

Global Automotive LiDAR Scanner Competitive Landscape Professional Research Report 2025

<https://marketpublishers.com/r/AAB0C7D7677AEN.html>

Date: June 2025

Pages: 165

Price: US\$ 3,500.00 (Single User License)

ID: AAB0C7D7677AEN

Abstracts

Market Overview

According to DIResearch's in-depth investigation and research, the global Automotive LiDAR Scanner market size will reach 1,646.58 Million USD in 2025 and is projected to reach 24,214.72 Million USD by 2032, with a CAGR of 46.82% (2025-2032). Notably, the China Automotive LiDAR Scanner market has changed rapidly in the past few years. By 2025, China's market size is expected to be Million USD, representing approximately % of the global market share.

Research Summary

An Automotive LiDAR scanner is a sensor system that uses light detection and ranging technology to measure distances and generate 3D maps of the surrounding environment, enabling autonomous vehicles to operate safely. It emits rapid pulses of laser light and measures the time taken for the light to reflect off nearby objects and return to the scanner, allowing it to create a detailed real-time map of the vehicle's surroundings. This technology is crucial for autonomous vehicles as it enables them to detect obstacles and avoid collisions, making them safe for drivers and passengers on the road.

The major global manufacturers of Automotive LiDAR Scanner include Valeo, RoboSense, Continental, Cepton, Livox, Innoviz, Luminar, Velodyne, ibeo, Hesai Tech, Innovusion, etc. The global players competition landscape in this report is divided into three tiers. The first tier comprises global leading enterprises that command a substantial market share, hold a dominant industry position, possess strong competitiveness and influence, and generate significant revenue. The second tier

includes companies with a notable market presence and reputation; these firms actively follow industry leaders in product, service, or technological innovation and maintain a moderate revenue scale. The third tier consists of smaller companies with limited market share and lower brand recognition, primarily focused on local markets and generating comparatively lower revenue.

This report studies the market size, price trends and future development prospects of Automotive LiDAR Scanner. Focus on analysing the market share, product portfolio, prices, sales, revenue and gross profit margin of global major manufacturers, as well as the market status and trends of different product types and applications in the global Automotive LiDAR Scanner market. The report data covers historical data from 2020 to 2024, based year in 2025 and forecast data from 2026 to 2032.

The regions and countries in the report include North America, Europe, China, APAC (excl. China), Latin America and Middle East and Africa, covering the Automotive LiDAR Scanner market conditions and future development trends of key regions and countries, combined with industry-related policies and the latest technological developments, analyze the development characteristics of Automotive LiDAR Scanner industries in various regions and countries, help companies understand the development characteristics of each region, help companies formulate business strategies, and achieve the ultimate goal of the company's global development strategy.

The data sources of this report mainly include the National Bureau of Statistics, customs databases, industry associations, corporate financial reports, third-party databases, etc. Among them, macroeconomic data mainly comes from the National Bureau of Statistics, International Economic Research Organization; industry statistical data mainly come from industry associations; company data mainly comes from interviews, public information collection, third-party reliable databases, and price data mainly comes from various markets monitoring database.

Global Key Manufacturers of Automotive LiDAR Scanner Include:

Valeo

RoboSense

Continental

Cepton

Livox

Innoviz

Luminar

Velodyne

ibeo

Hesai Tech

Innovusion

Automotive LiDAR Scanner Product Segment Include:

Mechanical Lidar

Solid State Lidar

Automotive LiDAR Scanner Product Application Include:

Passenger Car

Commercial Vehicle

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