

Global Humanoid Robot Multi-fingered Dexterous Hand Market 2026 by Manufacturers, Regions, Type and Application, Forecast to 2032

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Abstracts

According to our (Global Info Research) latest study, the global Humanoid Robot Multi-fingered Dexterous Hand market size was valued at US\$ 280 million in 2025 and is forecast to a readjusted size of US\$ 9402 million by 2032 with a CAGR of 65.9% during review period.

In 2024, global Humanoid Robot Multi-fingered Dexterous Hand sales reached approximately 14,984 Units, with an average market price of around 7,960 USD/Unit.

As a new type of end effector of robots, dexterous hands are an important topic in robot research, and research progress has accelerated at home and abroad in recent years.

Dexterous hands are a new type of end effector of robots. Generally speaking, the ways in which robots interact with the environment mainly include: moving and walking, obtaining information such as vision, and executing and outputting decisions. End effector is a general term for the robot's execution parts. It is generally installed at the end of the robot's wrist and is a device that directly executes tasks. As the last link and execution part of the interaction between the robot and the environment, the end effector plays an extremely important role in improving the flexibility and ease of use of the robot. The quality of its performance largely determines the working performance of the entire robot.

The dexterous hand of a humanoid robot is a special end effector designed based on the kinematics of the human hand. Unlike the end effector of an industrial robot, which has poor versatility and can only complete specific tasks such as welding and painting, the dexterous hand has universal grasping capabilities. The basic feature is that it has

at least 3 fingers, each finger has at least 3 degrees of freedom whose axes are not completely parallel, and usually integrates multiple sensors such as force perception and proximity perception.

Multi-fingered dexterous hand: The mechanism is multi-finger and multi-joint, and the most common is 3 to 5 fingers, each finger has 3 joints, and the kinematic pairs of the finger joints are all revolute pairs. The main driving methods of dexterous hands include 4 types: hydraulic drive, motor drive, pneumatic drive, and shape memory alloy drive. For example, the Okada dexterous hand of Japan's 'Electronic Technology Laboratory', the Stanford/JPL dexterous hand successfully developed by Stanford University in the United States, and the Utah/MIT dexterous hand jointly developed by the Massachusetts Institute of Technology and the University of Utah.

The humanoid robot multi-fingered dexterous hand has received continuous R&D investment and widespread attention because it can imitate the various dexterous grasping and complex operation capabilities of human hands. From the perspective of application fields, the fields where dexterous hands have achieved mature applications are mainly medical and industrial fields.

The report statistic scope is Multi-fingered dexterous hands (above three fingers, including three fingers, four fingers and five fingers types) for humanoid robots. The data analysis is beginning 2024.

This report is a detailed and comprehensive analysis for global Humanoid Robot Multi-fingered Dexterous Hand market. Both quantitative and qualitative analyses are presented by manufacturers, by region & country, by Type and by Application. As the market is constantly changing, this report explores the competition, supply and demand trends, as well as key factors that contribute to its changing demands across many markets. Company profiles and product examples of selected competitors, along with market share estimates of some of the selected leaders for the year 2025, are provided.

Key Features:

Global Humanoid Robot Multi-fingered Dexterous Hand market size and forecasts, in consumption value (\$ Million), sales quantity (Units), and average selling prices (US\$/Unit), 2021-2032

Global Humanoid Robot Multi-fingered Dexterous Hand market size and forecasts by region and country, in consumption value (\$ Million), sales quantity (Units), and average

selling prices (US\$/Unit), 2021-2032

Global Humanoid Robot Multi-fingered Dexterous Hand market size and forecasts, by Type and by Application, in consumption value (\$ Million), sales quantity (Units), and average selling prices (US\$/Unit), 2021-2032

Global Humanoid Robot Multi-fingered Dexterous Hand market shares of main players, shipments in revenue (\$ Million), sales quantity (Units), and ASP (US\$/Unit), 2021-2026

The Primary Objectives in This Report Are:

