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Global Humanoid Robot Springs Supply, Demand and Key Producers, 2026-2032

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Abstracts

The global Humanoid Robot Springs market size is expected to reach $ 679 million by 2032, rising at a market growth of 39.4% CAGR during the forecast period (2026-2032).

In the complex electromechanical systems of humanoid robots, actuators act like 'joints,' while high-precision, highly reliable springs and elastic elements play a crucial role as 'mechanical ligaments.' They are not simply accessories, but core functional components that enable the robot's dexterous, compliant, and safe movement, primarily undertaking key tasks such as cushioning and shock absorption, energy storage and return, force transmission, posture maintenance, and safety assurance. Their applications span the entire robot: in the torso, helical springs can mimic tendons and maintain dynamic balance, while disc springs can provide cushioning and energy storage; in weight-bearing joints such as the hips and knees, disc springs or helical springs effectively absorb impacts and protect precision transmission mechanisms; in the legs, helical springs or spring steel act as resilient bones, enabling high-frequency, rapid walking or jumping; in the ankles, compact combinations of ring springs provide excellent elasticity and damping within limited space, achieving smooth walking and landing cushioning, protecting both the robot and the ground; in the dexterous hand, miniature tension and torsion springs ensure precise gripping and rapid return of the fingers. Research from the Institute of Automation, Chinese Academy of Sciences, indicates that introducing springs or damping elements into rigid actuators to form 'series elastic actuators' (SEAs) can significantly improve the robot's environmental adaptability, force control accuracy, and energy efficiency, representing an inevitable trend in the future development of high-performance robots. In 2025, the global production capacity of humanoid robot springs is estimated at approximately 11.078 million units, with a unit price of approximately US$5.8 per unit. The industry's gross profit margin is generally between 20% and 35%, and companies have an annual

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production capacity of 100,000 units.

With the continuous breakthroughs in the application of humanoid robots in service industries, collaborative manufacturing, medical rehabilitation, and hazardous environments, the demand for precision elastic components in robot systems is rapidly increasing. Humanoid robots require complex joint movements, high-frequency vibration damping, and energy recovery capabilities when performing tasks, thus placing higher performance demands on spring components. Traditional industrial springs, limited by their non-adjustable stiffness, insufficient fatigue life, and poor dynamic performance, are unable to meet the needs of next-generation robot systems, creating a vast market space for high-performance robot springs. Simultaneously, advancements in materials science, computer-aided design and manufacturing technologies, and high-precision machining processes have enabled spring design to achieve adjustable stiffness, nonlinear load response, and optimized load distribution, significantly improving robot joint performance and durability. Furthermore, with the development of third-generation robot joint drive systems, keyed cable technology may gradually replace traditional spring technology, becoming a new trend in joint drive systems. This technological innovation will further improve system flexibility and accuracy, reduce mechanical complexity and energy loss, and may have a certain impact on the traditional spring market. Despite the broad market prospects, the humanoid robot spring market also faces challenges. First, as a crucial component of robot transmission systems, springs directly impact system stability and reliability, resulting in extremely high manufacturing standards and significant supply chain barriers. High-end robot springs typically require complex geometric designs, precision heat treatment, and rigorous fatigue testing, leading to high R&D and manufacturing thresholds and significant challenges in large-scale production. Second, the global robot application market is significantly influenced by macroeconomic cycles, industrial policies, and the pace of capital investment. Especially given the financial pressures faced by emerging robot companies, they are more cautious in their procurement decisions for core components. Furthermore, price fluctuations in spring materials (such as high-strength alloys and shape memory alloys) also disrupt costs. From a downstream demand perspective, the application of springs in humanoid robots is accelerating from experimental R&D to pilot production and industrialization. In industrial manufacturing automation, high-performance spring combinations are crucial components in robot joints and transmission chains, enhancing accuracy and response speed. In service robots, springs are used for leg support, energy recovery, and cushioning structures, reducing power system load and energy consumption. In medical rehabilitation robots, dual-lever spring systems optimize joint compliance and human-robot interaction safety. Furthermore, with the emergence of third-generation joint actuation solutions, keyed-wire actuation technology may

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gradually replace traditional spring designs, especially in the field of biomimetic robots requiring high compliance and precise motion control. Compared to springs, keyed-wire technology offers higher degrees of freedom and more precise control while avoiding the fatigue problems of traditional springs. In the coming years, with the large-scale deployment of humanoid robots and the expansion of high-end applications, the market demand for springs as core transmission and buffering components is expected to continue to grow, but the trend of keyed-wire replacing springs may impact the market structure.

This report studies the global Humanoid Robot Springs production, demand, key manufacturers, and key regions.

This report is a detailed and comprehensive analysis of the world market for Humanoid Robot Springs and provides market size (US$ million) and Year-over-Year (YoY) Growth, considering 2025 as the base year. This report explores demand trends and competition, as well as details the characteristics of Humanoid Robot Springs that contribute to its increasing demand across many markets.

Highlights and key features of the study
Global Humanoid Robot Springs total production and demand, 2021-2032, (K Units)
Global Humanoid Robot Springs total production value, 2021-2032, (USD Million)
Global Humanoid Robot Springs production by region & country, production, value, CAGR, 2021-2032, (USD Million) & (K Units), (based on production site)
Global Humanoid Robot Springs consumption by region & country, CAGR, 2021-2032 & (K Units)
U.S. VS China: Humanoid Robot Springs domestic production, consumption, key domestic manufacturers and share
Global Humanoid Robot Springs production by manufacturer, production, price, value and market share 2021-2026, (USD Million) & (K Units)
Global Humanoid Robot Springs production by Type, production, value, CAGR, 2021-2032, (USD Million) & (K Units)
Global Humanoid Robot Springs production by Application, production, value, CAGR, 2021-2032, (USD Million) & (K Units)

This report profiles key players in the global Humanoid Robot Springs market based on the following parameters - company overview, production, value, price, gross margin, product portfolio, geographical presence, and key developments. Key companies covered as a part of this study include John Evans' Sons, Newcomb Spring, Lee Spring, Kern Liebers, Vulcan Spring, Mario Schaaf GmbH & Co. KG, Associated Spring, Acxess

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Spring, Katy Spring, European Springs, etc.

