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Global Inertial Measurement Units for Robotics Market 2026 by Manufacturers, Regions, Type and Application, Forecast to 2032

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Abstracts

According to our (Global Info Research) latest study, the global Inertial Measurement Units for Robotics market size was valued at US$ 581 million in 2025 and is forecast to a readjusted size of US$ 1410 million by 2032 with a CAGR of 13.5% during review period.

Inertial Measurement Units for Robotics are sensing components used in industrial robots, mobile robots, service robots, humanoid robots, and other unmanned platforms to measure three-axis angular velocity and three-axis linear acceleration in real time and provide inertial data for attitude estimation, balance control, motion control, localization, and multi-sensor fusion. The market covers IMUs based primarily on MEMS, fiber-optic gyroscope, and ring laser gyroscope technologies, spanning IC/SiP devices, OEM modules, and self-contained enclosed units. Products can be differentiated by six-axis or nine-axis-and-above sensor configuration, gyroscope bias instability, and form factor. Core purchasing attributes include low noise and drift, bandwidth, latency, vibration robustness, temperature compensation, calibration consistency, and system interfaces such as SPI, UART, CAN, RS-422, and Ethernet. This study focuses on IMUs used for robot body-state sensing, AGV/AMR localization, unmanned-platform navigation, and motion control in medical and service robots, including integrated products that retain raw inertial-data output capability. The blended gross margin is approximately 45%.

Market Trends

Robotics IMUs are shifting from simple motion-sensing components toward calibrated,

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timing-aware inertial nodes designed to operate inside tightly coupled perception and control stacks. High-dynamic-range gyroscopes, lower noise, reduced vibration rectification error, tighter temperature compensation, lower latency, and faster output rates are becoming more important as mobile robots, unmanned platforms, and humanoids move faster and experience greater shock and vibration. Chip-level MEMS devices continue to improve through algorithms, packaging, and calibration, extending into use cases that previously required tactical or optical inertial devices. Fiber-optic solutions still retain an advantage where long-duration drift control, GNSS-denied navigation, and mission reliability justify higher cost. Timestamping, self-test, embedded processing, ROS compatibility, and standardized digital interfaces are also becoming major integration criteria. Humanoid designs add a further shift from one central IMU toward multiple synchronized sensors distributed across the torso and limbs.

Drivers

Continued deployment of industrial automation, warehouse logistics, unmanned systems, and service robots increases the baseline need for real-time attitude, angular-rate, and linear-acceleration measurements. As robots move from predefined trajectories toward autonomous navigation and dynamic balance, IMUs become more deeply embedded in localization fusion, closed-loop control, fall detection, motion compensation, and vision stabilization. Humanoid robots are particularly dependent on high-rate, low-latency inertial feedback and may use several IMUs per platform, increasing both sensor content and calibration requirements.

Restraints

Low-cost MEMS IMUs can still accumulate errors under temperature change, bias drift, strong vibration, and mechanical shock, requiring thermal compensation, structural isolation, and fusion with external sensors. High-stability modules and fiber-optic IMUs carry materially higher prices, limiting adoption in cost-sensitive platforms. Differences in vendor test conditions for bias instability, angle random walk, and dynamic error also make cross-platform benchmarking and substitution more difficult for robot OEMs.

Opportunities

Humanoids, multi-sensor AMRs, UAVs, and specialty robots create incremental demand for synchronized multi-IMU architectures, wider dynamic ranges, and higher

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reliability. Suppliers combining temperature calibration, precision timing, self-test, low-latency interfaces, and robotics software support are better positioned to win platform-level designs. Rapid expansion of the Chinese robotics supply chain also creates opportunities for suppliers with local calibration, fast delivery, and interface customization, while smaller FOG packages can penetrate high-value applications where GNSS availability is limited.

Challenges

Robot designers must continuously balance size, power, cost, dynamic range, and long-term stability, so leadership on a single specification does not guarantee system-level performance. Mounting location, structural vibration, thermal layout, and clock synchronization can materially change control results, requiring suppliers to provide stronger application validation and calibration support. High-end inertial products also face lengthy reliability qualification, process-yield challenges, and potential export or supply constraints for certain performance grades.

