

Global Closed-Loop Simulation System for Mobile Robots Supply, Demand and Key Producers, 2026-2032

<https://marketpublishers.com/r/G383255E155CEN.html>

Date: August 2026

Pages: 144

Price: US\$ 4,480.00 (Single User License)

ID: G383255E155CEN

Abstracts

The global Closed-Loop Simulation System for Mobile Robots market size is expected to reach \$ 1102 million by 2032, rising at a market growth of 15.3% CAGR during the forecast period (2026-2032).

A closed-loop simulation system for mobile robots is a virtual validation infrastructure for autonomous mobile robots, automated guided vehicles, unmanned ground vehicles, and mobile manipulators. By integrating 3D environments, robot body models, sensor models, dynamics models, task orchestration models, and control software interfaces, it connects perception, localization, mapping, planning, control, execution, and feedback into a repeatable closed loop. The system addresses high deployment cost, testing risk, insufficient long-tail scenario coverage, long software and hardware debugging cycles, and the difficulty of validating multi-robot collaboration. It typically supports ROS or ROS 2 communication, LiDAR, cameras, IMU, GNSS, radar, and other sensor simulation, as well as model-in-the-loop, software-in-the-loop, hardware-in-the-loop, human interaction, and digital twin synchronization. It can be used in warehouses, factories, campuses, roads, and unstructured ground environments for path planning, obstacle avoidance, scheduling, collision safety, policy learning, and remote operations validation. Its customers include robot OEMs, automation integrators, logistics and manufacturing companies, autonomous driving R&D teams, research institutions, universities, and cloud platform providers. Common delivery models include open-source frameworks, commercial software, cloud-based parallel simulation, private deployment, and project-based customization services.

The industrial value of closed-loop simulation systems for mobile robots is shifting from R&D support tools to engineering validation infrastructure. Real-world deployment of

mobile robots typically faces complex environments, high testing costs, costly on-site interruptions, and safety risks that are difficult to cover comprehensively. Relying only on physical robot testing makes it difficult to validate a large number of long-tail scenarios within a short development cycle. Closed-loop simulation brings 3D environments, robot dynamics, sensor inputs, control software, task orchestration, and feedback mechanisms into one operating chain, enabling R&D teams to repeatedly test localization and mapping, path planning, obstacle avoidance, collision detection, task allocation, and exception recovery in virtual environments. As ROS or ROS 2 interfaces, physics engines, sensor models, and cloud-based parallel computing mature, simulation systems are no longer limited to algorithm development, but are increasingly used for pre-delivery validation, customer-site replay, operations optimization, and safety compliance testing. This shift means that software quality, deployment efficiency, and scalable replication in the mobile robot industry will increasingly depend on closed-loop simulation capabilities. Simulation platforms will also become an important foundation for robot companies moving from single-unit delivery toward fleet-based, scenario-based, and continuously operated business models.

From the downstream application perspective, warehouse logistics and manufacturing lines remain the clearest commercial scenarios for closed-loop simulation of mobile robots. Core requirements focus on throughput efficiency, path conflicts, fleet scale, battery strategies, traffic rules, equipment coordination, and facility layout optimization. Unlike traditional robot simulation, which often emphasizes single-robot trajectories, mobile robot simulation must handle dynamic task flows, complex spatial constraints, and multi-robot collaboration. As a result, discrete-event simulation, 3D spatial simulation, robot control interfaces, and business process models are converging. Digital twin capabilities further amplify the value of these systems by enabling enterprises to synchronize maps, equipment, orders, tasks, and operational data from real factories, warehouses, or campuses into virtual environments, continuously identifying bottlenecks and optimizing scheduling strategies through simulation. As mobile robots penetrate semiconductors, automotive, electronics manufacturing, pharmaceutical logistics, commercial buildings, and campus delivery, customers will increasingly focus on the consistency between simulation results and real operating metrics. Platform vendors will differentiate through high-fidelity environments, real-time data integration, and measurable business indicators.

From a market structure perspective, closed-loop simulation systems for mobile robots sit at the intersection of robot simulation software, mobile robot software, digital twins, and autonomous driving validation tools, so industry boundaries are still forming. Open-source frameworks are accelerating the diffusion of foundational capabilities through the

ROS ecosystem, sensor plugins, and developer communities, while commercial software serves large customers through engineering modeling, visualization, virtual commissioning, HIL/SIL interfaces, enterprise deployment, and technical services. Future growth will be driven by three factors. First, as mobile robot fleets expand, enterprises will need more systematic planning and risk validation before deployment. Second, embodied intelligence and autonomous system development require large-scale, controllable, reproducible, and scalable environments for training and evaluation. Third, cloud-based parallel simulation and digital-twin operations will lower the cost of continuous validation. The industry is expected to move from single-tool competition toward platform ecosystem competition. Vendors that can connect real data, control stacks, sensor models, business processes, and cloud computing resources at the same time are more likely to gain long-term advantages.