This report also provides key insights about market drivers, restraints, opportunities, new product launches or approvals.

Stakeholders would have ease in decision-making through various strategy matrices used in analyzing the World Humanoid Robot Springs market

Detailed Segmentation:

Each section contains quantitative market data including market by value (US$ Millions), volume (production, consumption) & (K Units) and average price (US$/Unit) by manufacturer, by Type, and by Application. Data is given for the years 2021-2032 by year with 2025 as the base year, 2026 as the estimate year, and 2027-2032 as the forecast year.

Global Humanoid Robot Springs Market, By Region:

United States

China

Europe

Japan

South Korea

ASEAN

India

Rest of World

Global Humanoid Robot Springs Market, Segmentation by Type:

Tension Spring

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Compression Spring

Torsion Spring

Wave Spring

Disc Spring

Snap Ring

Global Humanoid Robot Springs Market, Segmentation by Material:

Chromium Alloy

Nickel-Titanium Alloy

Other

Global Humanoid Robot Springs Market, Segmentation by Channel:

Direct Selling

Distribution

Global Humanoid Robot Springs Market, Segmentation by Application:

Robot Torso

Robot Dexterous Hand

Others

Companies Profiled:

John Evans' Sons

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Newcomb Spring

Lee Spring

Kern Liebers

Vulcan Spring

Mario Schaaf GmbH & Co. KG

Associated Spring

Acxess Spring

Katy Spring

European Springs

Myers Spring

Tokai Spring industries, Inc.

Lesj?fors Group

Hwaway Technology Corporation

Freewon China Co.,Ltd.

Zhejiang Meili High Technology Co.,Ltd.

Key Questions Answered:

1. How big is the global Humanoid Robot Springs market?
2. What is the demand of the global Humanoid Robot Springs market?
3. What is the year over year growth of the global Humanoid Robot Springs market?
4. What is the production and production value of the global Humanoid Robot Springs market?
5. Who are the key producers in the global Humanoid Robot Springs market?

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6. What are the growth factors driving the market demand?

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Contents

1 SUPPLY SUMMARY

1.1 Humanoid Robot Springs Introduction
1.2 World Humanoid Robot Springs Supply & Forecast
  1.2.1 World Humanoid Robot Springs Production Value (2021 & 2025 & 2032)
  1.2.2 World Humanoid Robot Springs Production (2021-2032)
  1.2.3 World Humanoid Robot Springs Pricing Trends (2021-2032)
1.3 World Humanoid Robot Springs Production by Region (Based on Production Site)
  1.3.1 World Humanoid Robot Springs Production Value by Region (2021-2032)
  1.3.2 World Humanoid Robot Springs Production by Region (2021-2032)
  1.3.3 World Humanoid Robot Springs Average Price by Region (2021-2032)
  1.3.4 North America Humanoid Robot Springs Production (2021-2032)
  1.3.5 Europe Humanoid Robot Springs Production (2021-2032)
  1.3.6 China Humanoid Robot Springs Production (2021-2032)
  1.3.7 Japan Humanoid Robot Springs Production (2021-2032)
1.4 Market Drivers, Restraints and Trends
  1.4.1 Humanoid Robot Springs Market Drivers
  1.4.2 Factors Affecting Demand
  1.4.3 Humanoid Robot Springs Major Market Trends

2 DEMAND SUMMARY

2.1 World Humanoid Robot Springs Demand (2021-2032)
2.2 World Humanoid Robot Springs Consumption by Region
  2.2.1 World Humanoid Robot Springs Consumption by Region (2021-2026)
  2.2.2 World Humanoid Robot Springs Consumption Forecast by Region (2027-2032)
2.3 United States Humanoid Robot Springs Consumption (2021-2032)
2.4 China Humanoid Robot Springs Consumption (2021-2032)
2.5 Europe Humanoid Robot Springs Consumption (2021-2032)
2.6 Japan Humanoid Robot Springs Consumption (2021-2032)
2.7 South Korea Humanoid Robot Springs Consumption (2021-2032)
2.8 ASEAN Humanoid Robot Springs Consumption (2021-2032)
2.9 India Humanoid Robot Springs Consumption (2021-2032)

3 WORLD MANUFACTURERS COMPETITIVE ANALYSIS

3.1 World Humanoid Robot Springs Production Value by Manufacturer (2021-2026)

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3.2 World Humanoid Robot Springs Production by Manufacturer (2021-2026)
3.3 World Humanoid Robot Springs Average Price by Manufacturer (2021-2026)
3.4 Humanoid Robot Springs Company Evaluation Quadrant
3.5 Industry Rank and Concentration Rate (CR)
  3.5.1 Global Humanoid Robot Springs Industry Rank of Major Manufacturers
  3.5.2 Global Concentration Ratios (CR4) for Humanoid Robot Springs in 2025
  3.5.3 Global Concentration Ratios (CR8) for Humanoid Robot Springs in 2025
3.6 Humanoid Robot Springs Market: Overall Company Footprint Analysis
  3.6.1 Humanoid Robot Springs Market: Region Footprint
  3.6.2 Humanoid Robot Springs Market: Company Product Type Footprint
  3.6.3 Humanoid Robot Springs Market: Company Product Application Footprint
3.7 Competitive Environment
  3.7.1 Historical Structure of the Industry
  3.7.2 Barriers of Market Entry
  3.7.3 Factors of Competition
3.8 New Entrant and Capacity Expansion Plans
3.9 Mergers, Acquisition, Agreements, and Collaborations