Industry Chain Analysis

Upstream inputs include MEMS gyroscope and accelerometer wafers, ASICs, package substrates, oscillators, magnetic sensors, optical fiber coils, light sources, photodetectors, connectors, and precision mechanical parts. Midstream suppliers integrate sensing elements, packaging, thermal calibration, error compensation, firmware, module assembly, and environmental qualification into IC/SiP devices, OEM modules, or enclosed IMUs. Downstream customers include robot OEMs, mobile-robot manufacturers, unmanned-system developers, controller suppliers, and system integrators. Value capture is not determined by the sensing die alone: full-temperature calibration, bias control, vibration suppression, timing accuracy, software interfaces, and long-term unit-to-unit consistency materially increase the value of industrial and tactical products. Fiber-optic IMUs add dependence on optical components, precision coil winding, and closed-loop control know-how.

Segment Insights

MEMS IMUs account for the majority of robotics unit shipments because of their size, power, and cost advantages, while six-axis configurations remain the standard foundation for closed-loop control and motion sensing. Nine-axis-and-above products

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are used where magnetic heading assistance, redundancy, or broader state information is required. By gyroscope bias instability, higher-drift products primarily address consumer and basic service robots, the 1–10°/h range fits many industrial and mobile-robot platforms, and below-1°/h products are more common in high-end mobile systems, mapping, unmanned systems, and precision control. By form factor, IC/SiP products suit high-volume deep integration, OEM modules balance calibration with development speed, and enclosed IMUs command higher prices through environmental protection and rapid deployment.

Downstream Market Opportunities

Manufacturing and logistics remain the most stable volume opportunities, supported by AMRs, AGVs, robot arms, and mobile manipulators. Medical robotics offers lower unit volumes but stronger requirements for precision, reliability, and traceable calibration, supporting higher-value industrial modules. Consumer and commercial service robots are more price sensitive, yet cleaning, inspection, delivery, and companion platforms can generate substantial sensor volumes. Humanoid robotics is the most important emerging opportunity because balance control, limb-state estimation, and vision stabilization can require multiple synchronized IMUs, raising inertial content per robot. Aerospace and defense robots and unmanned systems are smaller in volume but support tactical MEMS and FOG products with much higher performance requirements.

Regional Insights

Asia is the largest robotics IMU shipment region because industrial robot deployment, mobile-robot manufacturing, and electronics supply chains are concentrated in China, Japan, and South Korea. China benefits from a rapidly expanding robot OEM and component ecosystem that is accelerating qualification of locally calibrated industrial MEMS IMUs, while Japan retains deep capabilities in precision sensing, MEMS processing, and industrial robotics. North American demand is more weighted toward high-value autonomous systems, warehouse automation, unmanned platforms, and defense, with greater emphasis on dynamic performance, stability, and software integration. Europe remains strong in industrial automation, mobile robotics, mapping, and high-performance inertial technology and hosts several specialist IMU and fiber-optic gyro suppliers.

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Competitive Landscape Analysis

Competition is layered by product architecture and performance. Semiconductor sensor suppliers compete through chip-level MEMS scale, unit cost, power, and integration, serving high-volume robotic platforms. Specialist inertial-module suppliers differentiate through full-temperature calibration, low bias drift, low noise, interfaces, firmware, and validation for industrial and premium autonomous systems. Tactical-grade MEMS and fiber-optic suppliers focus on GNSS-denied operation, long-duration stability, and mission reliability. Robot OEMs typically evaluate bias instability, angle random walk, vibration rectification error, output rate, latency, dynamic range, power, size, and interfaces together rather than relying on a single specification. Switching suppliers after design-in can require mechanical changes, thermal recalibration, timing validation, and state-estimation retuning, creating meaningful supplier stickiness and making delivery continuity, application support, and product-lifecycle management important competitive factors.

Report Scope

This report is a detailed and comprehensive analysis for global Inertial Measurement Units for Robotics market. Both quantitative and qualitative analyses are presented by manufacturers, by region & country, by Type and by Application. As the market is constantly changing, this report explores the competition, supply and demand trends, as well as key factors that contribute to its changing demands across many markets. Company profiles and product examples of selected competitors, along with market share estimates of some of the selected leaders for the year 2025, are provided.

