

Global Humanoid Robot with Dexterous Hands Supply, Demand and Key Producers, 2026-2032

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Abstracts

The global Humanoid Robot with Dexterous Hands market size is expected to reach \$ 20656 million by 2032, rising at a market growth of 59.5% CAGR during the forecast period (2026-2032).

A humanoid robot with dexterous hands refers to a robotic platform whose upper limbs are terminated in multi-fingered end effectors capable of independently actuating each joint, enabling precision pinch, power grasp, and in-hand manipulation across a wide range of object geometries and stiffness levels. The purpose of equipping such a robot with anthropomorphic hand morphology is to allow it to directly interface with human-centric tools and environments without requiring task-specific end effector swaps, thereby closing the gap between robotic automation and human dexterity. The core benefit lies in achieving force closure and form closure simultaneously at the fingertip level, which enables the robot to handle fragile, deformable, or irregularly shaped items that traditionally require human tactile feedback. This functional architecture transforms the robot from a simple position-controlled manipulator into a sensory-driven handling system, where each finger acts as both an actuator and a sensor to perceive contact condition, slip, and surface texture in real time. In 2025, global Humanoid Robot with Dexterous Hands production reached approximately 8925 units with an average global market price of around k US\$85 per unit.

The humanoid robot with dexterous hands industry is entering a critical phase of divergence. The core value of such products is concentrated in the force-tactile perception and precision grasping capabilities of the end effector, making the dexterous hand module the most profit-potential component within the entire machine. Official news from companies such as INtime Robot and ZHIYUN Robot indicates that their dexterous hand products have already been supplied in batches to multiple whole-

machine manufacturers. Their business revenue is shifting from simply selling hands to providing a complete solution that combines drive control algorithms with hand hardware. The State Council, in the '14th Five-Year Plan for the Development of the Robot Industry,' has explicitly identified 'high-dexterity manipulation' as a key breakthrough direction. This guidance leads companies to invest more profits into the research and development of servo miniaturization and sensor fusion rather than into whole-machine assembly.

Tesla has repeatedly emphasized at shareholder meetings and public demonstrations that the commercialization barrier for its Optimus humanoid robot lies in whether the dexterous hands can achieve fine-grained operations. This prompts related component companies to accelerate the domestic iteration of coreless motors and tactile arrays, shifting their profit focus from general-purpose reducers to customized micro-transmission systems. Meanwhile, companies such as Apple and ZF Friedrichshafen have entered the field by acquiring hand-perception startups. Their official statements show that they value the exclusive adaptability of dexterous hands in precision assembly and medical assistance scenarios, and are willing to pay higher module unit prices in exchange for technology lock-in. Taken together, the profit structure of the humanoid robot with dexterous hands industry is evolving from balanced distribution across the whole machine to high concentration in key modules. Companies that can first break through the batch assembly consistency problem will dominate the profit segmentation of the industrial chain, and the high-end manufacturing standards established by policy further strengthen the first-mover advantage in technology.

This report studies the global Humanoid Robot with Dexterous Hands production, demand, key manufacturers, and key regions.

This report is a detailed and comprehensive analysis of the world market for Humanoid Robot with Dexterous Hands and provides market size (US\$ million) and Year-over-Year (YoY) Growth, considering 2025 as the base year. This report explores demand trends and competition, as well as details the characteristics of Humanoid Robot with Dexterous Hands that contribute to its increasing demand across many markets.

Highlights and key features of the study

Global Humanoid Robot with Dexterous Hands total production and demand, 2021-2032, (Units)

Global Humanoid Robot with Dexterous Hands total production value, 2021-2032, (USD Million)

Global Humanoid Robot with Dexterous Hands production by region & country,

production, value, CAGR, 2021-2032, (USD Million) & (Units), (based on production site)

Global Humanoid Robot with Dexterous Hands consumption by region & country, CAGR, 2021-2032 & (Units)

U.S. VS China: Humanoid Robot with Dexterous Hands domestic production, consumption, key domestic manufacturers and share

Global Humanoid Robot with Dexterous Hands production by manufacturer, production, price, value and market share 2021-2026, (USD Million) & (Units)

Global Humanoid Robot with Dexterous Hands production by Type, production, value, CAGR, 2021-2032, (USD Million) & (Units)

Global Humanoid Robot with Dexterous Hands production by Application, production, value, CAGR, 2021-2032, (USD Million) & (Units)

This report profiles key players in the global Humanoid Robot with Dexterous Hands market based on the following parameters - company overview, production, value, price, gross margin, product portfolio, geographical presence, and key developments. Key companies covered as a part of this study include SKL Robotics, 1X Technologies, Figure AI, Rainbow Robotics, Reflex Robotics, AgiBot Innovation (Shanghai) Technology, Shenzhen UBTECH Robotics, Hangzhou Yushu Science And Technology, Leju (Shenzhen) Robotics, Suzhou Junji Robot Technology, etc.

This report also provides key insights about market drivers, restraints, opportunities, new product launches or approvals.

Stakeholders would have ease in decision-making through various strategy matrices used in analyzing the World Humanoid Robot with Dexterous Hands market

Detailed Segmentation:

Each section contains quantitative market data including market by value (US\$ Millions), volume (production, consumption) & (Units) and average price (K US\$/Unit) by manufacturer, by Type, and by Application. Data is given for the years 2021-2032 by year with 2025 as the base year, 2026 as the estimate year, and 2027-2032 as the forecast year.

Global Humanoid Robot with Dexterous Hands Market, By Region:

United States

China

Europe

Japan

South Korea

ASEAN

India

Rest of World

Global Humanoid Robot with Dexterous Hands Market, Segmentation by Type:

Wheeled Humanoid Robot

Bipedal Humanoid Robot

Global Humanoid Robot with Dexterous Hands Market, Segmentation by DoF:

?15 DoF

15?25 DoF

26?40 DoF

?40 DoF

Global Humanoid Robot with Dexterous Hands Market, Segmentation by End User:

Consumer-grade

Research-grade

Global Humanoid Robot with Dexterous Hands Market, Segmentation by Application:

Scientific Research

Industrial Manufacturing

Home

Others

Companies Profiled:

SKL Robotics

1X Technologies

Figure AI

Rainbow Robotics

Reflex Robotics

AgiBot Innovation (Shanghai) Technology

Shenzhen UBTECH Robotics

Hangzhou Yushu Science And Technology

Leju (Shenzhen) Robotics

Suzhou Junji Robot Technology

Suzhou UniX AI

Guangzhou Li-Gong Industrial

Chengdu Crp ROBOT Technology

GAC Group

Shenzhen Elephant Robotics Technology

Beijing Robotera

ROKAE Robotics

Beijing Galbot

Variable Robotics Technology (Shenzhen)

Key Questions Answered:

1. How big is the global Humanoid Robot with Dexterous Hands market?
2. What is the demand of the global Humanoid Robot with Dexterous Hands market?
3. What is the year over year growth of the global Humanoid Robot with Dexterous Hands market?
4. What is the production and production value of the global Humanoid Robot with Dexterous Hands market?
5. Who are the key producers in the global Humanoid Robot with Dexterous Hands market?
6. What are the growth factors driving the market demand?

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