

Global Drive-by-wire Chassis for Autonomous Mining Vehicles Market 2026 by Manufacturers, Regions, Type and Application, Forecast to 2032

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Abstracts

According to our (Global Info Research) latest study, the global Drive-by-wire Chassis for Autonomous Mining Vehicles market size was valued at US\$ 473 million in 2025 and is forecast to a readjusted size of US\$ 986 million by 2032 with a CAGR of 10.5% during review period.

Drive by wire chassis systems for autonomous mining trucks are electronic chassis control and actuation systems designed for unmanned haulage vehicles used in open pit mines, underground mines, quarrying sites and large scale mineral transportation operations. The core attribute of this product is the conversion of steering, braking, propulsion, gear shifting, parking, energy management and safety response from conventional mechanical or hydraulic operation into electronically controlled actuation. The product mainly covers factory installed native drive by wire chassis platforms, retrofit chassis kits for existing mining trucks, electric mining truck chassis systems, range extended mining truck chassis systems, automated underground vehicle chassis systems and autonomous ready chassis platforms for ultra class haul trucks. The main technical processes include chassis domain controller integration, electronic steering actuation, electronic braking control, drive control calibration, redundant power supply design, fault diagnosis, functional safety architecture, vehicle control software integration and mine site durability validation. Key specifications typically include vehicle payload class, steering response delay, braking redundancy level, steering angle control accuracy, CAN or Ethernet communication interface, dust and water protection rating, vibration resistance, safety stop logic and operating temperature range. The key function of the system is to enable autonomous mining trucks to perform accurate path tracking, remote takeover, automatic loading and dumping coordination, safe stop, low speed maneuvering and continuous driverless haulage under high dust, heavy load,

slope, vibration and mixed traffic conditions. It is mainly used in autonomous haul trucks, electric wide body mining trucks, underground mining trucks, unmanned quarry transport vehicles and autonomous ready ultra class haul trucks. In 2025, global shipments of drive by wire chassis systems for autonomous mining trucks were about 4,600 sets, the industry average price was about USD 100,000 per set, and the industry average gross margin was about 32%.

Drive by wire chassis systems for autonomous mining trucks represent the physical execution layer behind the transition from manned mine haulage to autonomous haulage. The upstream supply chain includes electronic steering, electronic braking, drive control units, chassis domain controllers, redundant power modules, safety software, actuators, connectors and ruggedized electrical components. The midstream consists of mining truck OEMs, underground mining vehicle manufacturers, chassis platform suppliers and retrofit solution providers. Downstream demand mainly comes from open pit coal mines, iron ore mines, copper mines, gold mines, aggregate quarries and underground hard rock mines. The product should be understood as a vehicle level control and actuation platform rather than a pure autonomous driving algorithm, dispatching platform or complete mining truck.

The competitive structure is split between global integrated mining equipment manufacturers and fast moving Chinese vehicle electrification and autonomy players. International suppliers are stronger in ultra class haul trucks, underground mining vehicles, closed architecture autonomous haulage systems and long cycle mining customer relationships. Chinese suppliers are gaining momentum in electric wide body mining trucks, retrofit projects and large scale deployment in open pit mines. This creates a market pattern in which overseas projects usually have higher unit value and longer validation cycles, while China contributes faster vehicle volume growth and more frequent project replication. Policy support for mine safety, unmanned operation, green mining and new energy mining vehicles is accelerating the shift from pilot deployment to repeated commercial installation.

Future demand will be driven by normalized autonomous haulage, factory installed drive by wire platforms for electric mining trucks, retrofit demand from existing diesel fleets, underground mine automation and capital expenditure upgrades by large mining groups. The industry outlook is positive, but the statistical boundary must remain conservative because full autonomous driving systems, fleet management software, perception hardware and complete vehicle sales can easily inflate the apparent market size. Over the long term, the product will evolve from project based customization toward modular chassis platforms, standardized functional safety architecture and

integrated vehicle control systems. Companies with vehicle integration capability, redundant safety design, mine site validation experience and after sales service networks are more likely to secure durable market positions.

This report is a detailed and comprehensive analysis for global Drive-by-wire Chassis for Autonomous Mining Vehicles market. Both quantitative and qualitative analyses are presented by manufacturers, by region & country, by Vehicle Type and by Application. As the market is constantly changing, this report explores the competition, supply and demand trends, as well as key factors that contribute to its changing demands across many markets. Company profiles and product examples of selected competitors, along with market share estimates of some of the selected leaders for the year 2025, are provided.