4 UNITED STATES VS CHINA VS REST OF THE WORLD

4.1 United States VS China: Humanoid Robot Springs Production Value Comparison
  4.1.1 United States VS China: Humanoid Robot Springs Production Value Comparison (2021 & 2025 & 2032)
  4.1.2 United States VS China: Humanoid Robot Springs Production Value Market Share Comparison (2021 & 2025 & 2032)
4.2 United States VS China: Humanoid Robot Springs Production Comparison
  4.2.1 United States VS China: Humanoid Robot Springs Production Comparison (2021 & 2025 & 2032)
  4.2.2 United States VS China: Humanoid Robot Springs Production Market Share Comparison (2021 & 2025 & 2032)
4.3 United States VS China: Humanoid Robot Springs Consumption Comparison
  4.3.1 United States VS China: Humanoid Robot Springs Consumption Comparison (2021 & 2025 & 2032)
  4.3.2 United States VS China: Humanoid Robot Springs Consumption Market Share Comparison (2021 & 2025 & 2032)
4.4 United States Based Humanoid Robot Springs Manufacturers and Market Share, 2021-2026
  4.4.1 United States Based Humanoid Robot Springs Manufacturers, Headquarters and Production Site (States, Country)

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4.4.2 United States Based Manufacturers Humanoid Robot Springs Production Value (2021-2026)
4.4.3 United States Based Manufacturers Humanoid Robot Springs Production (2021-2026)
4.5 China Based Humanoid Robot Springs Manufacturers and Market Share
4.5.1 China Based Humanoid Robot Springs Manufacturers, Headquarters and Production Site (Province, Country)
4.5.2 China Based Manufacturers Humanoid Robot Springs Production Value (2021-2026)
4.5.3 China Based Manufacturers Humanoid Robot Springs Production (2021-2026)
4.6 Rest of World Based Humanoid Robot Springs Manufacturers and Market Share, 2021-2026
4.6.1 Rest of World Based Humanoid Robot Springs Manufacturers, Headquarters and Production Site (State, Country)
4.6.2 Rest of World Based Manufacturers Humanoid Robot Springs Production Value (2021-2026)
4.6.3 Rest of World Based Manufacturers Humanoid Robot Springs Production (2021-2026)

5 MARKET ANALYSIS BY TYPE

5.1 World Humanoid Robot Springs Market Size Overview by Type: 2021 VS 2025 VS 2032
5.2 Segment Introduction by Type
5.2.1 Tension Spring
5.2.2 Compression Spring
5.2.3 Torsion Spring
5.2.4 Wave Spring
5.2.5 Disc Spring
5.2.6 Snap Ring
5.3 Market Segment by Type
5.3.1 World Humanoid Robot Springs Production by Type (2021-2032)
5.3.2 World Humanoid Robot Springs Production Value by Type (2021-2032)
5.3.3 World Humanoid Robot Springs Average Price by Type (2021-2032)

6 MARKET ANALYSIS BY MATERIAL

6.1 World Humanoid Robot Springs Market Size Overview by Material: 2021 VS 2025 VS 2032

+357 96 030922
info@marketpublishers.com

6.2 Segment Introduction by Material
6.2.1 Chromium Alloy
6.2.2 Nickel-Titanium Alloy
6.2.3 Other
6.3 Market Segment by Material
6.3.1 World Humanoid Robot Springs Production by Material (2021-2032)
6.3.2 World Humanoid Robot Springs Production Value by Material (2021-2032)
6.3.3 World Humanoid Robot Springs Average Price by Material (2021-2032)

7 MARKET ANALYSIS BY CHANNEL

7.1 World Humanoid Robot Springs Market Size Overview by Channel: 2021 VS 2025 VS 2032
7.2 Segment Introduction by Channel
7.2.1 Direct Selling
7.2.2 Distribution
7.3 Market Segment by Channel
7.3.1 World Humanoid Robot Springs Production by Channel (2021-2032)
7.3.2 World Humanoid Robot Springs Production Value by Channel (2021-2032)
7.3.3 World Humanoid Robot Springs Average Price by Channel (2021-2032)

8 MARKET ANALYSIS BY APPLICATION

8.1 World Humanoid Robot Springs Market Size Overview by Application: 2021 VS 2025 VS 2032
8.2 Segment Introduction by Application
8.2.1 Robot Torso
8.2.2 Robot Dexterous Hand
8.2.3 Others
8.3 Market Segment by Application
8.3.1 World Humanoid Robot Springs Production by Application (2021-2032)
8.3.2 World Humanoid Robot Springs Production Value by Application (2021-2032)
8.3.3 World Humanoid Robot Springs Average Price by Application (2021-2032)

9 COMPANY PROFILES

9.1 John Evans' Sons
9.1.1 John Evans' Sons Details
9.1.2 John Evans' Sons Major Business

+357 96 030922
info@marketpublishers.com

9.1.3 John Evans' Sons Humanoid Robot Springs Product and Services
9.1.4 John Evans' Sons Humanoid Robot Springs Production, Price, Value, Gross Margin and Market Share (2021-2026)
9.1.5 John Evans' Sons Recent Developments/Updates
9.1.6 John Evans' Sons Competitive Strengths & Weaknesses
9.2 Newcomb Spring
9.2.1 Newcomb Spring Details
9.2.2 Newcomb Spring Major Business
9.2.3 Newcomb Spring Humanoid Robot Springs Product and Services
9.2.4 Newcomb Spring Humanoid Robot Springs Production, Price, Value, Gross Margin and Market Share (2021-2026)
9.2.5 Newcomb Spring Recent Developments/Updates
9.2.6 Newcomb Spring Competitive Strengths & Weaknesses
9.3 Lee Spring
9.3.1 Lee Spring Details
9.3.2 Lee Spring Major Business
9.3.3 Lee Spring Humanoid Robot Springs Product and Services
9.3.4 Lee Spring Humanoid Robot Springs Production, Price, Value, Gross Margin and Market Share (2021-2026)
9.3.5 Lee Spring Recent Developments/Updates
9.3.6 Lee Spring Competitive Strengths & Weaknesses
9.4 Kern Liebers
9.4.1 Kern Liebers Details
9.4.2 Kern Liebers Major Business
9.4.3 Kern Liebers Humanoid Robot Springs Product and Services
9.4.4 Kern Liebers Humanoid Robot Springs Production, Price, Value, Gross Margin and Market Share (2021-2026)
9.4.5 Kern Liebers Recent Developments/Updates
9.4.6 Kern Liebers Competitive Strengths & Weaknesses
9.5 Vulcan Spring
9.5.1 Vulcan Spring Details
9.5.2 Vulcan Spring Major Business
9.5.3 Vulcan Spring Humanoid Robot Springs Product and Services
9.5.4 Vulcan Spring Humanoid Robot Springs Production, Price, Value, Gross Margin and Market Share (2021-2026)
9.5.5 Vulcan Spring Recent Developments/Updates
9.5.6 Vulcan Spring Competitive Strengths & Weaknesses
9.6 Mario Schaaf GmbH & Co. KG
9.6.1 Mario Schaaf GmbH & Co. KG Details

