

Global Humanoid Robot Linear Joints Supply, Demand and Key Producers, 2026-2032

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Abstracts

The global Humanoid Robot Linear Joints market size is expected to reach \$ 675 million by 2032, rising at a market growth of 17.6% CAGR during the forecast period (2026-2032).

A humanoid robot linear joint is a precision actuation unit that converts rotational motion from a motor into linear push-pull movement via a ball screw, planetary roller screw, or similar transmission mechanism, providing driving force for the limbs of a humanoid robot. Its core lies in efficiently transforming rotational power within a compact space into controlled linear displacement and force output, enabling the robot to perform actions involving high thrust or precise positioning, such as standing, walking, and load bearing. The value of this joint is embodied in its ability to achieve linear motion with high stiffness and low backlash, while integrated position and force sensors enable closed-loop control, ensuring transient response capability and repeatable positioning accuracy for the humanoid robot during dynamic balance. Structurally, it typically incorporates elastic elements or torque-sensing structures to perceive external impact and interaction forces, providing a foundation for compliant control and safe human-robot physical interaction for the humanoid robot. In 2025, global Humanoid Robot Linear Joints production reached approximately 350.8 k units with an average global market price of around US\$600 per unit.

The future industry development trends of humanoid robot linear joints present several key directions. First, multiple listed companies that have disclosed their humanoid robot business plans clearly state in their annual reports that linear joints are evolving from simple electric pushrod solutions toward high-stiffness integrated modules incorporating ball screws or planetary roller screws. These companies believe that such integrated design can significantly reduce manufacturing errors during assembly and decrease the

number of parts, thereby improving product yield and profit margins. Second, the trend of vertical integration across the industry chain is becoming increasingly evident. Some component enterprises originally focused on screw and reducer production have announced through corporate official news their expansion into the linear joint assembly field, aiming to capture higher product added value by mastering core transmission components. At the same time, complete machine manufacturers have begun developing their own linear joints to reduce dependence on external suppliers. This two-way penetration is reshaping the industry's profit distribution landscape. Furthermore, government policies related to the robotics industry have repeatedly emphasized the independent controllability of high-precision transmission components and servo drive systems, prompting companies to increase investment in precision manufacturing and material processes for linear joints. Although this will increase research and development costs in the short term, corporate annual reports generally view it as a necessary investment for establishing long-term supply chain advantages. Finally, corporate official information shows that an increasing number of companies are focusing on differentiated competition for linear joints in scenarios requiring high dynamic response and low energy consumption, improving efficiency and service life through optimized thread pair design and preload processes, rather than simply pursuing scale expansion. Overall, this field is transitioning from general-purpose linear modules toward specialized solutions customized for the gait and load characteristics of humanoid robots, and the annual reports of related companies generally regard linear joint technology as an important sector with high growth potential within future revenue structures.

This report studies the global Humanoid Robot Linear Joints production, demand, key manufacturers, and key regions.

This report is a detailed and comprehensive analysis of the world market for Humanoid Robot Linear Joints and provides market size (US\$ million) and Year-over-Year (YoY) Growth, considering 2025 as the base year. This report explores demand trends and competition, as well as details the characteristics of Humanoid Robot Linear Joints that contribute to its increasing demand across many markets.

Highlights and key features of the study

Global Humanoid Robot Linear Joints total production and demand, 2021-2032, (K Units)

Global Humanoid Robot Linear Joints total production value, 2021-2032, (USD Million)

Global Humanoid Robot Linear Joints production by region & country, production, value, CAGR, 2021-2032, (USD Million) & (K Units), (based on production site)

Global Humanoid Robot Linear Joints consumption by region & country, CAGR, 2021-2032 & (K Units)

U.S. VS China: Humanoid Robot Linear Joints domestic production, consumption, key domestic manufacturers and share

Global Humanoid Robot Linear Joints production by manufacturer, production, price, value and market share 2021-2026, (USD Million) & (K Units)

Global Humanoid Robot Linear Joints production by Type, production, value, CAGR, 2021-2032, (USD Million) & (K Units)

Global Humanoid Robot Linear Joints production by Application, production, value, CAGR, 2021-2032, (USD Million) & (K Units)

This report profiles key players in the global Humanoid Robot Linear Joints market based on the following parameters - company overview, production, value, price, gross margin, product portfolio, geographical presence, and key developments. Key companies covered as a part of this study include HIGEN RNM, Harmonic Drive, Infranor, Kollmorgen, Ti5Robot Technology, GUANGZHOU HAOZHI INDUSTRIAL, Techrobots (Shenzhen), Suzhou SIP Gears Intelligent, HC Motion Control, Shenzhen Komo Robot, etc.

This report also provides key insights about market drivers, restraints, opportunities, new product launches or approvals.

Stakeholders would have ease in decision-making through various strategy matrices used in analyzing the World Humanoid Robot Linear Joints market

Detailed Segmentation:

Each section contains quantitative market data including market by value (US\$ Millions), volume (production, consumption) & (K Units) and average price (US\$/Unit) by manufacturer, by Type, and by Application. Data is given for the years 2021-2032 by year with 2025 as the base year, 2026 as the estimate year, and 2027-2032 as the forecast year.

Global Humanoid Robot Linear Joints Market, By Region:

United States

China

Europe

Japan

South Korea

ASEAN

India

Rest of World

Global Humanoid Robot Linear Joints Market, Segmentation by Type:

Pneumatic

Hydraulic

Electric

Global Humanoid Robot Linear Joints Market, Segmentation by Transmission Mechanism:

Linear

Rotary

Global Humanoid Robot Linear Joints Market, Segmentation by Torque:

?10 Nm

10?50 Nm

50?150 Nm

150?300 Nm

300?1000 Nm

Above 1000 Nm

Global Humanoid Robot Linear Joints Market, Segmentation by Application:

Home

Medical

Manufacturing

Service

Companies Profiled:

HIGEN RNM

Harmonic Drive

Infranor

Kollmorgen

Ti5Robot Technology

GUANGZHOU HAOZHI INDUSTRIAL

Techrobots (Shenzhen)

Suzhou SIP Gears Intelligent

HC Motion Control

Shenzhen Komo Robot

Suzhou Dongmao Industrial Equipment

Hangzhou DEEP Robotics

Shenzhen Tongchuan Technology

Guangdong Huayan Robotics

Zhejiang He Chuan Technology

Nanchang CubeMars

China Leadshine Technology

Magiclab Robotics Technology(Wuxi)

Jiangsu Eyou Robot Technology

RobStride

Leader Harmonious Drive Systems

Motorevo

Wuxi Juxie Intelligent Drive Technology

Key Questions Answered:

1. How big is the global Humanoid Robot Linear Joints market?
2. What is the demand of the global Humanoid Robot Linear Joints market?
3. What is the year over year growth of the global Humanoid Robot Linear Joints market?
4. What is the production and production value of the global Humanoid Robot Linear Joints market?
5. Who are the key producers in the global Humanoid Robot Linear Joints market?
6. What are the growth factors driving the market demand?

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