Key Features:

Global Drive-by-wire Chassis for Autonomous Mining Vehicles market size and forecasts, in consumption value (\$ Million), sales quantity (Sets), and average selling prices (US\$/Set), 2021-2032

Global Drive-by-wire Chassis for Autonomous Mining Vehicles market size and forecasts by region and country, in consumption value (\$ Million), sales quantity (Sets), and average selling prices (US\$/Set), 2021-2032

Global Drive-by-wire Chassis for Autonomous Mining Vehicles market size and forecasts, by Vehicle Type and by Application, in consumption value (\$ Million), sales quantity (Sets), and average selling prices (US\$/Set), 2021-2032

Global Drive-by-wire Chassis for Autonomous Mining Vehicles market shares of main players, shipments in revenue (\$ Million), sales quantity (Sets), and ASP (US\$/Set), 2021-2026

The Primary Objectives in This Report Are:

To determine the size of the total market opportunity of global and key countries

To assess the growth potential for Drive-by-wire Chassis for Autonomous Mining Vehicles

To forecast future growth in each product and end-use market

To assess competitive factors affecting the marketplace

This report profiles key players in the global Drive-by-wire Chassis for Autonomous Mining Vehicles market based on the following parameters - company overview, sales quantity, revenue, price, gross margin, product portfolio, geographical presence, and key developments. Key companies covered as a part of this study include Caterpillar Inc., Komatsu Ltd., Hitachi Construction Machinery Co., Ltd., Liebherr Group, Volvo Construction Equipment, Sandvik AB, Epiroc AB, XCMG Machinery, SANY Group, Shaanxi Tonly Heavy Industries Co., Ltd., etc.

This report also provides key insights about market drivers, restraints, opportunities, new product launches or approvals.

Market Segmentation

Drive-by-wire Chassis for Autonomous Mining Vehicles market is split by Vehicle Type and by Application. For the period 2021-2032, the growth among segments provides accurate calculations and forecasts for consumption value by Vehicle Type, and by Application in terms of volume and value. This analysis can help you expand your business by targeting qualified niche markets.

Market segment by Vehicle Type

Ultra-class Mining Trucks

Wide-body Mining Trucks

Underground Mining Trucks

Electric Mining Trucks

Others

Market segment by Propulsion Type

Diesel Drive-by-wire Chassis

Battery Electric Drive-by-wire Chassis

Range-extended Electric Drive-by-wire Chassis

Hybrid Drive-by-wire Chassis

Others

Market segment by Application

Open-pit Coal Mines

Metal Mines

Aggregate and Quarry Mines

Underground Mines

Others

Major players covered

Caterpillar Inc.

Komatsu Ltd.

Hitachi Construction Machinery Co., Ltd.

Liebherr Group

Volvo Construction Equipment

Sandvik AB

Epiroc AB

XCMG Machinery

SANY Group

Shaanxi Tonly Heavy Industries Co., Ltd.

EACON Mining Technology Co., Ltd.

Yutong Mining Equipment

Inner Mongolia North Hauler Joint Stock Co., Ltd.

Market segment by region, regional analysis covers

North America (United States, Canada, and Mexico)

Europe (Germany, France, United Kingdom, Russia, Italy, and Rest of Europe)

Asia-Pacific (China, Japan, Korea, India, Southeast Asia, and Australia)

South America (Brazil, Argentina, Colombia, and Rest of South America)

Middle East & Africa (Saudi Arabia, UAE, Egypt, South Africa, and Rest of Middle East & Africa)

The content of the study subjects, includes a total of 15 chapters:

Chapter 1, to describe Drive-by-wire Chassis for Autonomous Mining Vehicles product scope, market overview, market estimation caveats and base year.

Chapter 2, to profile the top manufacturers of Drive-by-wire Chassis for Autonomous Mining Vehicles, with price, sales quantity, revenue, and global market share of Drive-by-wire Chassis for Autonomous Mining Vehicles from 2021 to 2026.

Chapter 3, the Drive-by-wire Chassis for Autonomous Mining Vehicles competitive situation, sales quantity, revenue, and global market share of top

manufacturers are analyzed emphatically by landscape contrast.

Chapter 4, the Drive-by-wire Chassis for Autonomous Mining Vehicles breakdown data are shown at the regional level, to show the sales quantity, consumption value, and growth by regions, from 2021 to 2032.

Chapter 5 and 6, to segment the sales by Vehicle Type and by Application, with sales market share and growth rate by Vehicle Type, by Application, from 2021 to 2032.

Chapter 7, 8, 9, 10 and 11, to break the sales data at the country level, with sales quantity, consumption value, and market share for key countries in the world, from 2021 to 2026. and Drive-by-wire Chassis for Autonomous Mining Vehicles market forecast, by regions, by Vehicle Type, and by Application, with sales and revenue, from 2027 to 2032.

Chapter 12, market dynamics, drivers, restraints, trends, and Porters Five Forces analysis.

Chapter 13, the key raw materials and key suppliers, and industry chain of Drive-by-wire Chassis for Autonomous Mining Vehicles.

Chapter 14 and 15, to describe Drive-by-wire Chassis for Autonomous Mining Vehicles sales channel, distributors, customers, research findings and conclusion.

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