+357 96 030922
info@marketpublishers.com

9.6.2 Mario Schaaf GmbH & Co. KG Major Business
9.6.3 Mario Schaaf GmbH & Co. KG Humanoid Robot Springs Product and Services
9.6.4 Mario Schaaf GmbH & Co. KG Humanoid Robot Springs Production, Price, Value, Gross Margin and Market Share (2021-2026)
9.6.5 Mario Schaaf GmbH & Co. KG Recent Developments/Updates
9.6.6 Mario Schaaf GmbH & Co. KG Competitive Strengths & Weaknesses
9.7 Associated Spring
9.7.1 Associated Spring Details
9.7.2 Associated Spring Major Business
9.7.3 Associated Spring Humanoid Robot Springs Product and Services
9.7.4 Associated Spring Humanoid Robot Springs Production, Price, Value, Gross Margin and Market Share (2021-2026)
9.7.5 Associated Spring Recent Developments/Updates
9.7.6 Associated Spring Competitive Strengths & Weaknesses
9.8 Acxess Spring
9.8.1 Acxess Spring Details
9.8.2 Acxess Spring Major Business
9.8.3 Acxess Spring Humanoid Robot Springs Product and Services
9.8.4 Acxess Spring Humanoid Robot Springs Production, Price, Value, Gross Margin and Market Share (2021-2026)
9.8.5 Acxess Spring Recent Developments/Updates
9.8.6 Acxess Spring Competitive Strengths & Weaknesses
9.9 Katy Spring
9.9.1 Katy Spring Details
9.9.2 Katy Spring Major Business
9.9.3 Katy Spring Humanoid Robot Springs Product and Services
9.9.4 Katy Spring Humanoid Robot Springs Production, Price, Value, Gross Margin and Market Share (2021-2026)
9.9.5 Katy Spring Recent Developments/Updates
9.9.6 Katy Spring Competitive Strengths & Weaknesses
9.10 European Springs
9.10.1 European Springs Details
9.10.2 European Springs Major Business
9.10.3 European Springs Humanoid Robot Springs Product and Services
9.10.4 European Springs Humanoid Robot Springs Production, Price, Value, Gross Margin and Market Share (2021-2026)
9.10.5 European Springs Recent Developments/Updates
9.10.6 European Springs Competitive Strengths & Weaknesses
9.11 Myers Spring

+357 96 030922
info@marketpublishers.com

9.11.1 Myers Spring Details
9.11.2 Myers Spring Major Business
9.11.3 Myers Spring Humanoid Robot Springs Product and Services
9.11.4 Myers Spring Humanoid Robot Springs Production, Price, Value, Gross Margin and Market Share (2021-2026)
9.11.5 Myers Spring Recent Developments/Updates
9.11.6 Myers Spring Competitive Strengths & Weaknesses
9.12 Tokai Spring industries, Inc.
9.12.1 Tokai Spring industries, Inc. Details
9.12.2 Tokai Spring industries, Inc. Major Business
9.12.3 Tokai Spring industries, Inc. Humanoid Robot Springs Product and Services
9.12.4 Tokai Spring industries, Inc. Humanoid Robot Springs Production, Price, Value, Gross Margin and Market Share (2021-2026)
9.12.5 Tokai Spring industries, Inc. Recent Developments/Updates
9.12.6 Tokai Spring industries, Inc. Competitive Strengths & Weaknesses
9.13 Lesj?fors Group
9.13.1 Lesj?fors Group Details
9.13.2 Lesj?fors Group Major Business
9.13.3 Lesj?fors Group Humanoid Robot Springs Product and Services
9.13.4 Lesj?fors Group Humanoid Robot Springs Production, Price, Value, Gross Margin and Market Share (2021-2026)
9.13.5 Lesj?fors Group Recent Developments/Updates
9.13.6 Lesj?fors Group Competitive Strengths & Weaknesses
9.14 Hwaway Technology Corporation
9.14.1 Hwaway Technology Corporation Details
9.14.2 Hwaway Technology Corporation Major Business
9.14.3 Hwaway Technology Corporation Humanoid Robot Springs Product and Services
9.14.4 Hwaway Technology Corporation Humanoid Robot Springs Production, Price, Value, Gross Margin and Market Share (2021-2026)
9.14.5 Hwaway Technology Corporation Recent Developments/Updates
9.14.6 Hwaway Technology Corporation Competitive Strengths & Weaknesses
9.15 Freewon China Co.,Ltd.
9.15.1 Freewon China Co.,Ltd. Details
9.15.2 Freewon China Co.,Ltd. Major Business
9.15.3 Freewon China Co.,Ltd. Humanoid Robot Springs Product and Services
9.15.4 Freewon China Co.,Ltd. Humanoid Robot Springs Production, Price, Value, Gross Margin and Market Share (2021-2026)
9.15.5 Freewon China Co.,Ltd. Recent Developments/Updates

