

Global Electromagnetic Brakes for Humanoid Robot Supply, Demand and Key Producers, 2026-2032

<https://marketpublishers.com/r/GF0C873CF7FCEN.html>

Date: August 2026

Pages: 148

Price: US\$ 4,480.00 (Single User License)

ID: GF0C873CF7FCEN

Abstracts

The global Electromagnetic Brakes for Humanoid Robot market size is expected to reach \$ 62.83 million by 2032, rising at a market growth of 20.1% CAGR during the forecast period (2026-2032).

In 2025, global Electromagnetic Brakes for Humanoid Robot production reached approximately 35,000 units with average price of 100 USD/Unit.

Electromagnetic brakes for humanoid robots are safety and motion-control components installed in joint actuators, servo motors or reducer assemblies. They stop joint motion, hold a commanded position and prevent uncontrolled movement or joint collapse during power loss, emergency shutdowns or control-system failures. A typical brake consists of an electromagnetic coil, armature, friction disc, springs, magnetic components and a mounting structure, and is integrated with the motor, reducer, encoder and drive electronics to form a compact joint actuator.

The principal technologies are spring-applied electromagnetic brakes and permanent-magnet brakes. Spring-applied brakes engage mechanically when power is removed and release when the coil is energized, providing fail-safe protection for load-bearing joints such as the hip, knee, ankle, waist and shoulder. Permanent-magnet brakes can provide compact construction, rapid response, backlash-free torque transmission and accurate holding performance. Product development is increasingly focused on slim profiles, hollow-shaft structures, high torque density, low power consumption and quiet operation.

Upstream suppliers provide soft magnetic steel, electrical steel, permanent magnets, enamelled copper wire, friction materials, spring steel, bearings, fasteners, precision-

stamped components and machined parts. Sensors, brake controllers and power-management electronics may also be included. Magnetic properties, friction stability, thermal resistance and dimensional accuracy directly influence holding torque, response time, service life and operating noise.

The midstream segment includes electromagnetic brake manufacturers, servo-motor suppliers, precision-reducer manufacturers and integrated joint-module companies. Brake suppliers undertake magnetic-circuit design, coil winding, friction-pair development, spring matching, thermal management, lifecycle testing and safety validation. Joint-module manufacturers integrate the brake with frameless torque motors, harmonic or planetary reducers, encoders, drives and structural housings. Slim hollow-shaft brakes are particularly suitable for humanoid joints because power, communication and sensor cables can be routed through the centre of the actuator.

Downstream customers include humanoid robot manufacturers and end users in automotive production, warehousing, logistics, electronics assembly, commercial services, rehabilitation and household assistance. Requirements differ by joint. Leg and waist joints emphasize high holding torque, shock resistance and fail-safe operation, while arm joints place greater importance on low weight, rapid release and low drag torque. Small hand and finger joints may use miniature brakes, mechanical locking mechanisms or brake-free actuator designs.

The market remains at an early commercialization stage but has attractive long-term growth potential. Commercial humanoid platforms increasingly contain large numbers of powered joints, with some systems disclosing more than twenty to forty joint motors and high peak torque at load-bearing leg joints. As humanoid robots move from demonstrations into factories, warehouses and human-shared environments, emergency stopping, power-off holding and protection against uncontrolled arm or body movement will become increasingly important. This is expected to support demand for high-reliability brakes in critical hip, knee, ankle, waist and shoulder actuators.

Future development will focus on higher torque density, thinner hollow-shaft construction, lower weight, minimal residual drag, millisecond-level response, low noise and reduced holding power. Energy-saving controllers can provide high initial current for brake release and then reduce voltage or use pulse-width modulation to limit steady-state power consumption and heat generation. Brakes are also expected to become more closely integrated with encoders, drives and functional-safety systems, enabling wear monitoring, temperature sensing, torque diagnostics and predictive maintenance.

Report Scope

This report studies the global Electromagnetic Brakes for Humanoid Robot production, demand, key manufacturers, and key regions.

This report is a detailed and comprehensive analysis of the world market for Electromagnetic Brakes for Humanoid Robot and provides market size (US\$ million) and Year-over-Year (YoY) Growth, considering 2025 as the base year. This report explores demand trends and competition, as well as details the characteristics of Electromagnetic Brakes for Humanoid Robot that contribute to its increasing demand across many markets.