This report studies the global Closed-Loop Simulation System for Mobile Robots demand, key companies, and key regions.

This report is a detailed and comprehensive analysis of the world market for Closed-Loop Simulation System for Mobile Robots, and provides market size (US\$ million) and Year-over-Year (YoY) growth, considering 2025 as the base year. This report explores demand trends and competition, as well as details the characteristics of Closed-Loop Simulation System for Mobile Robots that contribute to its increasing demand across many markets.

Highlights and key features of the study

Global Closed-Loop Simulation System for Mobile Robots total market, 2021-2032, (USD Million)

Global Closed-Loop Simulation System for Mobile Robots total market by region & country, CAGR, 2021-2032, (USD Million)

U.S. VS China: Closed-Loop Simulation System for Mobile Robots total market, key domestic companies, and share, (USD Million)

Global Closed-Loop Simulation System for Mobile Robots revenue by player, revenue and market share 2021-2026, (USD Million)

Global Closed-Loop Simulation System for Mobile Robots total market by Control Task, CAGR, 2021-2032, (USD Million)

Global Closed-Loop Simulation System for Mobile Robots total market by Application, CAGR, 2021-2032, (USD Million)

This report profiles major players in the global Closed-Loop Simulation System for Mobile Robots market based on the following parameters - company overview, revenue,

gross margin, product portfolio, geographical presence, and key developments. Key companies covered as a part of this study include NVIDIA Corporation, Cyberbotics Ltd., Coppelias AG, Open Source Robotics Foundation, The MathWorks, Inc., MORAI Inc., Applied Intuition, Inc., Dassault Systèmes SE, Siemens AG, Robotec.ai sp. z o.o., etc.

This report also provides key insights about market drivers, restraints, opportunities, new product launches or approvals.

Stakeholders would have ease in decision-making through various strategy matrices used in analyzing the world Closed-Loop Simulation System for Mobile Robots market

Detailed Segmentation:

Each section contains quantitative market data including market by value (US\$ Millions), by player, by regions, by Control Task, and by Application. Data is given for the years 2021-2032 by year with 2025 as the base year, 2026 as the estimate year, and 2027-2032 as the forecast year.

Global Closed-Loop Simulation System for Mobile Robots Market, By Region:

United States

China

Europe

Japan

South Korea

ASEAN

India

Rest of World

Global Closed-Loop Simulation System for Mobile Robots Market, Segmentation by

Global Closed-Loop Simulation System for Mobile Robots Supply, Demand and Key Producers, 2026-2032

Control Task:

Localization and Mapping Simulation System

Path Planning Simulation System

Motion Control Simulation System

Task Scheduling Simulation System

Collision Safety Simulation System

Policy Learning Simulation System

Other

Global Closed-Loop Simulation System for Mobile Robots Market, Segmentation by Closed-Loop Level:

Model-in-the-Loop

Software-in-the-Loop

Hardware-in-the-Loop

Operator-in-the-Loop

Global Closed-Loop Simulation System for Mobile Robots Market, Segmentation by Modeling Fidelity:

Kinematic Simulation System

Dynamic Simulation System

Physical Sensor Simulation System

Photorealistic Rendering Simulation System

Real-Time Digital Twin Simulation System

Other

Global Closed-Loop Simulation System for Mobile Robots Market, Segmentation by Application:

Warehouse Logistics Validation

Factory Line Commissioning

Campus Delivery Testing

Unmanned Vehicle Road Validation

Research and Education Experimentation

Embodied Intelligence Training

Remote Operations Monitoring

Safety and Compliance Validation

Other

Companies Profiled:

NVIDIA Corporation

Cyberbotics Ltd.

Coppelia Robotics AG

Open Source Robotics Foundation

The MathWorks, Inc.

MORAI Inc.

Applied Intuition, Inc.

Dassault Systèmes SE

Siemens AG

Robotec.ai sp. z o.o.

DUALIS GmbH IT Solution

Visual Components Oy

FlexSim Software Products, Inc.

The AnyLogic Company

SIASUN Robot & Automation Co., Ltd.

AutoCore Technology (Nanjing) Co., Ltd.

TIER IV, Inc.

Autoware Foundation

Key Questions Answered

1. How big is the global Closed-Loop Simulation System for Mobile Robots market?
2. What is the demand of the global Closed-Loop Simulation System for Mobile Robots market?
3. What is the year over year growth of the global Closed-Loop Simulation System for Mobile Robots market?
4. What is the total value of the global Closed-Loop Simulation System for Mobile Robots market?
5. Who are the Major Players in the global Closed-Loop Simulation System for Mobile Robots market?
6. What are the growth factors driving the market demand?

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