+357 96 030922
info@marketpublishers.com

9.15.6 Freewon China Co.,Ltd. Competitive Strengths & Weaknesses
9.16 Zhejiang Meili High Technology Co.,Ltd.
9.16.1 Zhejiang Meili High Technology Co.,Ltd. Details
9.16.2 Zhejiang Meili High Technology Co.,Ltd. Major Business
9.16.3 Zhejiang Meili High Technology Co.,Ltd. Humanoid Robot Springs Product and Services
9.16.4 Zhejiang Meili High Technology Co.,Ltd. Humanoid Robot Springs Production, Price, Value, Gross Margin and Market Share (2021-2026)
9.16.5 Zhejiang Meili High Technology Co.,Ltd. Recent Developments/Updates
9.16.6 Zhejiang Meili High Technology Co.,Ltd. Competitive Strengths & Weaknesses

10 INDUSTRY CHAIN ANALYSIS

10.1 Humanoid Robot Springs Industry Chain
10.2 Humanoid Robot Springs Upstream Analysis
10.2.1 Humanoid Robot Springs Core Raw Materials
10.2.2 Main Manufacturers of Humanoid Robot Springs Core Raw Materials
10.3 Midstream Analysis
10.4 Downstream Analysis
10.5 Humanoid Robot Springs Production Mode
10.6 Humanoid Robot Springs Procurement Model
10.7 Humanoid Robot Springs Industry Sales Model and Sales Channels
10.7.1 Humanoid Robot Springs Sales Model
10.7.2 Humanoid Robot Springs Typical Distributors

11 RESEARCH FINDINGS AND CONCLUSION

12 APPENDIX

12.1 Methodology
12.2 Research Process and Data Source
12.3 Disclaimer

+357 96 030922
info@marketpublishers.com

List Of Tables

LIST OF TABLES

Table 1. World Humanoid Robot Springs Production Value by Region (2021, 2025 and 2032) & (USD Million)
Table 2. World Humanoid Robot Springs Production Value by Region (2021-2026) & (USD Million)
Table 3. World Humanoid Robot Springs Production Value by Region (2027-2032) & (USD Million)
Table 4. World Humanoid Robot Springs Production Value Market Share by Region (2021-2026)
Table 5. World Humanoid Robot Springs Production Value Market Share by Region (2027-2032)
Table 6. World Humanoid Robot Springs Production by Region (2021-2026) & (K Units)
Table 7. World Humanoid Robot Springs Production by Region (2027-2032) & (K Units)
Table 8. World Humanoid Robot Springs Production Market Share by Region (2021-2026)
Table 9. World Humanoid Robot Springs Production Market Share by Region (2027-2032)
Table 10. World Humanoid Robot Springs Average Price by Region (2021-2026) & (US$/Unit)
Table 11. World Humanoid Robot Springs Average Price by Region (2027-2032) & (US$/Unit)
Table 12. Humanoid Robot Springs Major Market Trends
Table 13. World Humanoid Robot Springs Consumption Growth Rate Forecast by Region (2021 & 2025 & 2032) & (K Units)
Table 14. World Humanoid Robot Springs Consumption by Region (2021-2026) & (K Units)
Table 15. World Humanoid Robot Springs Consumption Forecast by Region (2027-2032) & (K Units)
Table 16. World Humanoid Robot Springs Production Value by Manufacturer (2021-2026) & (USD Million)
Table 17. Production Value Market Share of Key Humanoid Robot Springs Producers in 2025
Table 18. World Humanoid Robot Springs Production by Manufacturer (2021-2026) & (K Units)
Table 19. Production Market Share of Key Humanoid Robot Springs Producers in 2025
Table 20. World Humanoid Robot Springs Average Price by Manufacturer (2021-2026)

+357 96 030922
info@marketpublishers.com

& (US$/Unit)
Table 21. Global Humanoid Robot Springs Company Evaluation Quadrant
Table 22. World Humanoid Robot Springs Industry Rank of Major Manufacturers, Based on Production Value in 2025
Table 23. Head Office and Humanoid Robot Springs Production Site of Key Manufacturer
Table 24. Humanoid Robot Springs Market: Company Product Type Footprint
Table 25. Humanoid Robot Springs Market: Company Product Application Footprint
Table 26. Humanoid Robot Springs Competitive Factors
Table 27. Humanoid Robot Springs New Entrant and Capacity Expansion Plans
Table 28. Humanoid Robot Springs Mergers & Acquisitions Activity
Table 29. United States VS China Humanoid Robot Springs Production Value Comparison, (2021 & 2025 & 2032) & (USD Million)
Table 30. United States VS China Humanoid Robot Springs Production Comparison, (2021 & 2025 & 2032) & (K Units)
Table 31. United States VS China Humanoid Robot Springs Consumption Comparison, (2021 & 2025 & 2032) & (K Units)
Table 32. United States Based Humanoid Robot Springs Manufacturers, Headquarters and Production Site (States, Country)
Table 33. United States Based Manufacturers Humanoid Robot Springs Production Value, (2021-2026) & (USD Million)
Table 34. United States Based Manufacturers Humanoid Robot Springs Production Value Market Share (2021-2026)
Table 35. United States Based Manufacturers Humanoid Robot Springs Production (2021-2026) & (K Units)
Table 36. United States Based Manufacturers Humanoid Robot Springs Production Market Share (2021-2026)
Table 37. China Based Humanoid Robot Springs Manufacturers, Headquarters and Production Site (Province, Country)
Table 38. China Based Manufacturers Humanoid Robot Springs Production Value, (2021-2026) & (USD Million)
Table 39. China Based Manufacturers Humanoid Robot Springs Production Value Market Share (2021-2026)
Table 40. China Based Manufacturers Humanoid Robot Springs Production, (2021-2026) & (K Units)
Table 41. China Based Manufacturers Humanoid Robot Springs Production Market Share (2021-2026)
Table 42. Rest of World Based Humanoid Robot Springs Manufacturers, Headquarters and Production Site (State, Country)

