East & Africa (Saudi Arabia, UAE, Egypt, South Africa, and Rest of Middle East & Africa)

The content of the study subjects, includes a total of 15 chapters:

Chapter 1, to describe Mobile Manipulator Grippers product scope, market overview, market estimation caveats and base year.

Chapter 2, to profile the top manufacturers of Mobile Manipulator Grippers, with price, sales quantity, revenue, and global market share of Mobile Manipulator Grippers from 2021 to 2026.

Chapter 3, the Mobile Manipulator Grippers competitive situation, sales quantity, revenue, and global market share of top manufacturers are analyzed emphatically by landscape contrast.

Chapter 4, the Mobile Manipulator Grippers breakdown data are shown at the regional level, to show the sales quantity, consumption value, and growth by regions, from 2021 to 2032.

Chapter 5 and 6, to segment the sales by Type and by Application, with sales market share and growth rate by Type, by Application, from 2021 to 2032.

Chapter 7, 8, 9, 10 and 11, to break the sales data at the country level, with sales quantity, consumption value, and market share for key countries in the world, from 2021 to 2026. and Mobile Manipulator Grippers market forecast, by regions, by Type, and by Application, with sales and revenue, from 2027 to 2032.

Chapter 12, market dynamics, drivers, restraints, trends, and Porters Five Forces analysis.

Chapter 13, the key raw materials and key suppliers, and industry chain of Mobile Manipulator Grippers.

Chapter 14 and 15, to describe Mobile Manipulator Grippers sales channel, distributors, customers, research findings and conclusion.

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