Highlights and key features of the study

Global Electromagnetic Brakes for Humanoid Robot total production and demand, 2021-2032, (K Units)

Global Electromagnetic Brakes for Humanoid Robot total production value, 2021-2032, (USD Million)

Global Electromagnetic Brakes for Humanoid Robot production by region & country, production, value, CAGR, 2021-2032, (USD Million) & (K Units), (based on production site)

Global Electromagnetic Brakes for Humanoid Robot consumption by region & country, CAGR, 2021-2032 & (K Units)

U.S. VS China: Electromagnetic Brakes for Humanoid Robot domestic production, consumption, key domestic manufacturers and share

Global Electromagnetic Brakes for Humanoid Robot production by manufacturer, production, price, value and market share 2021-2026, (USD Million) & (K Units)

Global Electromagnetic Brakes for Humanoid Robot production by Type, production, value, CAGR, 2021-2032, (USD Million) & (K Units)

Global Electromagnetic Brakes for Humanoid Robot production by Application, production, value, CAGR, 2021-2032, (USD Million) & (K Units)

This report profiles key players in the global Electromagnetic Brakes for Humanoid Robot market based on the following parameters - company overview, production, value, price, gross margin, product portfolio, geographical presence, and key developments. Key companies covered as a part of this study include Kendrion N.V., Chr. Mayr GmbH + Co. KG, KEB Automation KG, Warner Electric, Ogura Clutch Co., Ltd., Miki Pulley Co., Ltd., Nexen Group, Inc., PRECIMA Magnettechnik GmbH, SINFONIA TECHNOLOGY CO., LTD., MinebeaMitsumi Inc., etc.

This report also provides key insights about market drivers, restraints, opportunities, new product launches or approvals.

Stakeholders would have ease in decision-making through various strategy matrices used in analyzing the World Electromagnetic Brakes for Humanoid Robot market

Detailed Segmentation:

Each section contains quantitative market data including market by value (US\$ Millions), volume (production, consumption) & (K Units) and average price (US\$/Unit) by manufacturer, by Type, and by Application. Data is given for the years 2021-2032 by year with 2025 as the base year, 2026 as the estimate year, and 2027-2032 as the forecast year.

Global Electromagnetic Brakes for Humanoid Robot Market, By Region:

United States

China

Europe

Japan

South Korea

ASEAN

India

Rest of World

Global Electromagnetic Brakes for Humanoid Robot Market, Segmentation by Type:

Spring-Applied Power-Off Electromagnetic Brake

Permanent-Magnet Power-Off Brake

Power-On Electromagnetic Friction Brake

Others

Global Electromagnetic Brakes for Humanoid Robot Market, Segmentation by Structure:

Ultra-Thin Hollow Compact Brake

Micro Flange Compact Brake

Flat Integrated Brake

Global Electromagnetic Brakes for Humanoid Robot Market, Segmentation by Torque:

Below 1 Nm

1-5 Nm

5-20 Nm

Above 20 Nm

Global Electromagnetic Brakes for Humanoid Robot Market, Segmentation by Application:

Humanoid Robot Arm Joints

Humanoid Robot Leg Joints

Waist and Torso Joints

Others

Companies Profiled:

Kendrion N.V.

Chr. Mayr GmbH + Co. KG

KEB Automation KG

Warner Electric

Ogura Clutch Co., Ltd.

Miki Pulley Co., Ltd.

Nexen Group, Inc.

PRECIMA Magnettechnik GmbH

SINFONIA TECHNOLOGY CO., LTD.

MinebeaMitsumi Inc.

Ortlinghaus-Werke GmbH

Electroid Company

Mach III Clutch, Inc.

Chengdu Reach Machinery Co., Ltd.

Chengdu CDC Technology Co., Ltd.

Zhuji Miki Technology Co., Ltd.

Suzhou Jipai Electromagnetic Technology Co., Ltd.

Jiangxi Huawu Brake Co., Ltd.

Key Questions Answered:

1. How big is the global Electromagnetic Brakes for Humanoid Robot market?

2. What is the demand of the global Electromagnetic Brakes for Humanoid Robot market?
3. What is the year over year growth of the global Electromagnetic Brakes for Humanoid Robot market?
4. What is the production and production value of the global Electromagnetic Brakes for Humanoid Robot market?
5. Who are the key producers in the global Electromagnetic Brakes for Humanoid Robot market?
6. What are the growth factors driving the market demand?

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