+357 96 030922
info@marketpublishers.com

Table 43. Rest of World Based Manufacturers Humanoid Robot Springs Production Value, (2021-2026) & (USD Million)
Table 44. Rest of World Based Manufacturers Humanoid Robot Springs Production Value Market Share (2021-2026)
Table 45. Rest of World Based Manufacturers Humanoid Robot Springs Production, (2021-2026) & (K Units)
Table 46. Rest of World Based Manufacturers Humanoid Robot Springs Production Market Share (2021-2026)
Table 47. World Humanoid Robot Springs Production Value by Type, (USD Million), 2021 & 2025 & 2032
Table 48. World Humanoid Robot Springs Production by Type (2021-2026) & (K Units)
Table 49. World Humanoid Robot Springs Production by Type (2027-2032) & (K Units)
Table 50. World Humanoid Robot Springs Production Value by Type (2021-2026) & (USD Million)
Table 51. World Humanoid Robot Springs Production Value by Type (2027-2032) & (USD Million)
Table 52. World Humanoid Robot Springs Average Price by Type (2021-2026) & (US$/Unit)
Table 53. World Humanoid Robot Springs Average Price by Type (2027-2032) & (US$/Unit)
Table 54. World Humanoid Robot Springs Production Value by Material, (USD Million), 2021 & 2025 & 2032
Table 55. World Humanoid Robot Springs Production by Material (2021-2026) & (K Units)
Table 56. World Humanoid Robot Springs Production by Material (2027-2032) & (K Units)
Table 57. World Humanoid Robot Springs Production Value by Material (2021-2026) & (USD Million)
Table 58. World Humanoid Robot Springs Production Value by Material (2027-2032) & (USD Million)
Table 59. World Humanoid Robot Springs Average Price by Material (2021-2026) & (US$/Unit)
Table 60. World Humanoid Robot Springs Average Price by Material (2027-2032) & (US$/Unit)
Table 61. World Humanoid Robot Springs Production Value by Channel, (USD Million), 2021 & 2025 & 2032
Table 62. World Humanoid Robot Springs Production by Channel (2021-2026) & (K Units)
Table 63. World Humanoid Robot Springs Production by Channel (2027-2032) & (K

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Units)
Table 64. World Humanoid Robot Springs Production Value by Channel (2021-2026) & (USD Million)
Table 65. World Humanoid Robot Springs Production Value by Channel (2027-2032) & (USD Million)
Table 66. World Humanoid Robot Springs Average Price by Channel (2021-2026) & (US$/Unit)
Table 67. World Humanoid Robot Springs Average Price by Channel (2027-2032) & (US$/Unit)
Table 68. World Humanoid Robot Springs Production Value by Application, (USD Million), 2021 & 2025 & 2032
Table 69. World Humanoid Robot Springs Production by Application (2021-2026) & (K Units)
Table 70. World Humanoid Robot Springs Production by Application (2027-2032) & (K Units)
Table 71. World Humanoid Robot Springs Production Value by Application (2021-2026) & (USD Million)
Table 72. World Humanoid Robot Springs Production Value by Application (2027-2032) & (USD Million)
Table 73. World Humanoid Robot Springs Average Price by Application (2021-2026) & (US$/Unit)
Table 74. World Humanoid Robot Springs Average Price by Application (2027-2032) & (US$/Unit)
Table 75. John Evans' Sons Basic Information, Manufacturing Base and Competitors
Table 76. John Evans' Sons Major Business
Table 77. John Evans' Sons Humanoid Robot Springs Product and Services
Table 78. John Evans' Sons Humanoid Robot Springs Production (K Units), Price (US$/Unit), Production Value (USD Million), Gross Margin and Market Share (2021-2026)
Table 79. John Evans' Sons Recent Developments/Updates
Table 80. John Evans' Sons Competitive Strengths & Weaknesses
Table 81. Newcomb Spring Basic Information, Manufacturing Base and Competitors
Table 82. Newcomb Spring Major Business
Table 83. Newcomb Spring Humanoid Robot Springs Product and Services
Table 84. Newcomb Spring Humanoid Robot Springs Production (K Units), Price (US$/Unit), Production Value (USD Million), Gross Margin and Market Share (2021-2026)
Table 85. Newcomb Spring Recent Developments/Updates
Table 86. Newcomb Spring Competitive Strengths & Weaknesses

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Table 87. Lee Spring Basic Information, Manufacturing Base and Competitors
Table 88. Lee Spring Major Business
Table 89. Lee Spring Humanoid Robot Springs Product and Services
Table 90. Lee Spring Humanoid Robot Springs Production (K Units), Price (US$/Unit), Production Value (USD Million), Gross Margin and Market Share (2021-2026)
Table 91. Lee Spring Recent Developments/Updates
Table 92. Lee Spring Competitive Strengths & Weaknesses
Table 93. Kern Liebers Basic Information, Manufacturing Base and Competitors
Table 94. Kern Liebers Major Business
Table 95. Kern Liebers Humanoid Robot Springs Product and Services
Table 96. Kern Liebers Humanoid Robot Springs Production (K Units), Price (US$/Unit), Production Value (USD Million), Gross Margin and Market Share (2021-2026)
Table 97. Kern Liebers Recent Developments/Updates
Table 98. Kern Liebers Competitive Strengths & Weaknesses
Table 99. Vulcan Spring Basic Information, Manufacturing Base and Competitors
Table 100. Vulcan Spring Major Business
Table 101. Vulcan Spring Humanoid Robot Springs Product and Services
Table 102. Vulcan Spring Humanoid Robot Springs Production (K Units), Price (US$/Unit), Production Value (USD Million), Gross Margin and Market Share (2021-2026)
Table 103. Vulcan Spring Recent Developments/Updates
Table 104. Vulcan Spring Competitive Strengths & Weaknesses
Table 105. Mario Schaaf GmbH & Co. KG Basic Information, Manufacturing Base and Competitors
Table 106. Mario Schaaf GmbH & Co. KG Major Business
Table 107. Mario Schaaf GmbH & Co. KG Humanoid Robot Springs Product and Services
Table 108. Mario Schaaf GmbH & Co. KG Humanoid Robot Springs Production (K Units), Price (US$/Unit), Production Value (USD Million), Gross Margin and Market Share (2021-2026)
Table 109. Mario Schaaf GmbH & Co. KG Recent Developments/Updates
Table 110. Mario Schaaf GmbH & Co. KG Competitive Strengths & Weaknesses
Table 111. Associated Spring Basic Information, Manufacturing Base and Competitors
Table 112. Associated Spring Major Business
Table 113. Associated Spring Humanoid Robot Springs Product and Services
Table 114. Associated Spring Humanoid Robot Springs Production (K Units), Price (US$/Unit), Production Value (USD Million), Gross Margin and Market Share (2021-2026)
Table 115. Associated Spring Recent Developments/Updates