- To determine the size of the total market opportunity of global and key countries
- To assess the growth potential for Humanoid Robot Multi-fingered Dexterous Hand
- To forecast future growth in each product and end-use market
- To assess competitive factors affecting the marketplace

This report profiles key players in the global Humanoid Robot Multi-fingered Dexterous Hand market based on the following parameters - company overview, sales quantity, revenue, price, gross margin, product portfolio, geographical presence, and key developments. Key companies covered as a part of this study include Shadow Robot, Linkerbot (Chius), Tesla (Optimus), Beijing Inspire Robots Technology, BrainCo, SCHUNK, OYMotion Technologies, Clone Robotics, Agile Robots, Unitree Robotics, etc.

This report also provides key insights about market drivers, restraints, opportunities, new product launches or approvals.

Market Segmentation

Humanoid Robot Multi-fingered Dexterous Hand market is split by Type and by Application. For the period 2021-2032, the growth among segments provides accurate calculations and forecasts for consumption value by Type, and by Application in terms of volume and value. This analysis can help you expand your business by targeting qualified niche markets.

Market segment by Type

Built-in Type

External Type

Hybrid Type

Market segment by Application

Industrial

Logistics

Medical

Research

Household

Others

Major players covered

Shadow Robot

Linkerbot (Chius)

Tesla (Optimus)

Beijing Inspire Robots Technology

BrainCo

SCHUNK

OYMotion Technologies

Clone Robotics

Agile Robots

Unitree Robotics

Qbrobotics

Tokyo Robotics

PaXini Tech

Shanghai AgiBot Innovation Technology

Wonik Robotics

RobotEra

DexRobot

Robopreneur

Tesollo

Suzhou Jodell Robotics

Ti5 Robot

Daimon Robotics

ChangingTek

HITBOT (Huiling-tech Robotic)

Shenzhen Zhaowei Machinery & Electronics

Shenzhen GLI Technology

Neurocean Technologies

MagicLab

Shenzhen RUI Intelligent Control

China Leadshine Technology

Market segment by region, regional analysis covers

North America (United States, Canada, and Mexico)

Europe (Germany, France, United Kingdom, Russia, Italy, and Rest of Europe)

Asia-Pacific (China, Japan, Korea, India, Southeast Asia, and Australia)

South America (Brazil, Argentina, Colombia, and Rest of South America)

Middle East & Africa (Saudi Arabia, UAE, Egypt, South Africa, and Rest of Middle East & Africa)

The content of the study subjects, includes a total of 15 chapters:

Chapter 1, to describe Humanoid Robot Multi-fingered Dexterous Hand product scope, market overview, market estimation caveats and base year.

Chapter 2, to profile the top manufacturers of Humanoid Robot Multi-fingered Dexterous Hand, with price, sales quantity, revenue, and global market share of Humanoid Robot Multi-fingered Dexterous Hand from 2021 to 2026.

Chapter 3, the Humanoid Robot Multi-fingered Dexterous Hand competitive situation, sales quantity, revenue, and global market share of top manufacturers are analyzed emphatically by landscape contrast.

Chapter 4, the Humanoid Robot Multi-fingered Dexterous Hand breakdown data are shown at the regional level, to show the sales quantity, consumption value, and growth by regions, from 2021 to 2032.

Chapter 5 and 6, to segment the sales by Type and by Application, with sales market share and growth rate by Type, by Application, from 2021 to 2032.

Chapter 7, 8, 9, 10 and 11, to break the sales data at the country level, with sales quantity, consumption value, and market share for key countries in the world, from 2021 to 2026. and Humanoid Robot Multi-fingered Dexterous Hand market forecast, by regions, by Type, and by Application, with sales and revenue, from 2027 to 2032.

Chapter 12, market dynamics, drivers, restraints, trends, and Porters Five Forces analysis.

Chapter 13, the key raw materials and key suppliers, and industry chain of Humanoid Robot Multi-fingered Dexterous Hand.

Chapter 14 and 15, to describe Humanoid Robot Multi-fingered Dexterous Hand sales channel, distributors, customers, research findings and conclusion.

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