

Global High-DOF Dexterous Hand for Robot Market 2026 by Manufacturers, Regions, Type and Application, Forecast to 2032

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Abstracts

According to our (Global Info Research) latest study, the global High-DOF Dexterous Hand for Robot market size was valued at US\$ 449 million in 2025 and is forecast to a readjusted size of US\$ 1400 million by 2032 with a CAGR of 17.8% during review period.

In 2025, global High-DOF Dexterous Hand for Robot production reached approximately 47,400 units with an average global market price of around US\$ 9,200 per unit, and a gross profit margin of approximately 20%-40%. A High-DOF Dexterous Hand for Robot is an anthropomorphic robotic end-effector designed to replicate the complex motion, grasping flexibility, and manipulation capability of the human hand. It normally adopts a four-finger or five-finger structure, provides at least 12 mechanical degrees of freedom, and typically includes eight or more actively driven joints. Advanced fully actuated models may offer 16-22 independent control axes, allowing multiple finger joints to move separately and perform coordinated actions. Compared with conventional industrial grippers or low-DOF underactuated hands, a high-DOF dexterous hand can execute precision grasping, adaptive holding, object rotation, in-hand manipulation, tool operation, button pressing, assembly, and other complex multi-finger tasks. The product generally integrates miniature motors or linear actuators, tendon, linkage, gear, direct-drive, or hybrid transmission mechanisms, together with encoders, motor drivers, embedded controllers, and communication interfaces. Higher-end products may also incorporate tactile arrays, force/torque sensors, fingertip pressure sensing, and closed-loop force-position control. These hands are mainly used in humanoid robots, industrial robots, service robots, teleoperation systems, embodied-intelligence platforms, research equipment, and robots operating in hazardous or unstructured environments.

The industrial chain of High-DOF Dexterous Hands for Robots includes upstream coreless motors, frameless motors, miniature reducers, planetary gearboxes, lead screws, tendons, steel cables, bearings, encoders, force sensors, tactile arrays, flexible circuits, control chips, motor drivers, engineering plastics, aluminum alloys, and elastomeric skin materials. Midstream activities include anthropomorphic structural design, finger-joint development, actuator integration, transmission-system assembly, sensor embedding, force-position hybrid control, tactile calibration, kinematic modeling, manipulation-algorithm development, communication-interface integration, durability testing, impact testing, thermal testing, and complete-hand assembly. Downstream applications include humanoid robots, robotic arms, industrial manipulation, service robots, hazardous-environment robots, teleoperation platforms, laboratory automation, embodied-AI research, and robot-learning systems.

This report is a detailed and comprehensive analysis for global High-DOF Dexterous Hand for Robot market. Both quantitative and qualitative analyses are presented by manufacturers, by region & country, by Type and by Application. As the market is constantly changing, this report explores the competition, supply and demand trends, as well as key factors that contribute to its changing demands across many markets. Company profiles and product examples of selected competitors, along with market share estimates of some of the selected leaders for the year 2025, are provided.

Key Features:

Global High-DOF Dexterous Hand for Robot market size and forecasts, in consumption value (\$ Million), sales quantity (Units), and average selling prices (US\$/Unit), 2021-2032

Global High-DOF Dexterous Hand for Robot market size and forecasts by region and country, in consumption value (\$ Million), sales quantity (Units), and average selling prices (US\$/Unit), 2021-2032

Global High-DOF Dexterous Hand for Robot market size and forecasts, by Type and by Application, in consumption value (\$ Million), sales quantity (Units), and average selling prices (US\$/Unit), 2021-2032

Global High-DOF Dexterous Hand for Robot market shares of main players, shipments in revenue (\$ Million), sales quantity (Units), and ASP (US\$/Unit), 2021-2026

The Primary Objectives in This Report Are:

Global High-DOF Dexterous Hand for Robot Market 2026 by Manufacturers, Regions, Type and Application, Forecast...

To determine the size of the total market opportunity of global and key countries

To assess the growth potential for High-DOF Dexterous Hand for Robot

To forecast future growth in each product and end-use market

To assess competitive factors affecting the marketplace

This report profiles key players in the global High-DOF Dexterous Hand for Robot market based on the following parameters - company overview, sales quantity, revenue, price, gross margin, product portfolio, geographical presence, and key developments. Key companies covered as a part of this study include LinkerBot, AGIBOT, RobotEra, DexRobot, PaXini, WUJI TECH, Shadow Robot, Agile Robots, Seed Robotics, Sharpa Robotics, etc.

This report also provides key insights about market drivers, restraints, opportunities, new product launches or approvals.

Market Segmentation

High-DOF Dexterous Hand for Robot market is split by Type and by Application. For the period 2021-2032, the growth among segments provides accurate calculations and forecasts for consumption value by Type, and by Application in terms of volume and value. This analysis can help you expand your business by targeting qualified niche markets.

Market segment by Type

Four-Fingered Dexterous Hand

Five-Fingered Dexterous Hand

Market segment by DOF

12?15 DoF

16?20 DoF

Over 20 DoF

Market segment by Application

Collaborative Robots

Humanoid Robots

Medical and Surgical Robots

Others

Major players covered

LinkerBot

AGIBOT

RobotEra

DexRobot

PaXini

WUJI TECH

Shadow Robot

Agile Robots

Seed Robotics

Sharpa Robotics

Tokyo Robotics

Inspire Robots Technology

Zhejiang BrainCo

Jodell Robotics

ZWHAND

Leadshine

Unitree Robotics

ENCOS

PsiBot

Stella-Robot

AIDIN Robotics

Market segment by region, regional analysis covers

North America (United States, Canada, and Mexico)

Europe (Germany, France, United Kingdom, Russia, Italy, and Rest of Europe)

Asia-Pacific (China, Japan, Korea, India, Southeast Asia, and Australia)

South America (Brazil, Argentina, Colombia, and Rest of South America)

Middle East & Africa (Saudi Arabia, UAE, Egypt, South Africa, and Rest of Middle East & Africa)

The content of the study subjects, includes a total of 15 chapters:

Chapter 1, to describe High-DOF Dexterous Hand for Robot product scope, market overview, market estimation caveats and base year.

Chapter 2, to profile the top manufacturers of High-DOF Dexterous Hand for Robot, with price, sales quantity, revenue, and global market share of High-DOF Dexterous Hand for Robot from 2021 to 2026.

Chapter 3, the High-DOF Dexterous Hand for Robot competitive situation, sales quantity, revenue, and global market share of top manufacturers are analyzed emphatically by landscape contrast.

Chapter 4, the High-DOF Dexterous Hand for Robot breakdown data are shown at the regional level, to show the sales quantity, consumption value, and growth by regions, from 2021 to 2032.

Chapter 5 and 6, to segment the sales by Type and by Application, with sales market share and growth rate by Type, by Application, from 2021 to 2032.

Chapter 7, 8, 9, 10 and 11, to break the sales data at the country level, with sales quantity, consumption value, and market share for key countries in the world, from 2021 to 2026. and High-DOF Dexterous Hand for Robot market forecast, by regions, by Type, and by Application, with sales and revenue, from 2027 to 2032.

Chapter 12, market dynamics, drivers, restraints, trends, and Porters Five Forces analysis.

Chapter 13, the key raw materials and key suppliers, and industry chain of High-DOF Dexterous Hand for Robot.

Chapter 14 and 15, to describe High-DOF Dexterous Hand for Robot sales channel, distributors, customers, research findings and conclusion.

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