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Table 116. Associated Spring Competitive Strengths & Weaknesses
Table 117. Acxess Spring Basic Information, Manufacturing Base and Competitors
Table 118. Acxess Spring Major Business
Table 119. Acxess Spring Humanoid Robot Springs Product and Services
Table 120. Acxess Spring Humanoid Robot Springs Production (K Units), Price (US$/Unit), Production Value (USD Million), Gross Margin and Market Share (2021-2026)
Table 121. Acxess Spring Recent Developments/Updates
Table 122. Acxess Spring Competitive Strengths & Weaknesses
Table 123. Katy Spring Basic Information, Manufacturing Base and Competitors
Table 124. Katy Spring Major Business
Table 125. Katy Spring Humanoid Robot Springs Product and Services
Table 126. Katy Spring Humanoid Robot Springs Production (K Units), Price (US$/Unit), Production Value (USD Million), Gross Margin and Market Share (2021-2026)
Table 127. Katy Spring Recent Developments/Updates
Table 128. Katy Spring Competitive Strengths & Weaknesses
Table 129. European Springs Basic Information, Manufacturing Base and Competitors
Table 130. European Springs Major Business
Table 131. European Springs Humanoid Robot Springs Product and Services
Table 132. European Springs Humanoid Robot Springs Production (K Units), Price (US$/Unit), Production Value (USD Million), Gross Margin and Market Share (2021-2026)
Table 133. European Springs Recent Developments/Updates
Table 134. European Springs Competitive Strengths & Weaknesses
Table 135. Myers Spring Basic Information, Manufacturing Base and Competitors
Table 136. Myers Spring Major Business
Table 137. Myers Spring Humanoid Robot Springs Product and Services
Table 138. Myers Spring Humanoid Robot Springs Production (K Units), Price (US$/Unit), Production Value (USD Million), Gross Margin and Market Share (2021-2026)
Table 139. Myers Spring Recent Developments/Updates
Table 140. Myers Spring Competitive Strengths & Weaknesses
Table 141. Tokai Spring industries, Inc. Basic Information, Manufacturing Base and Competitors
Table 142. Tokai Spring industries, Inc. Major Business
Table 143. Tokai Spring industries, Inc. Humanoid Robot Springs Product and Services
Table 144. Tokai Spring industries, Inc. Humanoid Robot Springs Production (K Units), Price (US$/Unit), Production Value (USD Million), Gross Margin and Market Share (2021-2026)

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Table 145. Tokai Spring industries, Inc. Recent Developments/Updates
Table 146. Tokai Spring industries, Inc. Competitive Strengths & Weaknesses
Table 147. Lesj?fors Group Basic Information, Manufacturing Base and Competitors
Table 148. Lesj?fors Group Major Business
Table 149. Lesj?fors Group Humanoid Robot Springs Product and Services
Table 150. Lesj?fors Group Humanoid Robot Springs Production (K Units), Price (US$/Unit), Production Value (USD Million), Gross Margin and Market Share (2021-2026)
Table 151. Lesj?fors Group Recent Developments/Updates
Table 152. Lesj?fors Group Competitive Strengths & Weaknesses
Table 153. Hwaway Technology Corporation Basic Information, Manufacturing Base and Competitors
Table 154. Hwaway Technology Corporation Major Business
Table 155. Hwaway Technology Corporation Humanoid Robot Springs Product and Services
Table 156. Hwaway Technology Corporation Humanoid Robot Springs Production (K Units), Price (US$/Unit), Production Value (USD Million), Gross Margin and Market Share (2021-2026)
Table 157. Hwaway Technology Corporation Recent Developments/Updates
Table 158. Hwaway Technology Corporation Competitive Strengths & Weaknesses
Table 159. Freewon China Co.,Ltd. Basic Information, Manufacturing Base and Competitors
Table 160. Freewon China Co.,Ltd. Major Business
Table 161. Freewon China Co.,Ltd. Humanoid Robot Springs Product and Services
Table 162. Freewon China Co.,Ltd. Humanoid Robot Springs Production (K Units), Price (US$/Unit), Production Value (USD Million), Gross Margin and Market Share (2021-2026)
Table 163. Freewon China Co.,Ltd. Recent Developments/Updates
Table 164. Freewon China Co.,Ltd. Competitive Strengths & Weaknesses
Table 165. Zhejiang Meili High Technology Co.,Ltd. Basic Information, Manufacturing Base and Competitors
Table 166. Zhejiang Meili High Technology Co.,Ltd. Major Business
Table 167. Zhejiang Meili High Technology Co.,Ltd. Humanoid Robot Springs Product and Services
Table 168. Zhejiang Meili High Technology Co.,Ltd. Humanoid Robot Springs Production (K Units), Price (US$/Unit), Production Value (USD Million), Gross Margin and Market Share (2021-2026)
Table 169. Zhejiang Meili High Technology Co.,Ltd. Recent Developments/Updates
Table 170. Zhejiang Meili High Technology Co.,Ltd. Competitive Strengths &