Key Features:

Global Inertial Measurement Units for Robotics market size and forecasts, in consumption value ($ Million), sales quantity (K Units), and average selling prices (US$/Unit), 2021-2032

Global Inertial Measurement Units for Robotics market size and forecasts by region and country, in consumption value ($ Million), sales quantity (K Units), and average selling prices (US$/Unit), 2021-2032

Global Inertial Measurement Units for Robotics market size and forecasts, by Type and

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by Application, in consumption value ($ Million), sales quantity (K Units), and average selling prices (US$/Unit), 2021-2032

Global Inertial Measurement Units for Robotics market shares of main players, shipments in revenue ($ Million), sales quantity (K Units), and ASP (US$/Unit), 2021-2026

The Primary Objectives in This Report Are:

To determine the size of the total market opportunity of global and key countries

To assess the growth potential for Inertial Measurement Units for Robotics

To forecast future growth in each product and end-use market

To assess competitive factors affecting the marketplace

This report profiles key players in the global Inertial Measurement Units for Robotics market based on the following parameters - company overview, sales quantity, revenue, price, gross margin, product portfolio, geographical presence, and key developments. Key companies covered as a part of this study include Analog Devices, TDK, STMicroelectronics, Bosch Sensortec, Murata Manufacturing, Seiko Epson, Honeywell, VectorNav, Xsens, SBG Systems, etc.

This report also provides key insights about market drivers, restraints, opportunities, new product launches or approvals.

Inertial Measurement Units for Robotics market is split by Type and by Application. For the period 2021-2032, the growth among segments provides accurate calculations and forecasts for consumption value by Type, and by Application in terms of volume and value. This analysis can help you expand your business by targeting qualified niche markets.

Market Segmentation

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Market segment by Type

MEMS IMUs

Fiber-Optic Gyro IMUs

Ring Laser Gyro IMUs

Other IMUs

Market segment by Sensor Configuration

6-Axis IMUs

9-Axis and Above IMUs

Other Configurations

Market segment by Gyroscope Bias Instability

Below 1°/h

1–10°/h

Above 10°/h

Market segment by Application

Manufacturing

Logistics and Warehousing

Healthcare

Consumer and Commercial Services

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Aerospace and Defense

Others

Major players covered

Analog Devices

TDK

STMicroelectronics

Bosch Sensortec

Murata Manufacturing

Seiko Epson

Honeywell

VectorNav

Xsens

SBG Systems

Advanced Navigation

Silicon Sensing

Safran

Exail

Gladiator Technologies

WitMotion

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Market segment by region, regional analysis covers

North America (United States, Canada, and Mexico)

Europe (Germany, France, United Kingdom, Russia, Italy, and Rest of Europe)

Asia-Pacific (China, Japan, Korea, India, Southeast Asia, and Australia)

South America (Brazil, Argentina, Colombia, and Rest of South America)

Middle East & Africa (Saudi Arabia, UAE, Egypt, South Africa, and Rest of Middle East & Africa)

Chapter Outline

Chapter 1, to describe Inertial Measurement Units for Robotics product scope, market overview, market estimation caveats and base year.

Chapter 2, to profile the top manufacturers of Inertial Measurement Units for Robotics, with price, sales quantity, revenue, and global market share of Inertial Measurement Units for Robotics from 2021 to 2026.

Chapter 3, the Inertial Measurement Units for Robotics competitive situation, sales quantity, revenue, and global market share of top manufacturers are analyzed emphatically by landscape contrast.

Chapter 4, the Inertial Measurement Units for Robotics breakdown data are shown at the regional level, to show the sales quantity, consumption value, and growth by regions, from 2021 to 2032.

Chapter 5 and 6, to segment the sales by Type and by Application, with sales market share and growth rate by Type, by Application, from 2021 to 2032.

Chapter 7, 8, 9, 10 and 11, to break the sales data at the country level, with sales quantity, consumption value, and market share for key countries in the world, from 2021

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to 2026.and Inertial Measurement Units for Robotics market forecast, by regions, by Type, and by Application, with sales and revenue, from 2027 to 2032.

Chapter 12, market dynamics, drivers, restraints, trends, and Porters Five Forces analysis.

Chapter 13, the key raw materials and key suppliers, and industry chain of Inertial Measurement Units for Robotics.

Chapter 14 and 15, to describe Inertial Measurement Units for Robotics sales channel, distributors, customers, research findings and conclusion.

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