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Weaknesses
Table 171. Global Key Players of Humanoid Robot Springs Upstream (Raw Materials)
Table 172. Global Humanoid Robot Springs Typical Customers
Table 173. Humanoid Robot Springs Typical Distributors

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List Of Figures

LIST OF FIGURES

Figure 1. Humanoid Robot Springs Picture
Figure 2. World Humanoid Robot Springs Production Value: 2021 & 2025 & 2032, (USD Million)
Figure 3. World Humanoid Robot Springs Production Value and Forecast (2021-2032) & (USD Million)
Figure 4. World Humanoid Robot Springs Production (2021-2032) & (K Units)
Figure 5. World Humanoid Robot Springs Average Price (2021-2032) & (US$/Unit)
Figure 6. World Humanoid Robot Springs Production Value Market Share by Region (2021-2032)
Figure 7. World Humanoid Robot Springs Production Market Share by Region (2021-2032)
Figure 8. North America Humanoid Robot Springs Production (2021-2032) & (K Units)
Figure 9. Europe Humanoid Robot Springs Production (2021-2032) & (K Units)
Figure 10. China Humanoid Robot Springs Production (2021-2032) & (K Units)
Figure 11. Japan Humanoid Robot Springs Production (2021-2032) & (K Units)
Figure 12. Humanoid Robot Springs Market Drivers
Figure 13. Factors Affecting Demand
Figure 14. World Humanoid Robot Springs Consumption (2021-2032) & (K Units)
Figure 15. World Humanoid Robot Springs Consumption Market Share by Region (2021-2032)
Figure 16. United States Humanoid Robot Springs Consumption (2021-2032) & (K Units)
Figure 17. China Humanoid Robot Springs Consumption (2021-2032) & (K Units)
Figure 18. Europe Humanoid Robot Springs Consumption (2021-2032) & (K Units)
Figure 19. Japan Humanoid Robot Springs Consumption (2021-2032) & (K Units)
Figure 20. South Korea Humanoid Robot Springs Consumption (2021-2032) & (K Units)
Figure 21. ASEAN Humanoid Robot Springs Consumption (2021-2032) & (K Units)
Figure 22. India Humanoid Robot Springs Consumption (2021-2032) & (K Units)
Figure 23. Producer Shipments of Humanoid Robot Springs by Manufacturer Revenue ($MM) and Market Share (%): 2025
Figure 24. Global Four-firm Concentration Ratios (CR4) for Humanoid Robot Springs Markets in 2025
Figure 25. Global Four-firm Concentration Ratios (CR8) for Humanoid Robot Springs Markets in 2025
Figure 26. United States VS China: Humanoid Robot Springs Production Value Market

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Share Comparison (2021 & 2025 & 2032)
Figure 27. United States VS China: Humanoid Robot Springs Production Market Share Comparison (2021 & 2025 & 2032)
Figure 28. United States VS China: Humanoid Robot Springs Consumption Market Share Comparison (2021 & 2025 & 2032)
Figure 29. United States Based Manufacturers Humanoid Robot Springs Production Market Share 2025
Figure 30. China Based Manufacturers Humanoid Robot Springs Production Market Share 2025
Figure 31. Rest of World Based Manufacturers Humanoid Robot Springs Production Market Share 2025
Figure 32. World Humanoid Robot Springs Production Value by Type, (USD Million), 2021 & 2025 & 2032
Figure 33. World Humanoid Robot Springs Production Value Market Share by Type in 2025
Figure 34. Tension Spring
Figure 35. Compression Spring
Figure 36. Torsion Spring
Figure 37. Wave Spring
Figure 38. Disc Spring
Figure 39. Snap Ring
Figure 40. World Humanoid Robot Springs Production Market Share by Type (2021-2032)
Figure 41. World Humanoid Robot Springs Production Value Market Share by Type (2021-2032)
Figure 42. World Humanoid Robot Springs Average Price by Type (2021-2032) & (US$/Unit)
Figure 43. World Humanoid Robot Springs Production Value by Material, (USD Million), 2021 & 2025 & 2032
Figure 44. World Humanoid Robot Springs Production Value Market Share by Material in 2025
Figure 45. Chromium Alloy
Figure 46. Nickel-Titanium Alloy
Figure 47. Other
Figure 48. World Humanoid Robot Springs Production Market Share by Material (2021-2032)
Figure 49. World Humanoid Robot Springs Production Value Market Share by Material (2021-2032)
Figure 50. World Humanoid Robot Springs Average Price by Material (2021-2032) &

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(US$/Unit)
Figure 51. World Humanoid Robot Springs Production Value by Channel, (USD Million), 2021 & 2025 & 2032
Figure 52. World Humanoid Robot Springs Production Value Market Share by Channel in 2025
Figure 53. Direct Selling
Figure 54. Distribution
Figure 55. World Humanoid Robot Springs Production Market Share by Channel (2021-2032)
Figure 56. World Humanoid Robot Springs Production Value Market Share by Channel (2021-2032)
Figure 57. World Humanoid Robot Springs Average Price by Channel (2021-2032) & (US$/Unit)
Figure 58. World Humanoid Robot Springs Production Value by Application, (USD Million), 2021 & 2025 & 2032
Figure 59. World Humanoid Robot Springs Production Value Market Share by Application in 2025
Figure 60. Robot Torso
Figure 61. Robot Dexterous Hand
Figure 62. Others
Figure 63. World Humanoid Robot Springs Production Market Share by Application (2021-2032)
Figure 64. World Humanoid Robot Springs Production Value Market Share by Application (2021-2032)
Figure 65. World Humanoid Robot Springs Average Price by Application (2021-2032) & (US$/Unit)
Figure 66. Humanoid Robot Springs Industry Chain
Figure 67. Humanoid Robot Springs Procurement Model
Figure 68. Humanoid Robot Springs Sales Model
Figure 69. Humanoid Robot Springs Sales Channels, Direct Sales, and Distribution
Figure 70. Methodology
Figure 71. Research Process and Data Source

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